Franchising as a Nexus of Incentive Devices for Brand Name Maintenance

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Abstract

Franchising involves a variety of contractual and ownership arrangements within a single company. In recent years, a great deal of effort has been made to understand this increasingly popular organization (Lafontaine, 1992, 1993, and Lafontaine and Slade, 1997). There are at least two stylized facts that have posed challenges to the existing theories of the firm. One is the co-existence of company-owned and franchised units, and the other is that franchisees make substantial amount of investment highly specific to their franchise companies.

We set out to explain both puzzles based on the importance of the brand name in franchising (Kaufmann and Lafontaine, 1994). The effort to develop and maintain the brand name changes over time and is difficult to verify (Hadford, 1990), which has two implications. One is that agents who run franchise units need to be given appropriate incentives for the brand-name-maintenance effort. The other is that franchising contracts are incomplete. For incentive purposes, it is optimal to divide the agents into two groups. Those in the first group (managers of company owned units) receive a salary and focus on brand maintenance. Those in the second group (franchisees) receive a share of the revenue in their own unit and focus mainly on unit specific sales effort (Bai and Tao, 2000). However, the franchisees should also be subject to a minimum service standard that is crucial for brand name maintenance. The high-powered incentive for the franchisees to increase sales revenue implies that they have a strong tendency to divert effort from meeting the minimum standard. To discourage the franchisees from doing so, they should be subject to severe penalty when found violating the standard. We show that, to serve this purpose, it is optimal to have the franchisees make investment highly specific to their franchise companies.

Specifically, the investment by the franchisee to buy physical assets (buildings, equipment, etc.) can be viewed as a performance bond for the minimum standard. If the franchisor controls the assets when the franchisee leaves the company, then the franchisor has an incentive to opportunistically accuse the franchisee of violating the standard and re the franchisee, getting all the profits arising from the assets. If the franchisee controls the assets, such opportunistic behavior of the franchisor will not occur. Furthermore, if the assets are relationship specific so that their value is very low when detached from the brand name, then the franchisee will have strong incentive not to violate the minimum standard, fearing of being deprived the right to use the brand name in the event of violation.

Overall, the plural forms of contractual and control right arrangements in franchising serve as a nexus of incentive devices for production involving brand-name-maintenance effort in an incomplete contract framework.

Field: Contract Theory, Theory of the Firm
1. Introduction

As arguably one of the most important organizational innovations of the last half century, the franchise has motivated and challenged recent developments in the theory of the firm.\(^1\) A franchise company typically has both company-owned units and franchised units, which differ in at least two important aspects: (1) Managers in the company-owned units have low-powered incentive contracts, that is, they receive fixed wages. Managers in the franchised units, however, have high-powered incentive contracts; they pay a portion of their revenue as a royalty to the company and keep the remainder. (2) Managers in the company-owned units do not own any assets of the units, whereas managers in the franchised units own part or all of the units' physical assets.\(^2\) To explain such intra-firm heterogeneity of organizational form, we study a multi-agent, multi-task model where one of the tasks generates a public good—the brand name in the context of the franchise. We show that it is optimal to offer a mix of high-powered and low-powered incentives to ex ante homogeneous agents. In addition, corresponding ownership arrangements are chosen to make the revenue-sharing agreements self-enforcing.

This study is inspired by the history of the development of the business format franchising in the United States. The efficiency and success of the McDonald brothers' California drive-in made it possible for Ray Kroc (the founder of the McDonald's company) to sell the brand name and the successful business format to would-be entrepreneurs (Love (1986)). Tom Monaghan, the founder of Domino's Pizza, started selling the business of making pizza only after years of perfecting the production process (Dicke (1992)). Indeed, in one of the earliest litigations about business format franchising (Susser v. Carrel), the courts realized that "the cornerstone of the franchise system must be the trademark or trade name of a product."\(^3\) Clearly, what is crucial to a business format franchise is the effort to develop and maintain brand name products and services shared by all units of the company (henceforth, goodwill), as well as the effort in production and distribution (henceforth, sales).

We consider a company that consists of the headquarters (HQ) and many units. The

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\(^1\)The multi-task theory of the firm (Holmstrom and Milgrom (1991, 1994)) rationalizes incentive contracts of various power, while the incomplete-contracts theory of the firm (Grossman and Hart (1986), Hart and Moore (1990), Hart (1995)) focuses on ownership structures.

\(^2\)In 1986, the percentage of franchised units was 76 percent in McDonald's, and 82 percent in Burger King (Lafontaine (1992)). Like most fast food chains, these are examples of the business format franchise, which includes business format as well as (usually generic) goods and services. The other type is the product franchise (such as car dealers) which involves complicated products and services (Dicke (1992)). This paper focuses on the business format franchise, as the aforementioned heterogeneity in organizational form is sharper in the business format franchise than in the product franchise. Furthermore, both the number of the outlets of the business format franchisors and the total nominal sales through them had phenomenal growth between 1972 and 1986 (Lafontaine (1992)).

\(^3\)Case studies reveal that the main reason for franchising is to offer perspective franchisees a strong brand under which to operate (Dnes (1992)). It has been found that franchised units suffered significant loss of revenue when their brand names were revoked (Kaufmann and Lafontaine (1994)).
manager of each unit performs two possible tasks, goodwill and sales. If a manager’s payo® is tied to the revenue of her unit with a high-powered incentive contract, she will allocate too little of her e®ort on goodwill and too much of it on sales. This is because goodwill is a company-wide feature and thus the manager can free ride on the goodwill provided by other units, whereas the sales e®ort is unit speci¯c and the manager cannot rely on other units for its provision. In contrast, if given a low-powered contract, then she is indi®erent to the allocation of her e®ort between the two tasks and thus is willing to expend some goodwill e®ort to the extent that it does not bring about disutility. Therefore, in order to induce a goodwill e®ort, the company offers some of its managers low-powered contracts, despite these contracts’ adverse implications on overall e®ort level. With the goodwill provided by these units, sales e®ort becomes more important in the remaining units of the company, and high-powered incentive contracts are thus optimal. In a word, contract mix allows the HQ to induce production of goodwill (public good) and at the same time capture its positive externality within the company.

It is well documented that company-owned units are better than franchised units in terms of quality of services and adherence to uniform standards. In addition, most (if not all) franchisors require their units not to reveal to the public the ownership status (i.e., franchised or company-owned). These facts directly support our explanation of contract mix in franchise. Moreover, our model can reconcile the existence of company-owned units with the empirical nding that the pro®t margin under franchise ownership is much higher than that under company ownership (Shelton (1967)). With the low-powered incentive contracts, managers of company-owned units provide goodwill e®ort for the whole company at the expense of sales e®ort that would enhance their own pro®tability. Finally, when ex ante heterogeneity is properly modeled, our explanation is consistent with the empirical nding that units located along highways are more likely to be franchised (Brickley and Dark (1987)).

With contract mix understood, it remains to be explained why managers with the high-powered contracts own part or all of the units’ physical assets whereas those with the low-powered contracts do not. Our analysis on this issue is inspired by a stylized fact of the franchise, namely, the incompleteness of franchise contracts (Had®eld (1990)). When ex ante contracts are incomplete about development and maintenance of brand name products and services, they may become unenforceable ex post.

4For a business format franchise, goodwill has to be generated by managers who also engage in sales activities. In contrast, for a product franchise, brand names of complicated goods and services could be established independently. See Section 2 for discussion.

5Following Holmstrom and Milgrom (1991), we assume that the manager may exert e®ort up to some limit without explicit incentives, and incentives are only required to encourage work beyond that limit. See Footnote 12 of Section 2 for discussion.

6For example, Love (1986) documents that there were problems of quality and cleanliness in Mc-Donald’s franchised units (Chapter 4) and that the company-owned units were set up to encourage wayward McDonald’s franchisees to clean up their act” (Chapter 9). Also see Lewin (1996).

7For example, “many of the standards with which a McDonald’s franchisee must comply will not even be articulated until well after the contract has been signed” (Had®eld (1990)).
From MacLeod and Malcomson (1993, 1996), we know that an ex ante contract could become self-enforcing if the HQ and the manager have appropriate outside options. In contrast to MacLeod and Malcomson's reliance on contractual remedies for outside options, we focus on such roles of ownership arrangements. When the manager owns the asset, she can deny the HQ access to it. Then, the HQ's outside option is to conduct business with only the brand name, while the manager's is to provide generic goods and services. When the HQ owns the asset, it can deny the manager access to both the brand name and the asset. The manager thus does not have any outside option, while the HQ has the outside option of capturing all the revenue. We show that, for their contracts to be self-enforcing, managers with the high-powered contracts need to own their units' physical assets whereas those with the low-powered contracts should not. We further show that, in our setting, optimally chosen contractual remedies cannot mimic what the ownership arrangements have achieved.

It is generally held that, because the value of franchisees' assets depends crucially on the access to their company brand names, franchisees are extremely vulnerable to franchisors' opportunistic behavior. However, empirical studies by Kostecka (1987) found that in 1985 franchisors terminated 2,651 units, which equals only .87 percent of the estimated 301,689 units of business-format franchise companies existing then. It is interesting to note that this puzzle could be easily explained by our theory of ownership structures in the franchise.

This paper is built upon the multi-task theory and incomplete-contracts theory of the firm. Compared with Holmstrom and Milgrom (1991, 1994), this paper incorporates the possibility that one of the many tasks is of public good nature. Heterogeneity in task importance is then endogenously determined, and contract mix is optimal even for ex ante homogeneous units of the company. Compared with Grossman and Hart (1986) and Hart and Moore (1990), this paper considers revenue-sharing contracts in the setting of contractual incompleteness and explores other roles of ownership. In particular, the optimal ownership structure is chosen to make the ex ante contracts self-enforcing rather than to provide direct ex ante effort incentive. Furthermore, the optimality of the contract mix implies multiple ownership arrangements of complementary assets.

Gallini and Lutz (1992) also offer an explanation of contract mix in franchise. Their signalling theory that the franchisor owns some units to reveal its private information about profitability is probably more relevant to new franchises (Lafontaine (1993) and Lafontaine and Shaw (1996)). Lutz (1995) attempts to explain the ownership structures in a franchise by allowing only short-term contracts. She shows that managers with low-powered contracts should own their units, while those with high-powered contracts should not.

The plan of the paper is as follows. In Section 2, we introduce a multi-task model where there is no contractual incompleteness. In Section 3, the HQ's contract design problem is

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8When all tasks are of private good nature, optimality of contract mix depends crucially on ex ante heterogeneous task importance (Holmstrom and Milgrom (1991, 1994)).

9Hart, Shleifer, and Vishny (1996) discuss incomplete contracts with multiple tasks in a different context. In particular, they exclude the possibility of revenue-sharing contracts, and focus on how ownership structure affects the allocation of an agent's attention among her various tasks.
studied, and the optimality of the contract mix is established. In Section 4, by incorporating contractual incompleteness into our model, we show that incentive contracts of various power can be self-enforcing only in the presence of corresponding ownership structures as observed in a franchise. The paper concludes with Section 5. All proofs are in the appendix.

2. The Model
2.1. Production technology

Consider a company (or chain) that consists of the headquarters (HQ) and many units. To highlight the free-rider problem, we assume that there are infinite identical units. Furthermore, for simplicity, we assume that the units are indexed by $i \in I = [0; 1]$.

The manager of each unit performs two tasks: $s$ and $g$. $s$ is a unit-specific effort that affects only the revenue of the unit, and $g$ is a general effort that increases the revenue of all units of the company. For a fast food chain, for example, $s$ is the sales effort, and $g$ is the effort to develop customer goodwill towards the brand name of the chain, or to learn about customer tastes, or to develop new products. Other examples concern employee hiring and training. $s$ could be the effort to hire employees who are quick and able to follow existing production procedures exactly, while $g$ is to hire employees who like to develop new production processes. $s$ could also be the effort to train employees to have efficient services, while $g$ is the effort to train employees to pay attention to customers' need and come up with new products. From now on, we will call $s$ the sales effort and $g$ goodwill. The level of the two efforts are not verifiable and hence cannot be contracted on.

We assume, however, that the revenue of each unit is verifiable, as is the case for fast food chains. Furthermore, it is given by $x(i) = y(s(i); G) + \mu(i)$; where $\mu(i)$ is a normally distributed random variable with mean 0 and variance $\sigma^2$, $\mu$ is independent across units, and $G = \sum g(i) d_i$ is the total stock of goodwill possessed by the company. The specification of $y$ assumes that $g$ is a pure public good. We also assume that,

Assumption 1 $y$ is increasing and concave in $(s; G)$.

Though the analysis of the model is made most clear-cut by the assumption of infinite units and the pure public good nature of $g(i)$, the qualitative features of our main results remain when the company has finite units and/or goodwill has local effects. We will discuss the relaxation of these assumptions in Subsection 3.6.

The manager incurs a private cost of $c(s; g)$ to provide these efforts. We assume that these efforts are perfectly substitutable in the manager's cost function and that effort is not

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10In Section 4, we will consider scenarios where sales revenue may not be verifiable under certain conditions.
costly before it reaches a certain level.\footnote{We follow Holmstrom and Milgrom (1991) in using this cost function. They argue that in one-dimensional agency models, it is typically assumed that the agent will not work without incentive pay. The reason for this is not that the agent dislikes even small amounts of work, but rather that the level of work the agent would provide without explicit incentives does not affect the optimal solution. In multitask models, however, the fact that agents supply inputs even without incentive pay can be quite consequential. Indeed, the managers could be restricted from engaging in other activities. With nothing else to do, they might as well spend their time on sales and goodwill. Furthermore, monitoring could be effective in enforcing effort up to a certain level and incentive pay is only needed to induce effort beyond the level.}

Assumption 2 The cost of efforts \( s \) and \( g \) is \( c = c(s + g) \) and there exists some positive number \( T \) such that \( c(t) = 0 \) for \( t \leq T \), \( c(T) = 0 \), and \( c(t) > 0 \), \( c''(t) > 0 \) for \( t > T \).

It is clear that we adopt a multi-task model pioneered by Holmstrom and Milgrom (1991). However, we emphasize the difference in the scope of influence of the two tasks, whereas they focus on the difference in the measurability of the tasks.

2.2. Incentive contracts

We assume that the manager has constant absolute risk aversion. That is, the manager's utility function is \( u(z) = -e^{-rz} \), where \( r \) is the coefficient of absolute risk aversion and \( z \) is the manager's net (but risky) payo\(^\circ\). The HQ is assumed to be a risk-neutral profit maximizer. The HQ chooses a compensation scheme to induce the manager's efforts.

Although all managers are identical ex ante, the HQ can offer them different contracts. Without losing generality, we consider two types of contracts: (1) a fixed-wage contract, and (2) a high-powered contract that rewards the manager according to the revenue of her own unit.\footnote{One may argue that the HQ could also write: (a) a contract that rewards the manager based on the revenue of other units, or (b) a contract that rewards the manager based on the revenue of other units as well as on that of her own unit. Because there are in\(^\infty\)nite identical units, each unit is so small relative to the whole company that its level of goodwill does not affect the total stock of goodwill of the company. Furthermore, revenue is stochastically independent across units. Therefore, the revenue of other units does not contain any information about the manager's efforts and thus should not affect her compensation. Refer to Holmstrom (1982).}

Let \( w_i(x(i)) \) be the incentive contract for the manager of unit \( i \). Then the manager's expected utility is assumed to take the form

\[
u(CE) = \mathbb{E} u[w_i(x(i)) \mid c(s(i) + g(i))]g;
\]

where \( CE \) is the manager's certainty equivalent money payo\(^\circ\), and \( \mathbb{E} \) is the expectation operator. Given the incentive contract, the manager chooses \( s(i) \) and \( g(i) \) to maximize \( U(CE) \).
To summarize, the timing of events is as follows.
(1) At $t=0$, the HQ chooses contract $w_i(x(i))$ for all $i \in I$.
(2) At $t=1$, managers choose their sales and goodwill efforts simultaneously.
(3) At $t = 2$, the revenue is realized and the contracts are implemented.

3. Contract Mix
3.1. Contract design problem

In this analysis, we constrain the HQ to the choice of linear contracts. There is no loss of generality though. Holmstrom and Milgrom (1987) show that the optimal incentive contract in suitably stationary dynamic environments in which the agent can continuously monitor her own performance is equivalent to the optimum of a reduced-form static model in which the principal is constrained to linear contracts.

For $w_i = \alpha(i)x(i) + \gamma(i)$ where $\alpha(i)$ and $\gamma(i)$ are constants unrestricted in sign, we have:

$$CE(w_i) = \alpha(i)y(s(i); G) + \gamma(i) c(s(i) + g(i)) + \frac{1}{2} r^{\frac{3}{2}} \alpha(i)^2$$

At $t = 1$, given the contracts offered by the HQ, $f(\alpha(i); \gamma(i)) : i \in I$ $g$, the managers choose $(s(i); g(i))$. Specifically, taking $G$ as given, the manager of unit $i$ solves

$$\max_{s(i), g(i)} CE(w_i)$$

If $\alpha(i) > 0$, the manager of unit $i$ chooses $g(i) = 0$ and

$$s(i) = \arg \max_{s(i), 0} \alpha(i)y(s(i); G) + c(s(i))$$

This is because, in this case, the manager has an incentive to increase the revenue of her unit. The optimal way to do so is to allocate no effort to goodwill and all her effort to sales, as her goodwill effort has only an infinitesimal effect on the revenue of the unit while sales effort has a non-trivial positive effect. An incentive contract with $\alpha(i) > 0$ is called a high-powered contract. A manager who receives a high-powered contract is called an H manager, and her unit an H unit.

If the manager of unit $i$ receives a fixed-wage contract ($\alpha(i) = 0$), then she puts a total level of $T$ effort (i.e., $s(i) + g(i) = T$ and $c(T) = 0$) and is indifferent between the sales and goodwill efforts. This is because, in contrast to the case of $\alpha(i) > 0$, the manager’s pay does not depend on the revenue of her unit and consequently not on how her effort is allocated between the two tasks. Therefore, when $\alpha(i) = 0$, the manager is assumed to do what is requested by the HQ among the set of $O_i = f(s(i); g(i)) : s(i) + g(i) = T g$. An incentive contract with $\alpha(i) = 0$ is called a low-powered contract. A manager who receives a low-powered contract is called an L manager, and her unit an L unit.\(^{13}\)

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\(^{13}\)It is never optimal to have a negative $\alpha$.
The above discussion shows that the HQ can induce a goodwill effort only by offering managers' fixed-wage incentive contracts; there is discontinuity in the provision of the goodwill effort. The fundamental reason for this result is that goodwill is of public good nature, which implies that the effect of a manager's goodwill effort on the revenue of her unit is generally smaller than that of her sales effort. It follows that, so long as the manager's income depends on the revenue of her unit, she will not fully take into account the externality of her goodwill effort and will provide too little goodwill. The HQ can overcome the under-provision of goodwill effort only by delinking a manager's income from the revenue of her unit.

Let \( p \) be the proportion of \( L \) units and \( L = [0; p] \mu L \) be the set of \( L \) units. Then \( G = \sum L g(j) dj \) and the HQ's expected total profit is

\[
\mathbb{E} = \sum_{L} \left[ y(T; g(j); G) w(j) \right] dj + \sum_{i \in L} \left[ (1 - \beta(i)) y(s(i); G) \right] \beta(i) di;
\]

where \( g(j) \) is the level of goodwill effort chosen by the HQ for the \( L \) unit with index \( j \) and \( s(i) \) is the level of sales effort chosen by the manager of the \( H \) unit with index \( i \). At \( t = 1 \) (given \( p, f(w(j)) g_{2L} \) and \( f(\beta(i)); \beta(i) g_{2j_1, L} \)), taking \( f(s(i)) g_{2i_1, L} \) as given, the HQ chooses \( f(g(j)) g_{2L} \) to maximize \( \mathbb{E} \), i.e.,

\[
f(g(j)) g = \arg \max_{f(g(j)) g} \mathbb{E} : (OP j G)
\]

In summary, at \( t = 1 \), \( f(s(i)) g_{2i_1, L} \) and \( f(g(j)) g_{2L} \) are jointly determined by \((OP j s)\) and \((OP j G)\).

At \( t = 0 \), the HQ chooses \( p, f(w(j)) g_{2L} \) and \( f(\beta(i)); \beta(i) g_{2j_1, L} \) to maximize the expected total profit, subject to the incentive compatibility constraints (i.e., \((OP j s)\) and \((OP j G)\)) and to the individual rationality constraints that managers are willing to accept the contracts. We normalize the reservation utility of the managers to be 0. Then, the HQ's problem at \( t = 0 \) is to choose \( p, f(\beta(i)); \beta(i) g_{2j_1, L} \), and \( f(w(j)) g_{2L} \) to

\[
\max_{L} \left[ y(T; g(j); G) w(j) \right] dj + \sum_{i \in L} \left[ (1 - \beta(i)) y(s(i); G) \right] \beta(i) di \quad (OP ; H Q)
\]

s.t: \((OP j s);(OP j G)\)

\[
f(w(j)) , 0 \quad \text{for all } j \in 2 L
\]

\[
\beta(i) y(s(i); G) + \beta(i) c(s(i)) \left[ \frac{1}{2} r^{3/2} \beta(i)^2 \right], 0 \quad \text{for all } i \in 2 I \quad (I R)
\]

Since \( w(j) \) and \( \beta(i) \) do not affect the incentive compatibility constraints, the individual rationality constraints must be binding at the optimum. Otherwise, the HQ's expected total profit can be increased by reducing \( w(j) \) or \( \beta(i) \). By substituting constraints (IR) into the objective function, the HQ's optimization problem at \( t = 0 \) is simplified as:

\[
\max_{p, \beta(i) g_{2j_1, L} \in L} \left[ y(T; g(j); G) \right] dj + \sum_{i \in L} \left[ y(s(i); G) c(s(i)) \right] \left[ \frac{1}{2} r^{3/2} \beta(i)^2 \right] di \quad (OP ; H Q^9)
\]
In order to analyze the HQ’s contract design problem, we first characterize some necessary conditions for the optimal incentive contracts (Subsection 3.2) and then investigate the equilibrium outcome given the incentive contracts (Subsection 3.3).

3.2. Uniformity of high-powered and low-powered incentive contracts

Our first result regards the uniformity of \( L \) units.

**Proposition 1** The HQ should request the same level of goodwill effort from all \( L \) managers.

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Thus \( g(j) \) is chosen at \( t=1 \) to solve program (OP \(_i \) G). Given any \( p \) and \( f @G(i) \) this can be done in two steps: (1) Given \( G \), choose the optimal allocation \( f g(j) \) so that \( g(j)\mathfrak{d}_j = G \); (2) Choose the optimal \( G \). Note that, for given \( G \), the second term of the objective function of (OP \(_i \) G) is independent of the allocation \( f g(j) \). Therefore, step (1) is equivalent to maximizing \( \sum L y(T-g(j);G)\mathfrak{d}_j \). Since \( y(T-g(j);G) \) is concave in \( g \), an application of Jensen’s inequality implies that it is optimal to choose the same \( g(j) \) for all \( L \) units.

To characterize the optimal incentive contracts further, we make additional assumptions about the production and cost functions.

**Assumption 3** \( \lim_{s \to 0} y_s \frac{\partial y_s(s;G)}{\partial s} = 1 \), and \( \lim_{G \to 0} y_G \frac{\partial y_G(s;G)}{\partial G} = 1 \).

**Assumption 4** \( \frac{c_s(s)}{y_s(s;G)} \) is convex in \( s \).

**Assumption 5** The marginal product of goodwill effort, \( y_G \frac{\partial y_G(s;G)}{\partial G} \), is increasing and concave in \( s \).

**Assumption 3** is made to avoid possible complications of corner solutions. Assumption 4 holds if the cost function is sufficiently convex. In the case that the production function is Cobb-Douglas and the cost function is \( c = (s + g)^\gamma \), it is satisfied if \( \gamma \) is sufficiently large. Assumption 5 says that \( s \) and \( G \) are complementary and the return to \( s \) in enhancing the marginal product of \( G \) diminishes.

By Proposition 1, Assumptions 1 and 3, we have

**Lemma 1** Program (OP \(_i \) HQ\(^0\)) is equivalent to

\[
\begin{align*}
\max & \quad \sum_{i \in I} p y(T-i;G) + \sum_{i \in I} y_s(T-i;G) \frac{c(s(i))}{y_G(s(i);G)} \frac{1}{2} r^2 \frac{\partial y_G(s(i);G)}{\partial G} \mathfrak{d}_i (IC \_i G) \\
\text{s.t.:} & \quad py_G(T-i;G) y_s(T-i;G) + \sum_{i \in I} (IC \_i G) y_G(s(i);G) \mathfrak{d}_i (IC \_i s)
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\]

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\text{s.t.:} & \quad py_G(T-i;G) y_s(T-i;G) + \sum_{i \in I} (IC \_i G) y_G(s(i);G) \mathfrak{d}_i (IC \_i s)
\end{align*}
\]
Program \((\text{OP}_{\text{HQC}})\) can be solved in three steps: (1) Solve for \(\text{OP}(i)\) from constraint \((\text{IC}_{i})\) and substitute it into the objective function and other constraint; (2) Given \(G\) and \(p\), solve for the optimal \(f_{s}(i)g\); (3) Solve for the optimal \(G\) and \(p\). By Lemma 1, Assumptions 4 and 5, we can show that step (2) is a concave program.

**Lemma 2** Let \(\text{OP}(i) = c(s) = y_{s}(s; G)\). Then, given \(G\), the integrand in the objective function of program \((\text{OP}_{\text{HQC}})\),

\[
y(s(i); G) = c(s(i)) \cdot \frac{1}{2} \alpha^{2}(i)^{2};
\]

and the integrand in constraint \((\text{IC}_{i})G\),

\[
(1 - \text{OP}(i))y_{G}(s(i); G);
\]

are both concave functions of \(s(i)\).

Lemma 2 and an application of Jensen's inequality imply,

**Proposition 2** The HQ should offer the same high-powered contract to all H managers.

Proposition 2 is more involved than Proposition 1 because, in contrast to the L managers, both the sales and total efforts by the H managers are directly affected by the high-powered incentive contracts, as is the HQ’s choice of goodwill level. Instead of offering a single high-powered contract, the HQ could offer two contracts, one less high-powered and the other more high-powered, under which one group of H managers would decrease their sales effort and the other increase their sales effort. When the cost function is not convex enough, the decrease in sales effort is not too much while the increase in the sales effort is quite a lot, and the HQ could benefit by offering different high-powered contracts. However, when the cost function is sufficiently convex (specifically, when Assumption 4 is satisfied), offering the same high-powered contract increases the average sales effort of the H managers. When \(s\) and \(G\) are complementary as Assumption 5 says, this also increases the HQ's incentive to choose a high level of goodwill.

Empirical studies by Lafontaine and Shaw (1996) show that, while they vary from one franchisor to another, franchise contracts are extremely uniform across franchisees and stable over time within any particular franchise company. McAfee and Schwartz (1994) offer a market-based explanation for this phenomenon. Specifically, in their model, after signing a contract with one franchisee, a franchisor is tempted to offer another franchisee a contract with a lower royalty rate to undercut the first franchisee and therefore obtain a higher lump-sum fee. Knowing the franchisor has such opportunistic behavior, the first franchisee is reluctant to accept the contract, and the franchisor is thus better off by committing to a uniform contract for all franchisees. Note that in our setup, each manager is a local monopoly and McAfee and Schwartz's argument is no longer applicable. Our model thus offers an alternative and purely technological explanation for the uniformity of franchise contracts.
3.3. Equilibrium outcomes given the uniform contracts

Propositions 1 and 2 greatly simplify the contract design problem (Subsection 3.1). Let \((w)\) be the low-powered contract offered by the HQ to all L managers, and \(g\) is the goodwill effort. Let \((\, g\, )\) be the high-powered contract offered by the HQ to all H managers, and \(s\) is the corresponding sales effort.

Recall that, at \(t = 1\) (given \(p\), \((w)\) and \((g\))), H managers choose \(s\) and the HQ picks \(g\). For \(\ominus > 0\), H manager's optimal choice of \(s\) is characterized by

\[
\frac{\partial y_s(s; G)}{\partial s} = 0; \quad (F O C \ i \ s)
\]

The HQ's objective function at \(t = 1\) becomes

\[
\frac{\partial \Pi}{\partial G} = p[y(T \mid g; G) \mid w] + (1 \mid p)[(1 \mid \ominus) y(s; G) \mid -]; \quad \text{where } G = pg
\]

For \(p > 0\), the HQ's optimal choice of \(g\) is characterized by

\[
p y_G(T \mid \frac{G}{p}; G) \mid y_s(T \mid \frac{G}{p}; G) + (1 \mid p)(1 \mid \ominus) y_G(s; G) = 0; \quad (F O C \ i \ G)
\]

where the left hand side of the equation is equal to \(\frac{\partial \Pi}{\partial G}\). Thus, at \(t = 1\) (given \(p\), \((w)\) and \((g\)')), equilibrium \((s; G)\) are determined simultaneously by \((F O C \ i \ s)\) and \((F O C \ i \ G)\).

By the concavity of \(y\), it is a standard exercise to show that, for \(\ominus > 0\) and \(p > 0\), the Jacobian matrix of \((F O C \ i \ s)\) and \((F O C \ i \ G)\) has a positive determinant. Then, we have,

Lemma 3 For \(\ominus > 0\) and \(p > 0\): (1) Equilibrium \(s\) and \(G\) are differentiable functions of \((\ominus, p)\). (2) Equilibrium \(s\) and \(G\) both increase (or decrease) with \(p\) if \(\frac{\partial^2 \Pi}{\partial \ominus \partial p} > 0\) (or \(\frac{\partial^2 \Pi}{\partial \ominus \partial p} < 0\)). (3) The effects of \(\ominus\) on equilibrium \(s\) and \(G\) are usually ambiguous.

Regarding the boundary cases, for \(p = 0\), \(G = pg = 0\) and \(s\) is determined by

\[
\frac{\partial y_s(s; 0)}{\partial s} = 0; \quad (F O C \ i \ s)
\]

For \(\ominus = 0\), \(s\) and \(G\) are defined as:

\[
s(0; p) = \lim_{\ominus \to 0} s(\ominus, p) \quad \text{and} \quad G(0; p) = \lim_{\ominus \to 0} G(\ominus, p)
\]

Then, we can show,

Lemma 4 \(s\) and \(G\) are continuous functions of \((\ominus, p)\) on \([0; 1]^2\).
To conclude our analysis in Subsections 3.2-3.3, note that the HQ's objective function at \( t = 0 \) becomes:

\[
\phi_0(\pi; p) = py(T; \frac{G}{p}; G) + (1 - p)[y(s; G) + c(s) - \frac{1}{2}r^{(G \pi)}];
\]

where \( s \) and \( g \) are the equilibrium defined by (FOC \( s \)) and (FOC \( G \pi \)), and functions of \( (\pi; p) \). By Lemma 4, \( \phi_0(\pi; p) \) is a continuous function of \( (\pi; p) \) on \([0, 1]^2\). The HQ chooses \( \pi \) and \( p \) to maximize \( \phi_0(\pi; p) \). The Weierstrass Theorem then implies,

Corollary 1 The optimal \( (\pi; p) \) exists.

### 3.4. Characterization of the high-powered contract

When the HQ chooses \( \pi \), it considers several factors. First, as \( \pi \) increases, H managers are subject to more risk and therefore need to be compensated more. Second, the value of \( \pi \) affects the HQ's incentives to provide goodwill \( \pi \) and H manager's incentives to expend sales \( \pi \). Differentiate \( \phi_0 \) with respect to \( \pi \) and simplify the derivative with (FOC \( s \)) and (FOC \( G \pi \)). We have, for \( \pi > 0 \),

\[
\frac{d\phi_0}{d\pi} = (1 - p)\frac{G}{\pi} + \pi(1 - p)y_s \frac{dG}{d\pi} + (1 - p)(1 - \pi)y_s \frac{ds}{d\pi},
\]

where a function with a superscript \( H \) means that it is evaluated at \( (s; G) \). On the right hand side of (2), the first term captures the risk factor and is negative, and the next two terms describe the effects of \( \pi \) on \( \phi_0 \) through \( G \) and \( s \), respectively.

Proposition 3 For any \( p \in [0, 1) \), the optimal \( \pi \in (0, 1) \).

The intuition for this result is quite clear. To induce \( \pi \) from H managers, the HQ has to offer them a positive \( \pi \). To commit itself to choosing a high level of goodwill \( \pi \), the HQ needs \( \pi < 1 \) so that it still cares about the \( \pi \) of goodwill \( \pi \) on H units' revenues.

### 3.5. Characterization of contract mix

By equation (1), the HQ's total profit is \( \phi = p^{\frac{1}{4}} + (1 - p)^{\frac{1}{4}} \), where \( \frac{1}{4} \) \( y(T; \frac{G}{p}; G) \) is the HQ's expected profit from a L unit, and \( \frac{1}{4} \) \( y(s; G) + c(s) - \frac{1}{2}r^{(G \pi)} \) is the HQ's expected profit from a H unit. If \( \frac{1}{4} \) and \( \frac{1}{4} \) were independent of \( p \), then either a high-powered contract or a low-powered contract would be offered by the HQ to all managers (namely, either \( p = 0 \)

\[\text{For the case } p = 0, \text{ the proposition needs the additional assumption that } y(s; 0) \notin 0. \text{ Note that } \phi_0(0; 0) \text{ is defined to be } \lim_{\pi \to 0} \phi_0(\pi; 0). \text{ At } p = 0, \text{ Proposition 3 says that there exists some } \pi \in (0, 1) \text{ such that } \lim_{\pi \to 0} \phi_0(\pi; 0) < \phi_0(0; 0).\]
or \( p = 1 \). The contract mix (namely, \( p 2 (0; 1) \)) would only be optimal with probability zero when \( 1/4 = 1/4^i \).

In this model, however, goodwill is a public good. In addition, only \( L \) managers can provide a goodwill e\( @\)ort. This seems to justify the existence of \( L \) units as they have positive externality on other units of the company. On the other hand, \( L \) managers, because of the low-powered contract, expend a lower level of total e\( @\)ort than \( H \) managers \( (s(j) + g(j) = T \) for \( j 2 L \), whereas \( s(i) < T \) for \( i 2 L \)), which makes the \( L \) units less pro\$table. Intuition therefore suggests that the HQ offers a high-powered contract to some managers and a low-powered contract to the others.

To investigate the optimality of contract mix, for \( p > 0 \), we differentiate \( \psi \) with respect to \( p \) and simplify the derivative by \( (FOC_i s) \) and \( (FOC_i G) \).

\[
\frac{d\psi}{dp} = \left( \frac{1}{4} \cdot i \cdot \frac{1}{4^i} \right) + (1 \cdot i \cdot p) \frac{\partial s}{\partial p} \frac{\partial G}{\partial p} + (1 \cdot i \cdot p)(1 \cdot i \cdot \frac{\partial s}{\partial p} \frac{\partial G}{\partial p}) + gy_L \frac{\partial s}{\partial p} + \frac{\partial s}{\partial p} \frac{\partial G}{\partial p} \right)
\]

where a function with a superscript \( H \) (\( L \), respectively) means that it is evaluated at \( (s; G) \) \( ((T \cdot i \cdot \frac{\partial s}{\partial p} \frac{\partial G}{\partial p}), \frac{\partial s}{\partial p} \frac{\partial G}{\partial p}) \) respectively.

When there is one more \( L \) unit, the HQ gains \( 1/4 \) but loses \( 1/4^i \). The first term on the right hand side of (3) captures this direct e\( @\)ect. Proposition 4 says that this direct e\( @\)ect is negative.

Proposition 4 For any given \( p 2 (0; 1) \), \( \frac{1}{4} < \frac{1}{4^i} \) at the corresponding HQ’s optimal choice of \( @ \).

There are two reasons for the result of Proposition 4. One is that, to induce goodwill e\( @\)ort, the HQ is constrained to e\( @\)ering the low-powered incentive contract to \( L \) managers. As a result, \( L \) managers expend a lower level of total e\( @\)ort than \( H \) managers. The other reason is that \( H \) managers free ride on \( L \) managers for goodwill and therefore they are able to put more e\( @\)ort on sales. Both reasons stem from the public good nature of goodwill e\( @\)ort. Interestingly, Proposition 4 is supported by empirical findings (Shelton (1967)).

Proposition 4, however, does not imply that there should be no or very few \( L \) units. \( L \) units are important because they are the only providers of goodwill e\( @\)ort, which not only increases pro\$ts of all units directly, but also a\$cts the productivity of sales e\( @\)ort in \( H \) units. The second and the third terms on the right hand side of (3) capture, respectively, the e\( @\)ect of \( p \) on \( \psi \) through total stock of goodwill and that through the level of sales e\( @\)ort of \( H \) managers. The signs of these two terms are the same as those of \( \frac{\partial s}{\partial p} \) and \( \frac{\partial G}{\partial p} \) respectively, and are therefore ambiguous by Lemma 3.

When \( p 6 1 \), the burden of providing a given level of goodwill, \( G \), is borne entirely by \( L \) units. Because the sales e\( @\)ort has decreasing returns to scale, the cost of \( L \) units devoting less e\( @\)ort to sales exceeds the bene\$t of \( H \) units being able to exert more e\( @\)ort in sales. Having more \( L \) units mitigates such inefficient substitution between sales and goodwill e\( @\)orts across units. This substitution e\( @\)ect is captured by the fourth term on the right hand side of (3) and is always positive.
Note that, if \( y(s;0) = 0 \) for all \( s \), the optimality of \( p^* > 0 \) is straightforward. Specifically, at \( p = 0 \), \( G = 0 \) and \( \frac{\partial}{\partial p} > 0 \); but at \( p > 0 \), \( G > 0 \) and \( \frac{\partial}{\partial p} > 0 \). Therefore, the optimal \( p \) must be positive. Intuitively, if the revenue vanishes in the absence of goodwill, then the HQ must have the L units to provide the essential input.

Our analysis, however, is focused on the scenario that \( y(s;0) > 0 \). It is then not so apparent that the optimal \( p \) has to be positive. In that case, a sufficient condition for \( p^* > 0 \) is \( \frac{d}{dp} > 0 \) as \( p \to 0 \), which we can show under the following assumption.

Assumption 6 If \( y(s;0) > 0 \) for \( s > 0 \), then \( y_s s s \cdot \frac{\partial}{\partial p} > 0 \) for \( \partial < 1 \).

Assumptions 1, 3, 5, and 6 (all about the revenue function) are satisfied by the functions of \( y(s;G) = c_0 s^a G^b + c_1 s^\pm + c_2 G^\prime \), with \( c_0 \), \( c_1 \), and \( c_2 \) non-negative as well as \( a \), \( b \), \( \pm \) and \( \prime \) between 0 and 1, which include Cobb-Douglas functions as special cases. Note that, in terms of the importance of \( G \) to the revenue function, Assumption 6 imposes much fewer restrictions than \( y(s;0) = 0 \) does. Furthermore, Assumption 4 is satisfied if \( y \) takes the above form and the cost function has the form of \( c = (s + g) \cdot \) with \( a \) sufficiently large.

Lemma 5 If \( y(s;0) \not= 0 \), then \( \lim_{p \to 0} \frac{\partial}{\partial p} > 0 \) for \( \partial < 1 \).

This, together with Lemma 4 and Proposition 3, implies that

Proposition 5 It is optimal for the company to have some L units.

Having established the optimality of \( p^* > 0 \), we turn to the question of when it is optimal for the HQ to have some H units, namely, \( p^* < 1 \). With L units providing the goodwill, the HQ can offer managers of the remaining units high-powered incentive contracts and thereby elicit high sales effort from them. Whether or not high-powered incentive contracts should be offered to some managers depends on the magnitudes of their costs and benefits.

One cost of high-powered incentive contracts is that they subject the managers to risks, resulting in inefficient risk sharing between the risk neutral HQ and the risk adverse managers. The cost is lower when the managers are less risk adverse or when there is less uncertainty. The main benefit of high-powered incentive contracts is that they elicit a high sales effort from H managers. When the marginal costs of sales effort are lower, it is easier to induce it and thus the benefit of high-powered contracts is higher. Therefore, we have:

Proposition 6 It is more likely for the HQ to have H units when the managers are less risk adverse, or when the uncertainty about the revenue is smaller, or when marginal cost of effort is smaller.

Proposition 6 gives one set of conditions for the HQ to have H units, namely, H units are attractive enough. A complementary set of conditions is that L units do not perform very well. With low-powered incentive contracts, the total level of efforts is \( T \). If \( T \) is very small, the profits from L units are very low. Therefore, we have:
Proposition 7 It is more likely for the HQ to have H units when T is smaller.

3.6. Discussion

Before concluding this section, we discuss the pure public good assumption and the infinite unit assumption. Then we argue for the consistency of our model with the evidence on the locational distribution of different types of units.

3.6.1. Finite units and local effects of goodwill

When $g$ is not a pure public good (equivalently, $g$ has some local effect), the managers will admittedly have more incentives to develop goodwill. However, they still will not take into account the positive externality of goodwill on other units and thus will not do enough for goodwill. In fact, so long as the local effect of goodwill effort is not extremely strong, it is still optimal to give some units low-powered incentive contracts so that their managers are more willing to provide goodwill than they would when they had high-powered incentive contracts.

When there are only finite units, the optimal reward to a manager could depend on the revenue of other units and this, admittedly, will give the manager some incentives to develop goodwill. However, for such incentives to be strong enough, the share of the manager's income from the revenue of other units must be large enough. Such a high share brings about a high cost of risk and has to be compensated by substantially lowering the share of income from the revenue of the manager's own unit. Therefore, the incentives for sales effort will be greatly reduced. In summary, inducing goodwill effort by linking the manager's reward to the revenue of other units is very costly in terms of sales effort. It is still better to generate goodwill by giving some managers low-powered incentive contracts.

3.6.2. Highway evidence

Since Rubin (1978), the franchise has been considered as a way of dealing with managers' incentive problems rather than raising money from small investors. Assuming that the goodwill is already established, the choice between company units and franchised units is influenced by the following two concerns: (1) company managers are more likely to put in low level of effort (the shirking problem), (2) franchisees have more incentive to substitute low quality products (the free-rider problem). What is implicit in the above discussion is that the shirking problem is much less severe for franchisees as they have high-powered contracts, while

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16 In this context, a high-powered contract links the manager’s reward more closely to the revenue of her own unit than to that of other units, whereas a low-powered contract links her reward only to the total revenue of the whole company.

17 Roughly speaking, a one-percentage-point increase in the share of revenue from other units needs to be compensated by a $\frac{1}{N}$-percentage-point decrease in the share of revenue from her own unit, where $N$ is the number of units in the company.

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the free-rider problem is much less severe for company managers as they have fixed wages.

When a unit is away from its monitoring center (HQ), the shirking problem becomes severe if the unit is company-owned. This implies that company ownership is more likely for units that are closer to the monitoring center. On the other hand, when a unit is situated in an area (such as a highway) where there are a lot of non-repeat customers, then the free-rider problem is serious if the unit is franchised. This suggests that, compared with other units, highway units are more likely to be company owned. Brickley and Dark (1987) formally test the above two hypotheses, but they find support only for the first one. In particular, they find that highway units are more likely to be franchised. Holmstrom and Milgrom (1994) also discuss the tension between their theoretical predictions and the highway evidence.

Note that, in our model, the goodwill is endogenously generated. Specifically, company-owned units are chosen for the production of goodwill, whereas franchised units are used to reap the benefits of company goodwill. In other words, the HQ is fully aware of the low goodwill effort in the franchised units, and it is simply not optimal for the HQ to induce same goodwill effort in all units. This implies that the free rider problem (which is affected by the percentage of non-repeat customers) itself is not that crucial so long as the HQ can enforce the minimum quality standard (i.e., $g$ is non-negative). More importantly, when units are heterogeneous, our model would predict that company ownership is more likely for those units that have more advantage in generating goodwill and that the HQ is located near those units to alleviate the shirking problem of the company managers.

Consider again that there are many types of customers (highway, residential, downtown, etc.). We want to argue that highway units do not have more advantage in generating goodwill than downtown stores, which could then explain the highway evidence. Our argument is based on how goodwill or brand name is established. Conceivably, for goodwill production, a company needs to ensure that its initial customers like the products and then spread favorable impressions to those who have not purchased the products. To achieve maximum impact, it is important that those initial customers are from various submarkets and therefore they can spread their impressions to a wide population of the society. We believe that the downtown units serve more diverse customers than the highway units. For example, for a Boston Common McDonald's, the customers could be tourists or business people of other cities as well as people who live in the vicinity of the Boston Common. Even truck drivers who usually frequent highway McDonald's may bring their kids to the Boston Common on Sundays. The rest of the argument follows immediately.

It is important to our argument that there are many types of customers, only one of which is highway customers. If the whole market were highway customers and downtown customers, then it would be optimal to have some company owned units along highways to spread positive impressions directly among such a large group of customers.

We have argued that the downtown units are in better position to spread positive impressions about existing brands than highway units. The same argument also works for product development. Note that, for the HQ to assess the marketability of a new product, it is important to get feedback from a diverse group of customers at fewest number of stores. As argued above, the downtown units tend to have more diverse customers and therefore
they are natural candidates for company ownership.\textsuperscript{18}

4. Ownership and Contract Enforceability

The above analysis has addressed the first distinguishing feature of a franchise, namely, that both high-powered and low-powered incentive contracts are used. What remains to be explained is why managers with the high-powered incentive contract own some or all of their units' physical assets whereas those with the low-powered incentive contract do not. In this section, we first discuss a stylized fact of franchise, namely, incompleteness and hence unenforceability (by third parties) of ex ante incentive contracts. We then show that the incentive contracts of various power can only be voluntarily enforced, and hence the desirable incentives be protected, in the presence of the corresponding ownership arrangements.

4.1. Contractual incompleteness in a franchise

A basic assumption in Sections 2 and 3 is that contracts are complete. The HQ offers the low-powered incentive contract to some managers who provide the goodwill effort, and the high-powered incentive contract to others who expend all their effort on sales. Once these contracts are written, the HQ is no longer needed for carrying out the business.\textsuperscript{19} In this complete-contracting framework, it does not matter whether the units' physical assets are owned by the managers or by the HQ.\textsuperscript{20}

In reality, the retail markets for the HQ's brand name products and services are significantly uncertain. The HQ needs to set the standards and policies to be followed by the franchisees in response to market changes in order to develop and maintain its brand name. For example, when new scientific studies reveal that some of the food ingredients are not healthy enough, the HQ (of a fast-food business) may choose to replace those ingredients. To write complete contracts with the managers, it requires the HQ to foresee all possible future contingencies and devise corresponding strategies for the managers, which is very costly if not impossible. As a result, "many of the standards with which a franchisee must comply will not even be articulated until well after the contract has been signed," and "the key characteristic of the franchise contract is its incompleteness" (Hadley (1990)).

Rather than writing complete contracts ex ante, the HQ retains the residual rights of control to make business decisions ex post as unforeseen contingencies arise (Grossman and}
Hart (1986), Hart and Moore (1990), Hart (1995)). An examination of the McDonald's franchise contract reveals that the HQ has substantial residual rights of control, and that its franchises are required to "strict adherence to licensor's standards and policies as they exist now and as they may be from time to time modified." A recent example is the outbreak of mad cow disease and the subsequent decision by McDonald's of not using UK beef.

While the residual rights of control greatly facilitates the HQ to develop and maintain its brand name in response to market changes, it also gives the HQ an opportunity to hold up the managers ex post. A HQ may investigate a minor or curable contract violation not to promote the quality of its franchisees but to achieve some other, opportunistic goal at the franchisee's expense, or abuse its power in order to transfer the franchises to more profitable franchisees or to convert the outlets to company ownership (Hedlund (1990)).

It should be stressed that the objective of this paper is not to probe why franchise contracts are often incomplete. There is an extensive body of legal studies on this issue (see Hedlund (1990) and references therein). Among the reasons suggested are the importance of brand name products and services, the uncertainty of the retail markets, and the need for quick responses to possible market changes. See also Anderlini and Felli (1994), Hart (1995), MacLeod (1996a, 1996b), Maskin and Tirole (1996), and Segal (1995) for the theoretical foundations of the incomplete-contracts approach. What this paper attempts to show is that, given the contractual incompleteness in a franchise, the ex ante incentive contracts of various power can be voluntarily enforced only in the presence of the corresponding ownership arrangements.

4.2. Unenforceability of ex ante contracts

In the presence of contractual incompleteness, disputes between the HQ and the managers are inevitable. Moreover, contractual incompleteness makes it difficult to verify which party is at fault and implement penalties for breach of ex ante incentive contracts. This implies that ex ante contracts may become unenforceable ex post, and renegotiation could be initiated by either the HQ or the managers.

Accordingly, the timing of events is modified as follows (see also Figure 1). At $t = 0$, the HQ designs the high-powered and low-powered contracts and chooses the contract mix ratio ($p$). It also makes ownership arrangements for the units' physical assets. At

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21In her seminal paper, Hedlund (1990) reviews several cases on franchise contracts (Picture Lake Campground v. Holiday Inns, 497 F. Supp. 858, 869 (E.D. Va. 1980), Vaughn v. General Foods Corp., 797 F.2d 1407, 1411, 1415 (7th Cir. 1986)) and concludes that the courts have taken the so-called business judgment approach. Specifically, the courts treat the franchisor's interest as if it represented the entirety of the relation. As a result, the franchisors could always come up with some business justification for termination of franchise contracts and therefore do not need to pay any penalty to the franchisees. As for franchisees, they certainly have the freedom to leave the relationship voluntarily; however, under the business judgment approach, they don't expect to receive any payment from the franchisors except for getting back the value that is attached with their asset investment.

22In the following analysis, we consider scenarios where it is optimal for the HQ to offer some
t = 1, the managers choose s and g simultaneously. We call this the investment stage of the game. We maintain the assumption that, if a manager is indifferent between some choices, she will choose the one most preferred by the HQ. At t = 2, potential revenue becomes known to the HQ and the manager. They then have the option to sever their relationship. They decide whether to sever the relationship, and if not, whether to renegotiate the revenue-sharing contract. We call this stage of the game the renegotiation stage. As there is perfect information at this stage, renegotiation takes a negligible amount of time. After the renegotiation stage, production is carried out. We normalize the length of the entire game to be 1 and assume that the period before t = 2 is of length 1 - 2 [0; 1) and that after t = 2 is thus of length 23.

We adopt MacLeod and Malcolmson's (1993) specification and analysis of the renegotiation stage of the game. In MacLeod and Malcolmson (1993), both a no-trade and outside option could be the triggers for contract renegotiation. In our model, however, trade is always preferred by both parties to no-trade, and the only possible trigger for contract renegotiation is the outside option. Let u denote the HQ's stage payoû under the ex ante incentive contract, and v denote that of the manager. Let u_0 be the HQ's stage payoû from the outside option, and v_0 be that of the manager. u_0 and v_0 are determined by the ownership arrangements in Subsection 4.3, and they can be specified by contracts in Subsection 4.4.

We obtain the following equilibrium of the renegotiation subgame.

Proposition 8 (MacLeod and Malcolmson (1993)) Suppose u + v > u_0 + v_0. The payoûs to the HQ and the manager in any subgame perfect equilibrium of the renegotiation subgame are given by U and V, where ½ is the interest rate,

\[ \frac{1}{2} U = u + v \]  
\[ \frac{1}{2} V = u + v - \frac{1}{2} U; \]  
\[ \frac{1}{2} U = u_0; \]  
\[ \frac{1}{2} V = v_0; \]  
\[ \frac{1}{2} U = v; \]  
\[ \frac{1}{2} V = u; \]  
\[ \frac{1}{2} U = v_0; \]  
\[ \frac{1}{2} V = u_0; \]  
\[ \frac{1}{2} U = u; \]  
\[ \frac{1}{2} V = v; \]  
\[ \frac{1}{2} U = \begin{cases} u + v - \frac{1}{2} U & \text{when } v > v_0; \\ u_0 & \text{when } u > u_0; \\ u & \text{otherwise.} \end{cases} \]  

Proposition 8 shows that, whenever the manager (or the HQ) has higher payoû from the outside option than from the ex ante incentive contract, the renegotiation is initiated and the manager (or the HQ) obtains her outside option payoû under the new incentive contract.

4.3. Ownership and self-enforcement of ex ante contracts

It was shown in Subsection 4.2 that, depending on the outside options of the HQ and the managers, the revenue-sharing contracts (designed at t = 0) could be renegotiated (at t = 2) thereby distorting the eûort incentive of the concerned parties. In this subsection, we assume away any contractual remedies for the event of an outside option. The parties' payoûs under managers the high-powered contract (i.e., p^e < 1).

23As long as the incentive contract is not renegotiated after the uncertainty is resolved, the argument for linear contracts still applies (Holmstrom and Milgrom (1987)).
the outside option are thus determined solely by the ownership arrangements of the units' physical assets. We show that appropriate ownership arrangements at $t = 0$ can ensure voluntary self-enforcement of the ex ante contracts at $t = 2$. In the next subsection, we conclude our analysis by showing that the contractual remedies, even optimally chosen, cannot mimic what the ownership arrangements do. Taken together, we can explain not only multiple ownership arrangements of a franchise but also their correspondence with the incentive contracts of various power.

Recall that, in the complete-contracting framework as described in Section 3, the HQ offers the high-powered incentive contract ($@^0; −^n$) to some managers and the low-powered incentive contract ($w^0$) to others. These contracts induce the second-best sales effort $s^a$ and goodwill effort $G^a = p g^a$. In the incomplete-contracting framework considered here, the same ex ante contracts would generally lead to inefficient equilibrium sales and goodwill efforts, denoted by $s^e$ and $G^e$ respectively, as the ex ante contracts may be renegotiated. Our objective is to find ownership arrangements under which, in the subgame perfect equilibrium, $(s^e; G^e)$ coincides with the second-best $(s^a; G^a)$ and no renegotiation occurs. Such ownership arrangements, if they exist, are said to make the ex ante contracts ($@^0; −^n$) and ($w^0$) self-enforcing.

Before we analyze individual cases, note that the managers' efforts are not human capital in our model. Once the goodwill and sales efforts are made by the manager of a unit, the former is attached to the company's brand name while the latter is embedded in the unit's physical asset.

Also note that the HQ could make a lump-sum payment $w_1$ to the manager between the investment stage and the renegotiation stage. In this case, the manager's outside option is either to provide generic goods and services without access to the company goodwill ($y(s^e; 0)$) or to work for another company and get her reservation wage ($−^n w_0$). On the other hand, the HQ's outside option is $y(0; G^e) + (−^n w_0)$.25

(A) We first turn to the question of whether ownership arrangements can ensure self enforcement of the high-powered contract ($@^0; −^n$). Under this contract, for the production period, the manager is promised a payment of $@^0 y(s^e; G^e) + (−^n w_1)$ while the HQ is to get $(1 − @^0) y(s^e; G^e) − (−^n w_1)$.25

(A1) Suppose that the manager owns the unit's physical assets.25 In this case, the manager's outside option is to provide generic goods and services without access to the company goodwill ($y(s^e; 0)$) or to work for another company and get her reservation wage ($−^n w_0$).26 On the other hand, the HQ's outside option is $y(0; G^e) + (−^n w_0)$ (where the

---

24 The payment has to be a fixed amount, as the revenue is not verifiable yet.
25 It can be checked that the cost of asset ownership is unimportant to the following analysis and is thus assumed to be zero.
26 For the clarity of argument, we assume that there is no uncertainty about the revenue, i.e., $\gamma = 0$, and restrict the discussion to linear incentive contracts. Note that in Section 3, uncertainty
HQ pays $w_0$ to hire a new manager for the production stage) as it will lose access to the effort-embedded physical asset.

**Lemma 6** Suppose that the manager owns the physical assets. The H contract is self-enforcing if conditions

$$\max_s y(s; 0) \circ c(s) + w_1 \circ \delta y(s^n; G^n) \circ c(s^n) + \omega = w_0; \quad (6)$$

$$\omega w_0 + w_1 < \circ \delta y(s^n; G^n) \circ c(s^n) + \omega = w_0; \quad (7)$$

$$\max g \delta \pi y(T; g; pg) + (1 - p) y(0; pg) g$$

$py(T; g^n; G^n) + (1 - p) [y(s^n; G^n) \circ c(s^n)] + (1 - p) (w_1 + \delta w_0; 0): \quad (8)$$

are met.

(6) implies that the manager can not benefit from leaving to work for herself with her asset at $t=2$ even if she chooses $s$ optimally for this purpose. (7) means that neither can the manager benefit from leaving to work for other employers at $t=2$. (8) means that the HQ can not benefit from kicking out H managers even if it directs the L managers to choose the optimal $g$ for this purpose. Together, the three conditions ensure that the second-best $s^n$ and $G^n$ will be chosen and renegotiation will not occur.

(6), (7) and (8) are implied by strong complementarity between $s$ and $G$, and high efficiency of the production technology. To parameterize complementarity and efficiency, we consider the following class of revenue functions:

$$y(s; G) = k z(s; G) + k_1 (s) + k_2 (G);$$

where $z(0; G) = z(s; 0) = 1(0) = 0$, $\frac{\partial z}{\partial G} > 0$, $z$, $1$ and $2$ are increasing and concave. $z(s; G)$ captures the complementarity between $s$ and $G$, and thus $k$ parameterizes the strength of the complementarity. $k$ also parameterizes the efficiency of the production technology. We can show:

**Lemma 7** Let $k_1 = k_2 = 0$. Then for sufficiently large $k$, there exists some $w_1$ such that (6)-(8) hold with strict inequality.

**Lemma 8** Suppose for some $k$ and $w_1$, (6)-(8) hold with strict inequality as $k_1 = k_2 = 0$. Then (6)-(8) also hold for sufficiently small $k_1$ and $k_2$.

**Corollary 2** For sufficiently large $k$ and sufficiently small $k_1$ and $k_2$, there exists some $w_1$ such that (6)-(8) are satisfied.

plays no essential role other than rationalizing linear incentive contracts if we assume that the HQ cannot take a negative share of any unit's revenue and thus the shares of any unit's revenue going to the managers must total no greater than one. All the results in Section 3 except Proposition 6 still hold. The discussion in Subsection 3.6 can also be modified so that it does not depend on uncertainty.
Suppose instead that the HQ owns the unit’s physical assets. In this case, the HQ can deny the manager access to the company goodwill and the effort-embedded physical assets. The manager has the outside option of working for another company and getting her reservation wage ($\bar{w}_0$), while the HQ has the outside option of hiring a new manager and capturing all the revenue ($y(s^n;G^n) i \bar{w}_0$).

A necessary condition for the contract to be self-enforcing is that, when $(s^n;G^n)$ is chosen, neither party wants to renegotiate. By Proposition 8, this is equivalent to:

$$\bar{w}_0 \leq y(s^n;G^n) + (s^n;G^n) i \bar{w}_0;$$
$$y(s^n;G^n) i \bar{w}_0 = y(s^n;G^n) i \bar{w}_0;$$

These inequalities imply that $w_1 = \bar{w}_0 + y(s^n;G^n) i \bar{w}_0$. Given such $w_1$, however, the manager will deviate from $s^n$. By choosing $s^0 = T$, the manager gets $w_1$ before the realization of the revenue and $\bar{w}_0$ after the renegotiation, and her total payoffs is $w_1 + \bar{w}_0 i c(T) = \bar{w}_0 + c(s^n)$, which is higher than her payoff of $w_1$ by choosing $s^n$. Therefore, the H contract is not self-enforcing when the HQ owns the physical assets. Combining (A1) and (A2), we have:

**Proposition 9** For sufficiently large $k$ and sufficiently small $k_1$ and $k_2$, the high-powered incentive contract ($\bar{w}_0; s^n;G^n$) is self-enforcing ex post if and only if the manager owns the unit’s physical assets.

In other words, when $s$ and $G$ are strongly complementary and the production technology is very efficient, the necessary and sufficient condition for the high-powered contract ($\bar{w}_0; s^n;G^n$) to be self-enforcing is manager ownership of the unit’s physical assets.

(B) Next we turn to the question of whether ownership arrangements can ensure self enforcement of the low-powered contract ($w^n = \bar{w}_0$). Under this contract, the production period payoffs are $w_1$ for the manager and $y(s^n;G^n) i \bar{w}_0 + w_1$ for the HQ.

(B1) Suppose that the HQ owns the physical assets. As in the case of (A2), the manager and the HQ have, respectively, outside options of $\bar{w}_0$ and $y(s^n;G^n) i \bar{w}_0$. By Proposition 8, the contract is not renegotiated if and only if

$$w_1 = \bar{w}_0 + y(s^n;G^n) i \bar{w}_0;$$

These inequalities imply that $w_1 = (1 i \bar{w})w_0$. Note that this condition does not depend on $(s^n;G^n)$. In particular, it ensures $f s^n;G^n$; no renegotiation as the equilibrium. Thus, the L contract is self-enforcing if the HQ owns the physical assets.

(B2) Suppose instead that the manager owns the physical assets. As in the case of (A1), the manager has the outside option of $\max f \bar{w}_0; y(s^n;0); g$ while the HQ has $y(0;G^n) i$.
For \( f = T \mid g^n; g' = g^n \); no renegotiation to be a subgame perfect equilibrium, by Proposition 8, the following conditions have to be satisfied:

\[
y(T \mid g^n; 0) \quad w_0 \quad w_1; \quad (9)
\]

\[
y(0; G^n) \quad w_0 \quad y(T \mid g^n; G^n) \quad w_0 + w_1; \quad (10)
\]

In addition, \( w_1 \) has to satisfy

\[
w_1 + \max_{s} y(s; 0) \quad c(s)g \quad w_0; \quad (12)
\]

Otherwise, the manager could benefit from deviation by choosing the sales effort that maximizes \( y(s; 0) \quad c(s)g \quad w_0 \). It is easy to see that (12) implies (9). Therefore, (10)-(12) are necessary conditions for \( f = T \mid g^n; g' = g^n \); no renegotiation to be a subgame perfect equilibrium. We can show that they are also sufficient.

Lemma 9 \( f = T \mid g^n; g' = g^n \); no renegotiation is a subgame perfect equilibrium if and only if there exists some \( w_1 \) satisfying (10)-(12).

However, \( f = T \mid g^n; g' = g^n \); no renegotiation is not the only subgame perfect equilibrium. There are other equilibria that are more likely to be selected. We know the second-best \( g^n \) is chosen to maximize \( \frac{1}{2} = p[y(T \mid g; pg) \quad w] + (1 - p)[(1 - p) y(s; pg) \quad w] \); Let \( g^0 \) be the goodwill effort that maximizes \( y(T \mid g; pg) \). It can be shown that \( g^0 < g^n \) and \( y(T \mid g^0, pg^0) > y(T \mid g^n; pg^n) \). These inequalities imply that (10)-(12) still hold when \( g^n \) is replaced by \( g^0 \). Similar to Lemma 9, we have:

Lemma 10 If there exists some \( w_1 \) satisfying (10)-(12), then \( f = T \mid g^0; g^0 \); no renegotiation is a subgame perfect equilibrium.

It remains to be argued that \( E^0 = f = T \mid g^0; g^0 \); no renegotiation is more likely to be selected than \( E^n = f = T \mid g^n; g^n \); no renegotiation. \( E^0 \) and \( E^n \) have the same equilibrium payoffs. However, compared to \( E^n \), \( E^0 \) gives the manager a higher outside option payoff; yields higher surplus for the unit, and gives the HQ the same outside option payoff. Therefore, \( E^0 \) gives the manager higher out-of-equilibrium payoff than \( E^n \). Note that in the game between the L manager and the HQ, the manager moves first by choosing \( s \) and \( g \) before any possible renegotiation. If the manager is even slightly concerned about possible uncertainty in the payoff, the game form, or the execution of the strategies, she will choose \( E^0 \) rather than \( E^n \). In this sense, \( E^0 \) is more likely to be the outcome of the game. In \( E^0 \), however, the second-best effort levels are not implemented.

Combining (B1) and (B2), we have:

Proposition 10 The low-powered incentive contract is self-enforcing ex post if and only if the HQ owns the unit's physical assets.
Propositions 9 and 10 are established under the assumption that the HQ owns the brand name in which goodwill is embedded. This is in fact an optimal arrangement. Following the logic of the above analysis, we can show that managers with the low-powered incentive contract should not own any assets, including the brand name. If managers with the high-powered incentive contract have some claim over the ownership of the brand name, they will want to renegotiate the low-powered incentive contract, because they are not given any of L units' revenue under the contract. Therefore, the HQ should be the sole owner of the brand name.

It is useful to compare self enforcement of high-powered and low-powered incentive contracts with that of performance pay and efficiency wage contracts (MacLeod and Malcomson (1996)). In their model, as revenue is unverifiable, performance contracts may not be self-enforcing. In our model, the high-powered contracts may not be self-enforcing, because contracts are incomplete about goodwill. Low-powered contracts, on the other hand, are similar to efficiency wage contracts, as neither is contingent on revenue or profit. As shown by MacLeod and Malcomson (1996), either performance pay contracts or efficiency wage contracts are not self-enforcing depending on market conditions, and their relative optimality follows accordingly. In this paper, contract mix is optimal and multiple ownership arrangements are required to ensure self enforcement of both high-powered and low-powered contracts.

4.4. Contractual remedies versus ownership arrangement

One may well ask the following question: can contractual remedies mimic the ownership arrangement to ensure self enforcement of the high-powered contract? Specifically, while the HQ owns both the unit's physical assets and company goodwill, it could write an ex ante contract that stipulates a payment (denoted by $M$) from the HQ to the manager once the high-powered contract is not enforced.\(^{27}\) Note that the actual sales revenue is no longer verifiable when the outside option is taken. This is because the HQ would hire another manager on a fixed-wage contract to finalize the production, and it is impossible for the court to verify the actual revenue without the help from the HQ or the new manager. Thus, the HQ's payment to the manager can only be a fixed payment depending on the expected sales revenue.

There are two conflicting concerns when choosing $M$. First, the manager should be given incentive to put in sales effort. Second, the HQ should ex post prefer enforcement of the high-powered contract. Specifically, the manager has the option of not putting in any sales effort but still receiving a fixed payment $M$ from the HQ. To provide the manager the effort incentive, $M < \check{\gamma}(s^n; G^n) - c(s^n)$ is required.\(^{28}\) That, however, implies that the HQ

\(^{27}\)The low-powered contract is self-enforcing so long as there is no contractual remedy at all.

\(^{28}\)The timing for the lump-sum payment \(\bar{\pi}\) is unimportant to the main results of this subsection. For simplicity of notations, it is assumed that all of \(\bar{\pi}\) is paid before the renegotiation stage. The value of the reservation wage does not affect the argument either and thus is again assumed to be 0.
gets more from the outside option than from the high-powered contract \( y(s^a; G^a) > (1 - \delta) y(s^a; G^a) \), and the high-powered contract would be renegotiated. Underlying the above argument is an important feature of the contractual remedies, namely, there is no automatic loss of surplus when the outside option is taken. In contrast, under the optimal ownership arrangement for the high-powered contract, there is a loss of surplus upon the outside option (namely, \( y(s^a; 0) + y(0; G^a) < y(s^a; G^a) \)), which is necessary to ensure self enforcement of the high-powered contract (Proposition 9).

One may further propose the following contractual remedies when the outside option is taken: the HQ pays \( M^a \) to the manager and also makes a large enough donation (\( D^a \)) to a third party such that the HQ prefers enforcement of the high-powered contract (i.e., \( y(s^a; G^a) > M^a + D^a < (1 - \delta) y(s^a; G^a) \)). However, under some reasonable circumstances, the proposed contractual remedies are inferior to the optimal ownership arrangement.

Without losing generality, suppose that, after the manager makes the sales and goodwill efforts, she may have to quit the business for some benign (for example, family) reasons with certain probability. Interestingly, this uncertainty does not present any problem for the ownership arrangement of the high-powered contract. In case of friendly separation, the manager could sell her asset to a third party and get her expected payoff \( y(s^a; G^a) \). In case of unfriendly separation, the manager gets \( y(s^a; 0) \) and the HQ has \( y(0; G^a) \), which prevents renegotiation of the high-powered contract and ensures optimal ex ante incentive for both parties.

Now, we consider contractual remedies in the presence of possible friendly separation. Again, payments in the contract have to be exed. One reason is that revenue also becomes unverifiable under friendly separation, for a new manager will be hired by the company and it is impossible for the court to verify the actual revenue without the help from the HQ or the new manager. A more important reason is that the incumbent manager will not have as much control over the hiring of the new manager when she does not own any assets as the control she has over the choice of the buyer of her assets when she owns them. In particular, she will not be given the rights of choosing the new manager and dictating the contract with the new manager. Only with these rights can she get \( \delta y(s^a; G^a) \) through side payment by the new manager to her.

The contract should include the following payments: under unfriendly separation, \( M^a \) to the manager and \( D^a \) to a third party; under friendly separation, \( M^a \) to the manager. These payments should be chosen so that (1) neither party would initiate the unfriendly separation, and (2) friendly separation is allowed to occur when there are good reasons for the manager to initiate it. (1) implies that payments (\( M^a; D^a \)) would not be invoked. However, (2) implies that the exed payment \( M^a \) would be invoked with a positive probability. Note that,
whenever the manager is expected to get fixed payoffs (in the event of friendly separation) with positive probability, the ex ante effort incentive will be adversely affected. Thus, there is a tension between adequate protection in case of friendly separation and proper ex ante incentive. In contrast, the ownership arrangement of the high-powered contract provides the manager with payoffs that are contingent upon both the manager's effort and the nature of the separation.

In summary, given there is severe contractual incompleteness in franchising, the incentive contracts of various power can only be voluntarily enforced in the presence of the corresponding ownership arrangements of the units' physical assets.

5. Conclusion

The contract mix and multiple ownership structure in a franchise both challenge the recent developments in the theory of the firm. With the observation that system-wide goodwill and unit-specific sales activity are crucial to a franchise company, we construct a multi-task model in which one task has the feature of the public good and the other has that of the private good. We show that, when the two tasks are complementary, the principal should offer a fixed-wage contract to some agents and a revenue-sharing contract to the remaining agents. In addition, by incorporating the stylized feature of contractual incompleteness in a franchise and possible ex post unenforceability of ex ante incentive contracts, we show that the ex ante incentive contracts of various power can be made self-enforcing only by the corresponding ownership arrangements.

This paper thus provides the first theory that explains both contract mix and multiple ownership structure in the franchise. More importantly, it adopts and extends important features from both the multi-task theory and the incomplete-contract theory of the firm. On the one hand, by incorporating the task of the public-good nature, it makes it possible for the multi-task model to explain the optimality of contract mix for ex ante homogeneous agents. On the other hand, it considers ex ante revenue-sharing contracts in settings of contractual incompleteness and explores other roles of ownership structures. In particular, the optimality of the contract mix in the presence of a multi-task framework implies multiple ownership arrangements of complementary assets.
References


Appendix

Proof of Proposition 1: The HQ should request the same level of goodwill effort from all managers of L units.

Let \( f(g(j))g_{2L} \) be a profile of goodwill effort levels and \( g^* \) denote the average of \( f(g(j))g_{2L} \). Since \( y(s;G) \) is concave in \( s \), \( y(T_i;g;G) \) is concave in \( g \). Then by Jensen's Inequality,

\[
\sum_{j \in L} y(T_i;g(j);G) g(j) \geq \sum_{j \in L} y(T_i;g;G) g^*
\]

Therefore, the solution to program (\( OP_{G_0} \)) is to choose \( g(j) \) to be a constant. That is, The HQ should request the same level of goodwill effort from all managers of L units.

Proof of Lemma 1: Program (\( OP_H \)) is equivalent to

\[
\max \sum \left[ y(T_i;g;G) + \sum_{j \in L} y(s(i);G) g(s(i)) \right] \quad (OP_H)
\]

subject to

\[
\sum y(s(i);G) g(s(i)) = 0 \quad (IC)
\]

Let us consider program (\( OP_H \)). Assumptions 1 and 3 say that \( y(s;G) \) is concave in \( s \) and \( \lim_{s \to 0} y(s;G) = 1 \). Therefore, incentive compatibility constraint (\( OP_{s} \)) can be replaced by

\[
\hat{g}(i)y_s(s(i);G) = c(q(s(i)))
\]

By Proposition 1, incentive compatibility constraint (\( OP_{G} \)) becomes

\[
g = \arg \max \left\{ \sum y(T_i;g;G) \right\} \quad (FOC)
\]

where, \( G = pg \). It is easy to show that, since \( y(s;G) \) is concave in \( (s;G) \),

\[
\sum y(T_i;g;G) \geq \sum y(T_i;g;G) g^*
\]

is concave in \( G \). Its derivative with respect to \( G \) is

\[
\frac{\partial}{\partial G} \sum y(T_i;g;G) = \sum (1 + \hat{g}(i)) y(s(i);G) \quad (IC)
\]

which decreases with \( G \), by Assumption 3, goes to 1 as \( G \to 0 \), and goes to \( -1 \) as \( G \to pT \). Therefore, (\( OP_{G} \)) can be replaced by

\[
\sum y(T_i;g;G) = 0 \quad (F OC)
\]
The objective function of program \((\text{OP}_i \ H \ Q^0)\) is now

\[
py(T \mid g; G) + \int \sum_{i \in L} \left[ y(s(i); G) \cdot c(s(i)) \cdot \frac{1}{2} r \frac{d^2}{(i)^2} \right] \mathrm{d}i;
\]

which is also concave in \(G\) and the derivative of which with respect to \(G\) is positive for \(G\) satisfying constraint \((\text{FOC}_i \ G)\). Therefore, program \((\text{OP}_i \ H \ Q^0)\) can be rewritten as

\[
\max \quad py(T \mid g; G) + \int \sum_{i \in L} \left[ y(s(i); G) \cdot c(s(i)) \cdot \frac{1}{2} r \frac{d^2}{(i)^2} \right] \mathrm{d}i \\
\text{s.t.} \quad py(G(T \mid g; G) \cdot y(s(T \mid g; G)) + \int \sum_{i \in L} (1 \cdot c(i)) y(s(i); G) \mathrm{d}i, \quad 0 \quad (\text{IC}_i \ G) \\
\end{array}
\]

When we change the equality sign in \((\text{FOC}_i \ G)\) to \(\leq\) in \((\text{IC}_i \ G)\), we expand the feasible region of program \((\text{OP}_i \ H \ Q^0)\) to the left along the \(G\)-direction, as the left hand side of \((\text{FOC}_i \ G)\) decreases with \(G\). This does not change the optimum because the objective function of \((\text{OP}_i \ H \ Q^0)\) increases with \(G\) in the expanded feasible region. \(\blacksquare\)

Proof of Lemma 2: Let \(c(i) = c(s) \cdot y(s; G)\). Then, given \(G\), the integrand in the objective function of program \((\text{OP}_i \ H \ Q^0)\),

\[
y(s(i); G) \cdot c(s(i)) \cdot \frac{1}{2} r \frac{d^2}{(i)^2};
\]

and the integrand in constraint \((\text{IC}_i \ G)\),

\[
(1 \cdot c(i)) y(s(i); G);
\]

are both concave functions of \(s(i)\).

Let \(\hat{A}(s; G) \cdot c(s) = y(s; G)\). Then \((\text{IC}_i \ s)\) implies \(c(i) = \hat{A}(s(i); G)\), which by Assumption 4 is convex in \(s(i)\). Substitute \(c(i) = \hat{A}(s(i); G)\) into the objective function and constraint \((\text{IC}_i \ G)\). Then the integrand in the objective function,

\[
y(s(i); G) \cdot c(s(i)) \cdot \frac{1}{2} r \frac{d^2}{(i)^2};
\]

becomes a concave function of \(s(i)\). The integrand in constraint \((\text{IC}_i \ G)\),

\[
(1 \cdot c(i)) y(s(i); G);
\]

is also concave in \(s(i)\) in the convex range \(f(s) : c(s) = y(s; G)\) \(\leq 1\)g, because \((1 \cdot c(i))\) is non-negative, concave and decreasing in \(s(i)\), and \(y(s(i); G)\) is, by Assumption 5, positive, concave and increasing in \(s(i)\); the product of two non-negative concave functions is concave if one of them is increasing and the other decreasing. \(\blacksquare\)

Proof of Proposition 2: The HQ should offer the same high-powered contract to all managers of \(H\) units.
Given a profile of sales effort levels, \( f(s(i))g_{2i} \), let \( s = \int_{i=1}^{R} s(i)di = (1_i \ p) \), the average of \( f(s(i))g_{2i} \). Then, for any given \( G \), Jensen’s inequality implies

\[
Z \int_{i=1}^{R} [y(s(i); G) i c(s(i))] \frac{1}{2} r^{Tf(i)^2} di Z \int_{i=1}^{R} y(s; G) i c(s) i \frac{1}{2} r^{Tf(i)^2} di;
\]

and

\[
py_G(T \ i \ \frac{G}{p} \ G) i y_s(T \ i \ \frac{G}{p} \ G) + R \ i=1 (1 \ i \ (i) \ y_G(s(i); G)) di
\]

\[
p y_G(T \ i \ \frac{G}{p} \ G) i y_s(T \ i \ \frac{G}{p} \ G) + R \ i=1 (1 \ i \ (i) \ y_G(s; G)) di;
\]

where \( i = A(s; G) \). Therefore, choosing the same \( i \) and \( s\) for all managers of \( H \) units is better than choosing different ones. That is, the HQ should offer the same high-powered contract to all managers of \( H \) units. ■

Proof of Lemma 4: \( s \) and \( G \) are continuous functions of \( (i) \ p \) on \([0; 1]^2\).

By Lemma 3, we only need to show continuity (1) at \( i = 0 \) and (2) at \( p = 0 \). (1) We first prove that \( \lim_{(i) \ p} (i) \ p) s(i) = T \), for all \( p \). By (F OC i),

\[
(i) y_s(s(i) ; G) = c(s(i) ; G);
\]

Therefore,

\[
0 \ c(s(i) ; G) i c(T) = (i) y_s(s(i) ; G) (i) y_s(T ; T) ! 0
\]

as \( i \) ! 0. The last inequality holds because \( s(i) ; G , T , G , T \), and \( y_s(s; G) \) increases with \( G \) but decreases with \( s \). Since \( c(i) > 0 \) as \( t > T \), \( (c(i))^{1} \) is continuous in \([0; 1] \) with \( (c(i))^{1}(0) = T \). Therefore, \( c(s(i) ; G) i c(T) ! 0 \) implies \( \lim_{(i) \ p} (i) \ p) s(i) = T \). The definition of \( s(0; p) \) implies that \( s(0; p) = T \). Therefore, \( s \) is continuous at \( i = 0 \).

When \( p > 0 \),

\[
(i) = py_G(T \ i \ \frac{G}{p} \ G) i 2 y_G(T \ i \ \frac{G}{p} \ G) + (1 \ i \ p)(1 \ i \ (i)) y_G(T \ i \ \frac{G}{p} \ G) < 0
\]

by (F OC i) and the concavity of \( y \), where a function with a superscript \( H \) (\( L \), resp.) means that it is evaluated at \((s; G) ((T \ i \ \frac{G}{p} ; G) \), resp.). Therefore (F OC i) implies \( G \) is a differentiable function of \( (s; i) \ p \) when \( p > 0 \), by the Implicit Function Theorem. Since we have shown that \( s \) is continuous at \( i = 0 \), so is \( G \).

When \( p = 0 \),

\[
(G(i) \ p) i G(0; 0) = pg ! 0;
\]

Note that the above argument also showed the continuity of \( s \) and \( G \) at \((i) \ p) = (0; 0)\). (2) First, \( G \) is continuous at \( p = 0 \) because \( G(i) 0 = 0 \) for all \( i \) and

\[
G(i) = pg(i) \ pT ! 0 \text{ as } p ! 0; \text{ for all } i;
\]

\( s(i) \) is defined by

\[
(i) y_s(s(i) ; G) i c(s(i) ; G) = 0;
\]

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At ($\theta^a; 0; p = 0$),
\[ \partial I_\theta(s(\theta^a; 0); 0) j \cdot c^q(s(\theta^a; 0)) = 0: \]

If $y_\theta(T; 0) \neq 0$, then $s(\theta^a; 0) > T$ and thus $\partial^2 y_\theta(s(\theta^a; 0); 0) j \cdot c^q(s(\theta^a; 0)) < 0$. By the Implicit Function Theorem, $s$ is a continuous function of $(\theta; G)$ at $(\theta^a; 0; p = 0)$. Since we have shown that $G$ is continuous at $p = 0$, $s$ is also continuous at $p = 0$.

If $y_\theta(T; 0) = 0$, then $s(\theta^a; 0) = T$ for all $\theta^a$.

\[ j c^q(s(\theta; p)) j \cdot c^q(T) j = \partial y_\theta(s(\theta; p); G(\theta; p)) \cdot \partial y_\theta(T; G(\theta; p)) \neq 0 \text{ as } p \neq 0: \]

Since $(c^q)^q$ is continuous in $[0; 1)$ with $(c^q)^q(0) = T$, $s(\theta; p) = T$ as $(\theta; p) \rightarrow (\theta^a, 0)$, i.e., $s$ is continuous at $p = 0$. ■

Proof of Proposition 3: For any $p \in [0; 1)$, the optimal $\theta^2(0; 1)$.

When $p = 0$, $\theta$ is chosen to maximize

\[ \max \ y(s; 0) j \cdot c(s) j \cdot \frac{1}{2} r^{\frac{3}{2}} \theta^2 \]

subject to $\partial y_\theta(s(\theta; 0); 0) j \cdot c^q(s) = 0$.

Apply the implicit function theorem to the constraint. We have,

\[ \frac{ds}{d\theta} = \frac{y_s}{\partial(c^q(s) j \cdot y_{ss})} > 0 \text{ for } \theta > 0: \]

Then,

\[ \frac{d^2 r}{d\theta^2} = (y_s j \cdot c^q) \frac{ds}{d\theta} j \cdot r^{\frac{3}{2}} \theta^2 = (1 j \cdot \theta) y_s \frac{ds}{d\theta} j \cdot r^{\frac{3}{2}} \theta^2 = \frac{1}{\theta} c^q y^2 j \cdot r^{\frac{3}{2}} \theta^2: \]

Therefore, as $\theta \rightarrow 0$, $\frac{d^2 r}{d\theta^2} \rightarrow 1$, and at $\theta = 1$, $\frac{d^2 r}{d\theta^2} = r^{\frac{3}{2}} \theta^2 < 0$. Consequently, the optimal $\theta^2(0; 1)$.

Now consider $p \in (0; 1)$. At $\theta = 1$, (2) becomes

\[ \frac{di^0}{d\theta} = i (1 j \cdot p) r^{\frac{3}{2}} + (1 j \cdot p) y_H \frac{G}{d\theta}: \]

Apply the implicit function theorem to $(F O C j \cdot s)$ and $(F O C j \cdot G)$. We have, at $\theta = 1$,

\[ \frac{dG}{d\theta} = \frac{1}{j} (1 j \cdot p) y_H (y^H j \cdot c^q): \]

where, the Jacobian matrix

\[ J = \begin{bmatrix} \tilde{A} & c^q(s) \\ 0 & p y_G \end{bmatrix} 0 \quad 0 \quad \begin{bmatrix} \tilde{A} & \partial y_H^s \\ p y_G & 2 y_{ss} + \frac{1}{p} y_{ss} + (1 j \cdot p) \partial y_H^G \end{bmatrix} \]

![Image]

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has positive determinant. Therefore, at \( \hat{\alpha} = 1 \), \( \frac{dG}{d\hat{\alpha}} < 0 \), which implies that \( \frac{dG}{d\hat{\alpha}} < 0 \). Thus the optimal \( \hat{\alpha} \) is not 1.

As \( \hat{\alpha} \to 0 \),

\[
\frac{ds}{dG} = 2y^H_{SG} \left[ py^H_{GG} + \frac{1}{2} y^H_{SS} + (1 - p)py^H_{GG} \right] > 0;
\]

\[
\frac{dG}{d\hat{\alpha}} = \frac{1}{2} \left( (1 - p)py^H_{GG} + (1 - p)y^H_{GG} y^H_{S} \right) > 0;
\]

These imply that \( \lim_{\hat{\alpha} \to 0} \frac{d\hat{\alpha}}{dG} > 0 \). Therefore, the optimal \( \hat{\alpha} \) is not 0.

**Proof of Proposition 4:** For any given \( p \in (0, 1) \), \( \frac{d}{d\hat{\alpha}} < \frac{d}{d\hat{\alpha}} \) at the corresponding HQ’s optimal choice of \( \hat{\alpha} \), denoted by \( \hat{\alpha}^*(p) \).

By the definition of \( \hat{\alpha}^*(p) \),

\[
\left( \hat{\alpha}^*(p) \right) = y(T; g(\hat{\alpha}^*), pg(\hat{\alpha}^*))) \max_{g} y(T; g; pg); \]

Since \( y(s; G) \) increases with \( s \) and \( p < 1 \),

\[
\max_{g} y(T; g; pg) < \max_{g} py(T; g; pg) + (1 - p)y(T; pg) = \frac{d}{d\hat{\alpha}} = 0;
\]

By the definition of \( \hat{\alpha}^*(p) \),

\[
\frac{d\hat{\alpha}}{dp} = \left( \frac{d}{d\hat{\alpha}} \right) = \left( \frac{d}{d\hat{\alpha}} \right) + (1 - p)(1 - \hat{\alpha})y^H_{SS} \frac{g_{SS}}{g} + (1 - p)(1 - \hat{\alpha})y^H_{S} \frac{g_{S} g}{g} \];

(FOC \( i \ G \)) implies that,

\[
y_s(T; g, G) \left( 1 - p \right)(1 - \hat{\alpha})y_G(s; G); \]

Since \( s \), \( T \), and \( y_{SG} > 0 \),

\[
(1 - p)(1 - \hat{\alpha})y_G(s; G) \left( 1 - p \right)(1 - \hat{\alpha})y_G(T; G); \]

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the right hand side of which ! 1 because $G = pg \ pT$, and Assumption 3 says that 
\[
\lim_{G \to 0} y_G = 1.
\]
Therefore, $y_s(T; G; G) = 1$, which implies $g \leq T$. Then, by Assumption 6, the substitution effect in (3), $gy_s^T = 1$;
\[
\lim_{p! 0} gy_s^T = T \lim_{p! 0} y_s(T; g; G) = T \lim_{(s; G)! (0; 0)} y_s(s; G) = 1.
\]
In (3), $\frac{\partial}{\partial p}$ is bounded. Then to determine the sign of $\frac{\partial}{\partial p}$ as $p \to 0$, it is sufficient to show that $\frac{\partial}{\partial p} > 0$ and $\frac{\partial^2}{\partial p^2} > 0$ as $p \to 0$. By Lemma 3, it suffices to show that $\frac{\partial}{\partial p} > 0$. Substitute (FOC $i G$) into $\frac{\partial}{\partial p}$ and rearrange. Then
\[
(1 \cdot p) \frac{i}{\partial(G)} = y_G^i + (1 \cdot p)gy_{ss}^i \ i \ (1 \cdot p)gy_{ss}^i \ y_s^i; \quad (A1)
\]
in which only the last term is negative. By Assumption 6, $y_s$ is weakly convex. Then
\[
y_s(T; G) \leq y_s(T; g; G), \quad gy_{ss}(T; g; G);
\]
in which $y_s(T; g; G) = 1$. Therefore,
\[
gy_{ss} = i \ gy_{ss}(T; g; G) = 1;
\]
Rearranging (A1) yields
\[
(1 \cdot p) \frac{i}{\partial(G)} = y_G^i + (1 \cdot p)gy_{ss}^i \ i \ (1 \cdot p)gy_{ss}^i \ y_s^i, \quad y_G^i + (1 \cdot p)gy_{ss}^i \ i \ (1 \cdot p)gy_{ss}^i \ y_s(T; G) = 1;
\]
In summary, we have shown $\lim_{p! 0} \frac{i}{\partial(G)} > 0$ for $i < 1$.

Proof of Proposition 5: It is optimal for the company to have some $L$ units.

Corollary 1 says that the optimal $(\alpha, p)$ exists. Let it be $(\alpha^p; p^p)$. We wish to show that $p^p > 0$. Suppose instead that $p^p = 0$. By Proposition 4, $\alpha^p < 1$. By Lemma 5, 
\[
\lim_{p! 0} \alpha^p = (\alpha^p; p) > 0.
\]
Thus there exists some positive $p$ such that $\alpha(\alpha^p; p) > 1(\alpha^p; p^p)$. This is a contradiction. This completes the proof of the Proposition.

Proof of Proposition 6: It is more likely for the HQ to have $H$ units when the managers are less risk averse, or when the uncertainty about the revenue is smaller, or when marginal cost of effort is smaller.

We first consider the optimal choice of $\alpha$ and $s$ when only an infinitesimal proportion of units are given $H$ contracts, i.e., $p = 1$. In this case, (FOC $i G$) becomes
\[
y_G(T; G) \leq y_s(T; G; G) = 0;
\]
which implies that $G$ does not depend on $\hat{\beta}$. Therefore, $\hat{\beta}$ is chosen to

$$\frac{1}{4}t = \max_{y(s;G), c(s)} \quad Kc(s) + \frac{1}{2}r \hat{\beta}^2$$

subject to

$$y(s;G), c(s) \quad \hat{\beta} = 0$$ (I C)

where $K$ is a cost parameter.

The Lagrangian of the program that chooses the optimal $\hat{\beta}$ and $s$ is

$$L = y(s;G) + Kc(s) + \frac{1}{2}r \hat{\beta}^2 + \lambda \left[ \hat{\beta}y(s;G) - Kc(s) \right]$$

Differentiation yields

$$\frac{\partial L}{\partial \hat{\beta}} = r \hat{\beta} + \lambda y(s;G); \quad \frac{\partial L}{\partial s} = (1 - \hat{\beta})y(s;G) + \lambda \left[ \hat{\beta}y(s;G) - Kc(s) \right]$$

By the incentive compatibility constraint, $s \geq T > 0$. Therefore, $\frac{\partial L}{\partial s} = 0$. If $\hat{\beta} = 1$, then $\frac{\partial L}{\partial \hat{\beta}} = 0$ implies $\lambda = 0$, which in turn implies $\frac{\partial L}{\partial s} < 0$. This is a contradiction. If $\hat{\beta} = 0$, the incentive compatibility constraint implies that $s = T$. Therefore, $\frac{\partial L}{\partial \hat{\beta}} = y(s;G) > 0$. This is again a contradiction. Therefore, the optimal $\hat{\beta} \in (0; 1)$ and $\frac{\partial L}{\partial \hat{\beta}} = 0$, which implies that $\hat{\beta} > 0$ and the optimal $s > T$.

By the envelope theorem, we have, $\frac{d}{dp} \left|_{p=1} \right. = \frac{dy(T;G;G)}{dp} = y(T;G;G)$ and $\frac{d}{dp} \left|_{p=0} \right. = \frac{dy(G;G;G)}{dp} = 0$.

Since at $p = 1$, $\frac{d}{dp} \left|_{p=1} \right. = \frac{dy(T;G;G)}{dp} = y(T;G;G)$ and $\frac{d}{dp} \left|_{p=0} \right. = \frac{dy(G;G;G)}{dp} = 0$, the proposition follows from equation (3) and the above results.

Proof of Proposition 7: It is more likely for the HQ to have $H$ units when $T$ is smaller.

This proposition needs additional assumptions:

$$y(s;0) > 0 \quad \text{for} \quad s > 0 \quad \text{and} \quad \lim_{(s;G) \to (0,0)} G_y(s;G) = 0: \quad \text{(A2)}$$

Suppose the cost function is now $c = c(s + g; T)$ with $c$ being strictly increasing and convex. It suffices to show that $\frac{d}{dp} \left|_{p=1} \right. > 0$ for sufficiently small $T$. As $T \to 0$, $\frac{1}{4} = y(T;G;G)$ and $\frac{d}{dp} \left|_{p=1} \right. = y(T;G;G)$. By (FOC $G$), this is $G_y(T;i;G;G)$, which, by Assumption (A2), approaches 0 as both $G$ and $T$ go to 0.

$$\frac{1}{4}t = \max_{y(s;G), c(s)} \quad y(s;G) + Kc(s) + \frac{1}{2}r \hat{\beta}^2$$

subject to

$$y(s;G), c(s) \quad \hat{\beta} = 0$$

As $T \to 0$, $\frac{1}{4}t$ approaches,

$$\frac{1}{4}t(T = 0) = \max_{y(s;0), c(s)} \quad y(s;0) + Kc(s) + \frac{1}{2}r \hat{\beta}^2$$

subject to

$$y(s;0), c(s) \quad \hat{\beta} = 0$$

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which is independent of $T$ and greater than $y(0; 0)$. Therefore,

$$\lim_{T \to 0} \frac{d^{1/4}}{dp} j_{p=1} = y(0; 0) \quad \forall t (T = 0) < 0;$$

that is, $\frac{d^{1/4}}{dp} j_{p=1} < 0$ for sufficiently small $T$.

**Proof of Lemma 6:** Suppose that the manager owns the physical asset. The H contract is self-enforcing if conditions

$$\max_s f y(s; 0) - c(s) + w_1 \geq y(s; G^n) - c(s^n) + w_0; \quad (6)$$

$$\max_g f y(T; g, pg) + (1 - p)y(0; pg) g < w_0; \quad (7)$$

are met.

To make the ex ante contract $(@g; \sim)\text{-}n$ self-enforcing in the incomplete-contracting framework, we need to prove: (1) given that $(s^n; G^n)$ is chosen the contract is not renegotiated at $t = 2$, and (2) $(s^n; G^n)$ is an Nash equilibrium when the managers choose effort levels at $t = 1$ in anticipation of possible renegotiation of the contract. Note that part (1) is met under the following conditions:

$$@y(s^n; G^n) + (\sim_{i} w_1) = y(s^n; 0); \quad (A3)$$

$$@y(s^n; G^n) + (\sim_{i} w_1) = w_0; \quad (A4)$$

$$\max_p y(T; g, pg) + (1 - p)y(0; pg) g < w_0; \quad (A5)$$

It is easy to show that (A3), (A4) and (A5) are implied by (6), (7) and (8), respectively. Now we consider the investment stage to show that $(s^n; G^n)$ is an Nash equilibrium. We first consider the manager’s sales effort given the goodwill effort $G^n$.

1. If the manager chooses $s^n$, then renegotiation does not occur under (A3) - (A5). Her total payo is $@y(s^n; G^n) + (\sim_{i} w_1)$ due to the individual rationality constraint.

2. If the manager deviates by choosing $s^0$, then her total payo is $@y(s^0; G^n) + (\sim_{i} w_1)$ if $s^0$ does not lead to renegotiation.

---

As there is no contract renegotiation, the manager’s total payo is equal to $w_1$ from the HQ before the realization of the revenue plus $@y(s^n; G^n) + (\sim_{i} w_1)$ from the HQ after the realization minus her effort cost $c(s^n)$.
given the sales effort $G$. The HQ's pay off under deviation 2(c) is even lower than that under deviation 2(d) is not worthwhile. The manager will not take deviation 2(c) given the goodwill effort which is guaranteed by (8).

Note that, by the definition of $\hat{w}$, $\hat{w}$ if $\hat{w}$ (6) ensures that deviation 2(b) is not worthwhile. The manager will not take deviation 2(c) if $\hat{w}$ and $\hat{w}$ which is guaranteed by (7). Finally, deviation 2(d) is not worthwhile as $y(s^0; G^n) > y(0; G^n) + \hat{w}_0 y(s^n) + w_1$ does not lead to renegotiation. The HQ initiates renegotiation.

We next consider the HQ's effort choice given the sales effort $s^n$:

1. If the HQ chooses $G^n$, then renegotiation does not occur under (A3)-(A5). Its total pay off $p[y(T_i; g^n; G^n) + (1 - p)[(1 - \hat{p})y(s^n; G^n) i \hat{w}]]$ if $G$ does not lead to renegotiation.

2. If the HQ deviates by choosing $G = pg$, then its total pay off is

(a) $p[y(T_i g^n G^n; G^n) + (1 - p)[(1 - \hat{p})y(s^n; G^n) i \hat{w}]]$ if $G$ does not lead to renegotiation.

(b) $p[y(T_i g^n G^n; G^n) + (1 - p)[y(0; G^n) + \hat{w}_0 + w_1]$ if $y(0; G^n) + \hat{w}_0 > (1 - \hat{p})y(s^n; G^n) i \hat{w}$ (the HQ initiates renegotiation).

(c) $p[y(T_i g^n G^n; G^n) + (1 - p)y(s^n; G^n) i \max f y(s^n; 0); \hat{w}_0 + \hat{w}$ if $\max f y(s^n; 0); \hat{w}_0 > (1 - \hat{p})y(s^n; G^n) i \hat{w}$ (the manager initiates renegotiation).

To induce the HQ to make the second-best goodwill effort $G^n$, we need to ensure that, given the sales effort $s^n$, its pay off from choosing $G^n$ is higher than that from choosing $G^0$. Note that, by the definition of $G^n$ in Section 3, it is not worthwhile for the HQ to have deviation 2(a). The HQ's pay off under deviation 2(c) is even lower than that under deviation 2(a), which implies that deviation 2(c) is unprofitable either. Finally, deviation 2(b) is not worthwhile if $\max f y(T_i g^n; G^n) + (1 - p)[(1 - \hat{p})y(s^n; G^n) i \hat{w}]]$ if $\max f y(s^n; 0); \hat{w}_0 > (1 - \hat{p})y(s^n; G^n) + \hat{w}$ (the manager initiates renegotiation).

which is guaranteed by (8).
Proof of Lemma 7: Let \( k_1 = k_2 = 0 \). Then for sufficiently large \( k \), there exists some \( w_1 \) such that (6)-(8) hold with strict inequality.

With \( k_1 = k_2 = 0 \), (6)-(8) become:

\[
\begin{align*}
\max_{p;G} & \quad p(T_i; g; G) + (1_i \ p)[kz(s^n; G^n) + c(s^n)] + (1_i \ p)(w_1 + w_0) = w_1 - w_0; \\
\max_{g} & \quad pkz(T_i; g; G) + pkz(T_i; g^n; G^n) + (1_i \ p)[kz(s^n; G^n) + c(s^n)] + (1_i \ p)(w_1 + w_0).
\end{align*}
\]

Choose \( w_1 = (1_i \ p)w_0 \) for some \( w_0^2 > 0 \). Then the first two inequalities hold strictly. The third inequality, divided by \( k \), becomes:

\[
\begin{align*}
\max_{p;G} & \quad pz(T_i; g; G) + pz(T_i; g^n; G^n) + (1_i \ p) z(s^n; G^n) i \frac{c(s^n)}{k} \frac{1}{k} (1_i \ p)^2; \\
\max_{g} & \quad pkz(T_i; g; G) + pkz(T_i; g^n; G^n) + (1_i \ p)[kz(s^n; G^n) + c(s^n)] + (1_i \ p)(w_1 + w_0) = w_1 - w_0; \\
\end{align*}
\]

The left-hand-side of (8) is bounded from above by \( z(T_i; T) \). If we can show \( p(T_i; g^n; G^n) + (1_i \ p) z(s^n; G^n) i \frac{c(s^n)}{k} \frac{1}{k} (1_i \ p)^2 \) as \( k \to 1 \), then (8) holds for sufficiently large \( k \).

Consider the HQ’s optimization problem:

\[
\begin{align*}
\max_{p;G} & \quad \frac{1}{\kappa_0} = \frac{pz(T_i; g; G) + (1_i \ p) z(s; G) i \frac{c(s)}{k}}{\kappa_0} \\
\text{s.t.:} & \quad \@x z(s; G) i \frac{c(s)}{k} = 0 \\
& \quad p z(T_i; g; G) i z_1(T_i; G; G) + (1_i \ p)(1_i \ S) \@x z_G(s; G) = 0
\end{align*}
\]

Let us \( \kappa_0 \) p (0; 1) and \( \kappa_0 \) (0; 1). From (FOC i s) and (FOC i G), it is a standard exercise to show that \( \frac{dz}{dk} > 0 \) and \( \frac{dz}{dk} > 0 \). (The computation is similar to that of \( \frac{dz}{dk} \) in the proof of Proposition 3.) Then \( \@x z(s; G) i \frac{c(s)}{k} \) increases with \( k \), because its derivative with respect to \( k \) is, by the envelope theorem, \( \@x z_G \frac{dz}{dk} + \frac{dz}{dk} = \frac{dz}{dk} > 0 \). Furthermore, \( \lim_{k \to 1} s = 1 \). Otherwise, \( \lim_{k \to 1} s = s_1 < 1 \), and \( \@x z_1(s; G_1) = \lim_{k \to 1} \frac{c(s)}{k} = 0 \) by (FOC i s). This is a contradiction because \( z_G > 0 \). Therefore, \( z(s; G) \frac{dz}{dk} = (1_i \ S) \@x z(s; G) + \@x z(s; G) i \frac{c(s)}{k} \) as \( k \to 1 \). In summary, we have shown that when \( p \) and \( \@x \) are optimally chosen, \( \kappa_0 \) is even larger.

Proof of Lemma 8: Suppose for some \( k \) and \( w_1 \), (6)-(8) hold with strict inequality as \( k_1 = k_2 = 0 \). Then (6)-(8) also hold for sufficiently small \( k_1 \) and \( k_2 \).

The conclusion about (6) and (7) is very easy to see. The left-hand-side of (8) is \( \lambda(p; k_1; k_2) \) \( \max_{g} \) \( py(T_i; g; pg) + (1_i \ p)y(0; pg)g \). By the theorem of the maximum" (Berge (1963)), the optimal \( g \) is an upper semi-continuous function of \( (p; k_1; k_2) \) and thus \( \lambda(p; k_1; k_2) \) is continuous in \( (p; k_1; k_2) \). On the right-hand-side of (8),

\[
\begin{align*}
\max_{p;G} & \quad p(T_i; g^n; G^n) + (1_i \ p)[y(s^n; G^n) i \ c(s^n)] = \\
\text{s.t.:} & \quad \@x y(s; G) i \ c(s) = 0 \\
& \quad py(T_i; G; G) i y_1(T_i; G) + (1_i \ p)(1_i \ S) \@x y_G(s; G) = 0
\end{align*}
\]
To prove the inequality, we rst perform an exercise similar to Lemmas 1 and 2. Let \( \hat{\alpha}(s;G) \) \( c(s) = y(s;G) \). Then \((\text{FOC} \cap s) \) becomes \( \hat{\alpha}(s;G) \). By Assumption 4, \( \hat{\alpha} \) is convex in \( s \). Substitute \( \hat{\alpha}(s;G) \) into the objective function and constraint \((\text{FOC} \cap G) \) in \((\text{OP} \cap H \text{ Q3}) \). Then \((\text{OP} \cap H \text{ Q3}) \) becomes

\[
\begin{align*}
\text{max } & \quad py(T_i g_i G) + (1_i p)[y(s;G) i c(s) i \frac{1}{2} f^2 \hat{\alpha}(s;G)^2] \\
\text{s.t. } & \quad py_G(T_i g_i G)i y_s(T_i g_i G) + (1_i p)(1_i \hat{\alpha}(s;G))y_G(s;G) - 0 \\
\end{align*}
\]

The reason why we can change the equality in \((\text{FOC} \cap G) \) to inequality is the same as that offered in Lemma 1. Now, given \((p;G) \), \((\text{OP} \cap H \text{ Q4}) \) is a concave program that chooses the optimal \( s \). The solution \( s = s(p;G;k_1;k_2) \) is differentiable. Substitute the solution into the objective function. We have an unconstrained optimization problem

\[
\text{max } f(p;G;k_1;k_2);
\]

where \( f \) is differentiable. Again, by the \( \text{theorem of the maximum"} \), \((p;G) \) are upper continuous functions of \((k_1;k_2) \); that is

\[
S' f(p;G;k_1;k_2) : (p;G) = \text{argmax } f(p;G;k_1;k_2)g
\]

is a closed set.

Now, we are ready to prove (8) by contradiction. Denote the left (right)-hand side of (8) by \( \text{LHS} \ \text{(RHS)} \). Suppose there exists a sequence \((p_n;G_n;k_{1n};k_{2n}) \) \( 2 S \) such that \( \lim_{n \to 1} (p_n;G_n;k_{1n};k_{2n}) = (p_0;G_0;0;0) \) \( 2 S \), and \( \lim_{n \to 1} (\text{LHS} \cap \text{RHS}) = 0 \). Then,

\[
\lim_{n \to 1} \text{LHS} = p_0 y(T_i g_0;G_0) + (1_i p)[y(s_0;G_0) i c(s_0)] + (1_i p)(w_1 + g_{w_0} + w_0):
\]

Lemma 7 says that \( \lim_{n \to 1} \text{LHS} < \lim_{n \to 1} \text{RHS} \); i.e., (8) holds with strict inequality as \( k_1 = k_2 = 0 \). This is a contradiction. ■

Proof of Lemma 9: \( fT_i g^i;g^i \); no renegotiation is a subgame perfect equilibrium if and only if there exists some \( w_1 \) satisfying (10)-(12).

By (12), the manager will not choose \( s > T \) because such a costly action does not improve her payo®. (12) also implies that \( y(T;0) + w_0 \); \( w_1 \). Therefore, if the manager chooses \( s \); \( T \); her outside option payo® will not be greater than her payo® under the contract and hence she will not be in a position to initiate renegotiation. Given other L manager's choice of \( g = g^i \), (11) implies that the HQ will not want to renegotiate the contract either for \( s \); \( T \); \( g^i \). Therefore, the manager's payo®s are the same for all \( s \); \( 2 \); \( T \); \( g^i \). For \( s < T \); \( g^i \), the total surplus \( y(s;G^m) \) is smaller than that for \( s = T \); \( g^i \), and thus the manager cannot be better-o® than choosing \( s = T \); \( g^i \). ■

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32 The constraint that \( p \); \( 2 \); \([0;1]\) does not a®ect the argument and is thus omitted.