# Integral representation of renormalized self-intersection local times 

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#### Abstract

In this paper we apply Clark-Ocone formula to deduce an explicit integral representation for the renormalized self-intersection local time of the $d$-dimensional fractional Brownian motion with Hurst parameter $H \in(0,1)$. As a consequence, we derive the existence of some exponential moments for this random variable.


## 1 Introduction

The purpose of this paper is to apply Clark-Ocone's formula to the renormalized self-intersection local time of the $d$-dimensional fractional Brownian motion. As a consequence, we derive the existence of some exponential moments for this local time.

A well-known result in Itô's stochastic calculus asserts that any square integrable random variable in the filtration generated by a $d$-dimensional Brownian motion $W=\left\{W_{t}, t \geq 0\right\}$ can be expressed as the sum of its expectation plus the stochastic integral of a square integrable adapted process:

$$
F=E(F)+\sum_{i=1}^{d} \int_{0}^{\infty} u^{i}(t) d W_{t}^{i} .
$$

The process $u$ is determined by $F$, except on sets of measure zero. In this context, Clark-Ocone formula provides an explicit representation of $u$ in

[^0]terms of the derivative operator in the sense of Malliavin calculus. More precisely, if $F$ belongs to the Sobolev space $\mathbb{D}^{1,2}$, then $u^{i}(t)=E\left(D_{t}^{i} F \mid \mathcal{F}_{t}\right)$, where $D^{i}$ denotes the derivative with respect to the $i$ th component of the Brownian motion and $\left\{\mathcal{F}_{t}, t \geq 0\right\}$ is the filtration generated by the Brownian motion. Extensions of this formula have been developed by Üstünel in [17, and by Karatzas, Ocone and Li in [12]. Clark-Ocone formula has proved to be a useful tool in finding hedging portfolios in mathematical finance (see, for instance, [11]).

The fractional Brownian motion on $\mathbb{R}^{d}$ with Hurst parameter $H \in(0,1)$ is a $d$-dimensional Gaussian process $B^{H}=\left\{B_{t}^{H}, t \geq 0\right\}$ with zero mean and covariance function given by

$$
\begin{equation*}
E\left(B_{t}^{H, i} B_{s}^{H, j}\right)=\frac{\delta_{i j}}{2}\left(t^{2 H}+s^{2 H}-|t-s|^{2 H}\right), \tag{1.1}
\end{equation*}
$$

where $i, j=1, \ldots, d, s, t \geq 0$, and

$$
\delta_{i j}=\left\{\begin{array}{lll}
1 & \text { if } & i=j \\
0 & & i \neq j
\end{array}\right.
$$

is the Kronecker symbol. Assume $d \geq 2$. The self-intersection local time of $B^{H}$ is formally defined as

$$
L=\int_{0}^{T} \int_{0}^{t} \delta_{0}\left(B_{t}^{H}-B_{s}^{H}\right) d s
$$

where $\delta_{0}$ is the Dirac delta function. It measures the amount of time that the process spends intersecting itself on the time interval $[0, T]$. Rigorously, $L$ is defined as the limit in $L^{2}$, if it exists, of $L_{\varepsilon}=\int_{0}^{T} \int_{0}^{t} p_{\varepsilon}\left(B_{t}^{H}-B_{s}^{H}\right) d s d t$, as $\varepsilon$ tends to zero, where $p_{\varepsilon}$ denotes the heat kernel.

For $H=\frac{1}{2}$, the process $B^{H}$ is a classical Brownian motion and its selfintersection local time has been studied by many authors (see Albeverio et al. [1], Calais and Yor [4, He et al. 66, Hu [7, Imkeller et al. [10], Varadhan [18], Yor [20], and the references therein). In this case, if $d=2$, Varadhan [18] has proved that $L_{\varepsilon}$ does not converge in $L^{2}$, but it can be renormalized so that $L_{\varepsilon}-E\left(L_{\varepsilon}\right)$ converges in $L^{2}$ as $\varepsilon$ tends to zero to a random variable that we denote by $\widetilde{L}$. This result has been extended by Rosen 16 to the case $H \in\left(\frac{1}{2}, \frac{3}{4}\right)$ (still when $d=2$ ), and by Hu and Nualart in [9], where they have obtained the following complete result on the existence of the self-intersection local time of the fractional Brownian motion:
(i) The self-intersection local time $L$ exists if and only if $H d<1$.
(ii) If $H d \geq 1$, the renormalized self-intersection local time $\widetilde{L}$ exists if and only if $H d<\frac{3}{2}$.

An important question is the existence of moments and exponential moments for the (renormalized) self-intersection local time. Along this direction, Le Gall [13] proved that for the planar Brownian motion, there is a critical exponent $\lambda_{0}$, such that $E(\exp \lambda \widetilde{L})<\infty$ for all $\lambda<\lambda_{0}$, and $E(\exp \lambda \widetilde{L})=\infty$ if $\lambda>\lambda_{0}$. Using the theory of large deviations, Bass and Chen proved in [2] that the critical exponent $\lambda_{0}$ coincides with $A^{-4}$, where $A$ is the best constant in the Gagliardo-Nirenberg inequality.

Clark-Ocone formula seems to be a suitable tool to analyze the renormalized self-intersection local time, because in this formula we do not take into account the expectation of the random variable. The fractional Brownian motion can be expressed as the stochastic integral

$$
B_{t}^{H}=\int_{0}^{t} K_{H}(t, s) d W_{s}
$$

of a square integrable kernel $K_{H}(t, s)$ with respect to an underlying Brownian motion $W$. In this way the renormalized self-intersection local time $\widetilde{L}$ is a functional of the Brownian motion $W$, and we can obtain an explicit integral representation $\widetilde{L}$, in the general case $H d<\frac{3}{2}$. This formula allows us to obtain some exponential moments for the renormalized self-intersection local time, using the method of moments.

The paper is organized as follows. In Section 2 we present some preliminaries on Malliavin calculus and Clark-Ocone formula. Section 3 is devoted to derive estimates for the moments of the self-intersection local time in the case of a general $d$-dimensional Gaussian process, using the method of moments. In the case of the fractional Brownian motion, this provides the existence of exponential moments in the case $H d<1$. Section 4 contains the main result, which is the integral representation of the renormalized self-intersection local time of the fractional Brownian motion in the case $H<\min \left(\frac{3}{2 d}, \frac{2}{d+1}\right)$. As an application we show that $E\left(\exp |\widetilde{L}|^{p}\right)<\infty$ if $p<\frac{1}{2}\left[\left(\frac{1}{2}+H\right)\left(\frac{d}{2}-\frac{1}{4 H}\right)\right]^{-1}$. A crucial tool is the local nondeterminism property introduced by Berman in [3] and developed by many authors (see Xiao [19] and the references therein).

## 2 Preliminaries on Malliavin calculus and Clark-Ocone formula

We need some preliminaries on the Malliavin calculus for the $d$-dimensional Brownian motion $W=\left\{W_{t}, t \geq 0\right\}$. We refer to Malliavin [14] and Nualart [15] for a more detailed presentation of this theory.

We assume that $W$ is defined in a complete probability space $(\Omega, \mathcal{F}, P)$, and the $\sigma$-field $\mathcal{F}$ is generated by $W$. Let us denote by $H$ the Hilbert space $L^{2}\left(\mathbb{R}_{+} ; \mathbb{R}^{d}\right)$, and for any function $h \in H$ we set

$$
W(h)=\sum_{i=1}^{d} \int_{0}^{\infty} h^{i}(t) d W_{t}^{i} .
$$

Let $\mathcal{S}$ be the class of smooth and cylindrical random variables of the form

$$
F=f\left(W\left(h_{1}\right), \ldots, W\left(h_{n}\right)\right),
$$

where $n \geq 1, h_{1}, \ldots, h_{n} \in H$, and $f$ is an infinitely differentiable function such that together with all its partial derivatives has at most polynomial growth order. The derivative operator of the random variable $F$ is defined as

$$
D_{t}^{i} F=\sum_{j=1}^{n} \frac{\partial f}{\partial x_{j}}\left(W\left(h_{1}\right), \ldots, W\left(h_{n}\right)\right) h_{j}^{i}(t),
$$

where $i=1, \ldots, d$ and $t \geq 0$. In this way, we interpret $D F$ as a random variable with values in the Hilbert space $H$. The derivative is a closable operator on $L^{2}(\Omega)$ with values in $L^{2}(\Omega ; H)$. We denote by $\mathbb{D}^{1,2}$ the Hilbert spaced defined as the completion of $\mathcal{S}$ with respect to the scalar product

$$
\langle F, G\rangle_{1,2}=E(F G)+E\left(\sum_{i=1}^{d} \int_{0}^{\infty} D_{t}^{i} F D_{t}^{i} G d t\right) .
$$

The divergence operator $\delta$ is the adjoint of the derivative operator $D$. The operator $\delta$ is an unbounded operator from $L^{2}(\Omega ; H)$ into $L^{2}(\Omega)$, and is determined by the duality relationship

$$
E(\delta(u) F)=E\left(\langle u, D F\rangle_{H}\right),
$$

for any $u$ in the domain of $\delta$, and $F$ in $\mathbb{D}^{1,2}$. Gaveau and Trauber [5] proved that $\delta$ is an extension of the classical Itô integral in the sense that any $d$ dimensional square integrable adapted process belongs to the domain of $\delta$,
and $\delta(u)$ coincides with the Itô integral of $u$ :

$$
\delta(u)=\sum_{i=1}^{d} \int_{0}^{\infty} u^{i}(t) d W_{t}^{i}
$$

It is well-known that any random variable $F \in L^{2}(\Omega)$, possesses a stochastic integral representation of the form

$$
F=E(F)+\sum_{i=1}^{d} \int_{0}^{\infty} u^{i}(t) d W_{t}^{i}
$$

for some $d$-dimensional square integrable adapted process $u$. Clark-Ocone formula says that if $F \in \mathbb{D}^{1,2}$, then

$$
\begin{equation*}
F=E(F)+\sum_{i=1}^{d} \int_{0}^{\infty} E\left(D_{t}^{i} F \mid \mathcal{F}_{t}\right) d W_{t}^{i} \tag{2.1}
\end{equation*}
$$

## 3 Exponential integrability of the self-intersection local time

Suppose that $W=\left\{W_{t}, t \geq 0\right\}$ is a $d$-dimensional standard Brownian motion, defined in a complete probability space $(\Omega, \mathcal{F}, P)$. Suppose that $\mathcal{F}$ is generated by $W$. We denote by $\left\{\mathcal{F}_{t}, t \geq 0\right\}$ the filtration generated by $W$ and the sets of probability zero. Consider a $d$-dimensional Gaussian processs of the form

$$
\begin{equation*}
B_{t}=\int_{0}^{t} K(t, s) d W_{s}, \tag{3.1}
\end{equation*}
$$

where $K(t, s)$ is a measurable kernel satisfying $\int_{0}^{t} K(t, s)^{2} d s<\infty$ for all $t \geq 0$. We will assume that $K(t, s)=0$ if $s>t$.

Fix a time interval $[0, T]$. We will make use of the following property on the kernel $K(t, s)$ :
(H1) For any $s, t \in[0, T], s<t$ we have

$$
\begin{equation*}
\int_{s}^{t} K(t, \theta)^{2} d \theta \geq k_{1}(t-s)^{2 H} \tag{3.2}
\end{equation*}
$$

for some constants $k_{1}>0$, and $H \in(0,1)$.
Notice that $\operatorname{Var}\left(B_{t}^{i} \mid \mathcal{F}_{s}\right)=\int_{s}^{t} K(t, \theta)^{2} d \theta$, so condition (H1) is equivalent to say that $\operatorname{Var}\left(B_{t}^{i} \mid \mathcal{F}_{s}\right) \geq k_{1}(t-s)^{2 H}$, for each component $i=1, \ldots, d$. This property is satisfied, for instance, in the following two examples:

Example 1 Suppose that $K(t, s)=(t-s)^{H-\frac{1}{2}}$. Then, we have equality in (3.2) with $k_{1}=\frac{1}{2 H}$.

Example 2 Condition (H1) is satisfied by the kernel of the fractional Brownian motion, as a consequence of the local nondeterminism property (see (4.1) below).

We will denote by $C$ a generic constant depending on $T$, the dimension $d$, and the constants appearing in the hypothesis such as $H$ and $k_{1}$.

The self-intersection local time of the process $B$ in the time interval $[0, T]$, denoted by $L$, is defined as the limit in $L^{2}$ as $\varepsilon$ tends to zero of

$$
\begin{equation*}
L_{\varepsilon}=\int_{0}^{T} \int_{0}^{t} p_{\varepsilon}\left(B_{t}-B_{s}\right) d s \tag{3.3}
\end{equation*}
$$

where $p_{\varepsilon}$ denotes the heat kernel

$$
p_{\varepsilon}(x)=(2 \pi \varepsilon)^{-\frac{d}{2}} \exp \left(-\frac{|x|^{2}}{2 \varepsilon}\right)
$$

The next theorem asserts that $L$ exists if $H d<1$, and it has exponential moments of order $\frac{1}{H d}$.

Theorem 1 Suppose that $H d<1$. Then, the self-intersection local time $L$ exists as the limit in $L^{2}$ of $L_{\varepsilon}$, as $\varepsilon$ tends to zero, and for all integers $n \geq 1$ we have

$$
E\left(L^{n}\right) \leq C^{n}(n!)^{H d},
$$

for some constant C. As a consequence,

$$
E\left(e^{L^{p}}\right)<\infty,
$$

for any $p<\frac{1}{H d}$, and there exists a constant $\lambda_{0}>0$ such that $E\left(e^{\lambda L \frac{1}{H d}}\right)<\infty$ for all $\lambda<\lambda_{0}$.

Proof. From the equality

$$
p_{\varepsilon}(x)=\frac{1}{(2 \pi)^{d}} \int_{\mathbb{R}^{d}} \exp \left(i\langle\xi, x\rangle-\frac{\varepsilon|\xi|^{2}}{2}\right) d \xi
$$

and the definition of $L_{\varepsilon}$, we obtain

$$
L_{\varepsilon}=\frac{1}{(2 \pi)^{d}} \int_{0}^{T} \int_{0}^{t} \int_{\mathbb{R}^{d}} \exp \left(i\left\langle\xi, B_{t}-B_{s}\right\rangle-\frac{\varepsilon|\xi|^{2}}{2}\right) d \xi d s d t .
$$

This expression allows us to compute the moments of $L_{\varepsilon}$. Fix an integer $n \geq 1$. Denote by $T_{n}$ the set $\{0<s<t<T\}^{n}$. Then

$$
\begin{align*}
E\left(L_{\varepsilon}^{n}\right)= & \frac{1}{(2 \pi)^{n d}} \int_{T_{n}} \int_{\mathbb{R}^{n d}} E\left[\exp \left(i\left\langle\xi_{1}, B_{t_{1}}-B_{s_{1}}\right\rangle+\cdots+i\left\langle\xi_{n}, B_{t_{n}}-B_{s_{n}}\right\rangle\right)\right] \\
& \times \exp \left(-\frac{\varepsilon}{2} \sum_{j=1}^{n}\left|\xi_{j}\right|^{2}\right) d \xi_{1} \cdots d \xi_{n} d s d t \tag{3.4}
\end{align*}
$$

where $s=\left(s_{1}, \ldots, s_{n}\right)$ and $t=\left(t_{1}, \ldots, t_{n}\right)$. Notice that

$$
\begin{align*}
& \int_{\mathbb{R}^{n d}} E\left[\exp \left(i\left\langle\xi_{1}, B_{t_{1}}-B_{s_{1}}\right\rangle+\cdots+i\left\langle\xi_{n}, B_{t_{n}}-B_{s_{n}}\right\rangle\right)\right] \\
& \times e^{-\frac{\varepsilon}{2} \sum_{j=1}^{n}\left|\xi_{j}\right|^{2}} d \xi_{1} \cdots d \xi_{n} \\
= & \int_{\mathbb{R}^{n d}} \exp \left(-\frac{1}{2} E\left[\left(\left\langle\xi_{1}, B_{t_{1}}-B_{s_{1}}\right\rangle+\cdots+\left\langle\xi_{n}, B_{t_{n}}-B_{s_{n}}\right\rangle\right)^{2}\right]\right) \\
& \times e^{-\frac{\varepsilon}{2} \sum_{j=1}^{n}\left|\xi_{j}\right|^{2}} d \xi_{1} \cdots d \xi_{n} \\
= & \left(\int_{\mathbb{R}^{n}} \exp \left(-\frac{1}{2} \xi^{T} Q \xi\right) e^{-\frac{\varepsilon}{2}|\xi|^{2}} d \xi\right)^{d}, \tag{3.5}
\end{align*}
$$

where $Q$ is the covariance matrix of the $n$-dimensional random vector ( $B_{t_{1}}^{1}-$ $B_{s_{1}}^{1}, \ldots, B_{t_{n}}^{1}-B_{s_{n}}^{1}$ ). Substituting (3.5) into (3.4) yields

$$
E\left(L_{\varepsilon}^{n}\right)=\frac{1}{(2 \pi)^{n d}} \int_{T_{n}}\left(\int_{\mathbb{R}^{n}} \exp \left(-\frac{1}{2} \xi^{T} Q \xi\right) e^{-\frac{\varepsilon}{2}|\xi|^{2}} d \xi\right)^{d} d s d t
$$

and $E\left(L_{\varepsilon}^{n}\right)$ converges as $\varepsilon$ tends to zero to

$$
\begin{aligned}
\alpha_{n} & =\frac{1}{(2 \pi)^{n d}} \int_{T_{n}}\left(\int_{\mathbb{R}^{n}} \exp \left(-\frac{1}{2} \xi^{T} Q \xi\right) d \xi\right)^{d} d s d t \\
& =\frac{1}{(2 \pi)^{\frac{n d}{2}}} \int_{T_{n}}(\operatorname{det} Q)^{-\frac{d}{2}} d s d t,
\end{aligned}
$$

provided $\alpha_{n}$ is finite.
If $\alpha_{2}<\infty$, then in the same way as before we obtain

$$
\lim _{\varepsilon, \delta \downarrow 0} E\left(L_{\varepsilon} L_{\delta}\right)=\alpha_{2},
$$

which implies that $L_{\varepsilon}$ converges in $L^{2}$ as $\varepsilon$ tends to zero. Furthermore, if $\alpha_{n}$ is finite for all $n \geq 1$, then we deduce the convergence in $L^{p}$ for any $p \geq 2$
of $L_{\varepsilon}$ as $\varepsilon$ tends to zero. The limit, denoted by $L$, will be, by definition, the self-intersection local time of the process $B$ in the time interval $[0, T]$. To complete the proof of the theorem it suffices to show that $\alpha_{n}$ is bounded by $C^{n}(n!)^{H d}$, for some constant $C$.

We can write

$$
\alpha_{n}=\frac{n!}{(2 \pi)^{\frac{n d}{2}}} \int_{T_{n} \cap\left\{t_{1}<\cdots<t_{n}\right\}}(\operatorname{det} Q)^{-\frac{d}{2}} d s d t .
$$

For each $i=1, \ldots, n$ we denote by $\tau_{i}$ the point in the set $\left\{s_{i}, s_{i+1}, \ldots, s_{n}, t_{i-1}\right\}$ which is closer to $t_{i}$ from the left. Then, by (H1) and the fact that $s_{i}<t_{i}$, $i=1, \ldots, n$, we obtain, using Lemma 5 in the Appendix,

$$
\begin{aligned}
\operatorname{det} Q= & \operatorname{Var}\left(B_{t_{1}}^{1}-B_{s_{1}}^{1}\right) \operatorname{Var}\left(B_{t_{2}}^{1}-B_{s_{2}}^{1} \mid B_{t_{1}}^{1}-B_{s_{1}}^{1}\right) \\
& \times \cdots \times \operatorname{Var}\left(B_{t_{n}}^{1}-B_{s_{n}}^{1} \mid B_{t_{1}}^{1}-B_{s_{1}}^{1}, \ldots, B_{t_{n-1}}^{1}-B_{s_{n-1}}^{1}\right) \\
\geq & \operatorname{Var}\left(B_{t_{1}}^{1} \mid B_{s_{1}}^{1} \operatorname{Var}\left(B_{t_{2}}^{1} \mid B_{t_{1}}^{1}, B_{s_{1}}^{1}, B_{s_{2}}^{1}\right)\right. \\
& \times \cdots \times \operatorname{Var}\left(B_{t_{n}}^{1} \mid B_{t_{1}}^{1}, B_{s_{1}}^{1}, \ldots, B_{t_{n-1}}^{1}, B_{s_{n-1}}^{1}, B_{s_{n}}^{1}\right) \\
\geq & \operatorname{Var}\left(B_{t_{1}}^{1} \mid \mathcal{F}_{\tau_{1}}\right) \operatorname{Var}\left(B_{t_{2}}^{1} \mid \mathcal{F}_{\tau_{2}}\right) \cdots \operatorname{Var}\left(B_{t_{n}}^{1} \mid \mathcal{F}_{\tau_{n}}\right) \\
\geq & k_{1}^{n}\left(t_{1}-\tau_{1}\right)^{2 H}\left(t_{2}-\tau_{2}\right)^{2 H} \cdots\left(t_{n}-\tau_{n}\right)^{2 H} .
\end{aligned}
$$

As a consequence,

$$
\alpha_{n} \leq \frac{n!}{(2 \pi)^{\frac{n d}{2}}} k_{1}^{-\frac{n d}{2}} \int_{T_{n} \cap\left\{t_{1}<\cdots<t_{n}\right\}} \prod_{i=1}^{n}\left(t_{i}-\tau_{i}\right)^{-H d} d s d t
$$

If we fix the points $t_{1}<\cdots<t_{n}$, there are $3 \times 5 \times \cdots \times(2 n-1)=(2 n-1)!$ ! posible ways to place the points $s_{1}, \ldots, s_{n}$. In fact, $s_{1}$ must be in $\left(0, t_{1}\right)$. For $s_{2}$ we have three choices: $\left(0, s_{1}\right),\left(s_{1}, t_{1}\right)$ and $\left(t_{1}, t_{2}\right)$. By a recursive argument it is clear that we have $(2 i-1)$ possible choices for $s_{i}$, given $s_{1}, \ldots, s_{i-1}$. In this way, up to a set of measure zero, we can decompose the set $T_{n} \cap\left\{t_{1}<\cdots<t_{n}\right\}$ into the union of $(2 n-1)!$ ! disjoint subsets. The integral of $\prod_{i=1}^{n}\left(t_{i}-\tau_{i}\right)^{-H d}$ on each one of these subset can be expressed as

$$
\Phi_{\sigma}=\int_{\left\{0<z_{1}<\cdots<z_{2 n}<T\right\}} \prod_{i=1}^{n}\left(z_{\sigma(i)}-z_{\sigma(i)-1}\right)^{-H d} d z
$$

where $\sigma(1)<\cdots<\sigma(n)$ are $n$ elements in $\{1,2, \ldots, 2 n\}$, and $z=\left(z_{1}, \ldots, z_{2 n}\right)$. Making the change of variables $y_{i}=z_{i}-z_{i-1}, i=1, \ldots, 2 n$ (with the con-
vention $z_{0}=0$ ) we obtain

$$
\begin{aligned}
\Phi_{\sigma} & =\int_{\left\{0<y_{1}+\cdots+y_{2 n}<T\right\}} \prod_{i=1}^{n} y_{\sigma(i)}^{-H d} d y \leq \frac{T^{n}}{n!} \int_{\left\{0<y_{1}+\cdots+y_{n}<T\right\}} \prod_{i=1}^{n} y_{i}^{-H d} d y \\
& =\frac{1}{n!} T^{n(2-H d)+H d} \frac{\Gamma(1-H d)^{n-1}}{\Gamma(n(1-H d)+H d+1)}
\end{aligned}
$$

Therefore

$$
\begin{aligned}
\alpha_{n} & \leq \frac{k_{1}^{-\frac{n d}{2}}(2 n-1)!!T^{n(2-H d)+H d} \Gamma(1-H d)^{n-1}}{(2 \pi)^{\frac{n d}{2}} \Gamma(n(1-H d)+H d+1)} \\
& =C_{1} C_{2}^{n} \frac{(2 n-1)!!}{\Gamma(n(1-H d)+H d+1)},
\end{aligned}
$$

with $C_{1}=T^{H d} \Gamma(1-H d)^{-1}$, and $C_{2}=\frac{k_{1}^{-\frac{d}{2}} \Gamma(1-H d) T^{2-H d}}{(2 \pi)^{\frac{d}{2}}}$. Taking into account that $(2 n-1)!!\leq 2^{n-1} n!$, and that

$$
\Gamma(n(1-H d)+H d+1) \geq C^{n}(n!)^{1-H d}
$$

for some constant $C$, we obtain the desired estimate.
If $H d \geq 1$, the above result is no longer true. In that case the expectation of $L_{\varepsilon}$ blows up as $\varepsilon$ tends to zero. In fact, if we denote $\sigma^{2}(s, t)=\operatorname{Var}\left(B_{t}^{1}-\right.$ $\left.B_{s}^{1}\right)$, for $s<t$, then

$$
E\left(L_{\varepsilon}\right)=\int_{0}^{T} \int_{0}^{t} p_{\varepsilon+\sigma^{2}(s, t)}(0) d s d t=(2 \pi)^{-\frac{d}{2}} \int_{0}^{T} \int_{0}^{t}\left(\varepsilon+\sigma^{2}(s, t)\right)^{-\frac{d}{2}} d s d t
$$

which converges to

$$
(2 \pi)^{-\frac{d}{2}} \int_{0}^{T} \int_{0}^{t} \sigma^{2}(s, t)^{-\frac{d}{2}} d s d t \geq(2 \pi)^{-\frac{d}{2}} k_{1}^{-\frac{d}{2}} \int_{0}^{T} \int_{0}^{t}(t-s)^{-H d} d s d t=\infty
$$

In this case, one can study the existence of the renormalized self-intersection local time defined as the limit as $\varepsilon$ tends to zero of $L_{\varepsilon}-E\left(L_{\varepsilon}\right)$. In the next section we discuss the existence and exponential moments of the renormalized self-intersection local time, using Clark-Ocone formula, in the case of the fractional Brownian motion.

## 4 Renormalized self-intersection local time of the fBm

The fractional Brownian motion on $\mathbb{R}^{d}$ with Hurst parameter $H \in(0,1)$ is a $d$-dimensional Gaussian process $B^{H}=\left\{B_{t}^{H}, t \geq 0\right\}$ with zero mean and covariance function given by (1.1). We will assume that $d \geq 2$.

It is well-known that $B^{H}$ possesses the following integral representation

$$
B_{t}^{H}=\int_{0}^{t} K_{H}(t, s) d W_{s}
$$

where $W=\left\{W_{t}, t \geq 0\right\}$ is a $d$-dimensional Brownian motion, and $K_{H}(s, t)$ is the square integrable kernel given by

$$
K_{H}(t, s)=C_{H, 1} s^{\frac{1}{2}-H} \int_{s}^{t}(u-s)^{H-\frac{3}{2}} u^{H-\frac{1}{2}} d u
$$

if $H>\frac{1}{2}$, and by
$K_{H}(t, s)=C_{H, 2}\left[\left(\frac{t}{s}\right)^{H-\frac{1}{2}}(t-s)^{H-\frac{1}{2}}-\left(H-\frac{1}{2}\right) s^{\frac{1}{2}-H} \int_{s}^{t} u^{H-\frac{3}{2}}(u-s)^{H-\frac{1}{2}} d u\right]$,
if $H<\frac{1}{2}$, for any $s<t$, where the constants are $C_{H, 1}=\left[\frac{H(2 H-1)}{B\left(2-2 H, H-\frac{1}{2}\right)}\right]^{\frac{1}{2}}$, and $C_{H, 2}=\left[\frac{2 H}{(1-2 H) b\left(1-2 H, H+\frac{1}{2}\right)}\right]^{\frac{1}{2}}$, where $B(\alpha, \beta)$ denotes th beta function.

The processes $B^{H}$ and $W$ generate the same filtration, that is, $\mathcal{F}_{t}=$ $\sigma\left\{W_{s}, 0 \leq s \leq t\right\}=\sigma\left\{B_{s}^{H}, 0 \leq s \leq t\right\}$.

The fractional Brownian motion satisfies the following local nondeterminism property:
(LND) There exists a constant $k_{2}>0$, depending only on $H$ and $T$, such that for any $t \in[0, T], 0<r<t \wedge(T-t)$ and for $i=1, \ldots, d$,

$$
\begin{equation*}
\operatorname{Var}\left(B_{t}^{H, i}\left|B_{s}^{H, i}:|s-t| \geq r\right) \geq k_{2} r^{2 H}\right. \tag{4.1}
\end{equation*}
$$

Consider the approximated self-intersection local time $L_{\varepsilon}$ introduced in (3.3). From the general result proved in Section 2 it follows that if $H d<1$, then $L_{\varepsilon}$ converges in $L^{2}$ to the self-intersection local time $L$, and the random variable $L$ has exponential moments. If $H d \geq 1$, this result is no longer true, and one considers the renormalization of the self-intersection local time, introduced by Varadhan.

The purpose of this section is to apply the Clark-Ocone formula to provide a stochastic integral representation for the renormalized self-intersection local time $\widetilde{L}$. As a consequence, we will prove the existence of some exponential moments for the random variable $\widetilde{L}$.

Theorem 2 Suppose that $H<\min \left(\frac{3}{2 d}, \frac{2}{d+1}\right)$. Then the renormalized selfintersection local time of the d-dimensional fractional Brownian motion $B^{H}$ exists in $L^{2}$ and it has the following integral representation
$\widetilde{L}=-\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{t} \frac{A_{r, t, s}^{i}}{\sigma_{r, s, t}^{2}} p_{\sigma_{r, s, t}^{2}}\left(A_{r, t, s}^{i}\right)\left[K_{H}(t, r)-K_{H}(s, r)\right] d s d t\right) d W_{r}^{i}$,
where

$$
\begin{equation*}
A_{r, t, s}=E\left(B_{t}^{H}-B_{s}^{H} \mid \mathcal{F}_{r}\right) \tag{4.2}
\end{equation*}
$$

and

$$
\sigma_{r, s, t}^{2}=\operatorname{Var}\left(B_{t}^{H, i}-B_{s}^{H, i} \mid \mathcal{F}_{r}\right) .
$$

Proof. The proof will be done in several steps.
Step 1 We are going to apply Clark-Ocone formula to the random variable $L_{\varepsilon}$. It is clear that $L_{\varepsilon}$ belongs to $\mathbb{D}^{1,2}$, and its derivative can be computed as follows

$$
D_{r}^{i} L_{\varepsilon}=\int_{0}^{T} \int_{0}^{t} \frac{\partial p_{\varepsilon}}{\partial x_{i}}\left(B_{t}^{H}-B_{s}^{H}\right) D_{r}^{i}\left(B_{t}^{H, i}-B_{s}^{H, i}\right) d s d t
$$

where $r \in[0, T]$, and $i=1, \ldots, d$. Using

$$
D_{r}^{i}\left(B_{t}^{H, i}-B_{s}^{H, i}\right)=\left[K_{H}(t, r)-K_{H}(s, r)\right] \mathbf{1}_{[0, t]}(r)
$$

we obtain

$$
\begin{equation*}
D_{r}^{i} L_{\varepsilon}=\int_{r}^{T} \int_{0}^{t} \frac{\partial p_{\varepsilon}}{\partial x_{i}}\left(B_{t}^{H}-B_{s}^{H}\right)\left[K_{H}(t, r)-K_{H}(s, r)\right] d s d t \tag{4.3}
\end{equation*}
$$

The next step is to compute the conditional expectation $E\left(D_{r}^{i} L_{\varepsilon} \mid \mathcal{F}_{r}\right)$. The conditional law of $B_{t}^{H}-B_{s}^{H}$ given $\mathcal{F}_{r}$ is normal with mean $A_{r, t, s}$ and covariance matrix $\sigma_{r, s, t}^{2} I_{d}$, where $I_{d}$ is the $d$-dimensional identity matrix. Hence,
the conditional expectation $E\left(\left.\frac{\partial p_{\varepsilon}}{\partial x_{i}}\left(B_{t}^{H}-B_{s}^{H}\right) \right\rvert\, \mathcal{F}_{r}\right)$ is given by

$$
\begin{aligned}
E\left(\left.\frac{\partial p_{\varepsilon}}{\partial x_{i}}\left(B_{t}^{H}-B_{s}^{H}\right) \right\rvert\, \mathcal{F}_{r}\right) & =\int_{\mathbb{R}^{d}} \frac{\partial p_{\varepsilon}}{\partial x_{i}}(y) p_{\sigma_{r, s, t}^{2}}\left(y-A_{r, t, s}\right) d y \\
& =\frac{\partial p_{\varepsilon+\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right)}{\partial x_{i}} \\
& =-\frac{A_{r, t, s}^{i}}{\varepsilon+\sigma_{r, s, t}^{2}} p_{\varepsilon+\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right) .
\end{aligned}
$$

As a consequence, from (4.3) we obtain
$E\left(D_{r}^{i} L_{\varepsilon} \mid \mathcal{F}_{r}\right)=-\int_{r}^{T} \int_{0}^{t} \frac{A_{r, t, s}^{i}}{\varepsilon+\sigma_{r, s, t}^{2}} p_{\varepsilon+\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right)\left[K_{H}(t, r)-K_{H}(s, r)\right] d s d t$,
and this leads to the following integral representation for $L_{\varepsilon}-E\left(L_{\varepsilon}\right)$

$$
\begin{aligned}
& L_{\varepsilon}-E\left(L_{\varepsilon}\right) \\
= & -\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{t} \frac{A_{r, t, s}^{i}}{\varepsilon+\sigma_{r, s, t}^{2}} p_{\varepsilon+\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right)\left[K_{H}(t, r)-K_{H}(s, r)\right] d s d t\right) d W_{r}^{i} .
\end{aligned}
$$

Step 2 In order to pass to the limit as $\varepsilon$ tends to zero we proceed as follows. Set

$$
\begin{equation*}
\Sigma_{\varepsilon}^{i}(r, t, s)=\frac{A_{r, t, s}^{i}}{\varepsilon+\sigma_{r, s, t}^{2}} p_{\varepsilon+\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right)\left[K_{H}(t, r)-K_{H}(s, r)\right] . \tag{4.4}
\end{equation*}
$$

Clearly, $\Sigma_{\varepsilon}^{i}(r, t, s)$ converges pointwise as $\varepsilon$ tends to zero to

$$
\Sigma^{i}(r, t, s)=\frac{A_{r, t, s}^{i}}{\sigma_{r, s, t}^{2}} p_{\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right)\left[K_{H}(t, r)-K_{H}(s, r)\right] .
$$

In order to establish the convergence of the integrals in the variables $s$ and $t$, we will first decompose the interval $[0, t]$ into the disjoint union of $[r, t]$ and $[0, r)$. In this way we obtain

$$
L_{\varepsilon}-E\left(L_{\varepsilon}\right)=L_{\varepsilon}^{(1)}+L_{\varepsilon}^{(2)}
$$

where

$$
L_{\varepsilon}^{(1)}=-\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{r}^{t} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t\right) d W_{r}^{i}
$$

and

$$
L_{\varepsilon}^{(2)}=-\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t\right) d W_{r}^{i}
$$

Step 3 We claim that the random field $\Sigma_{\varepsilon}^{i}(r, t, s)$ is uniformly bounded on the set $0<r<s<t$ by an integrable function not depending on $\varepsilon$. In fact, using the local nondeterminism property (LND), and Lemma 5 in the Appendix, we obtain the following lower bound for the conditional variance $\sigma_{r, s, t}^{2}=\operatorname{Var}\left(B_{t}^{H, i}-B_{s}^{H, i} \mid \mathcal{F}_{r}\right)$ :

$$
\begin{equation*}
\sigma_{r, s, t}^{2} \geq \operatorname{Var}\left(B_{t}^{H, i}-B_{s}^{H, i} \mid \mathcal{F}_{s}\right)=\operatorname{Var}\left(B_{t}^{H, i} \mid \mathcal{F}_{s}\right) \geq k_{2}(t-s)^{2 H} . \tag{4.5}
\end{equation*}
$$

We can get rid off the factor $A_{r, t, s}^{i}$ in the expression (4.4) of $\Sigma_{\varepsilon}^{i}(r, t, s)$ using the inequality

$$
\begin{equation*}
p_{t}(x) \leq C \frac{t^{-\frac{d}{2}+\frac{1}{2}}}{|x|} e^{-\frac{|x|^{2}}{4 t}} \leq C \frac{t^{-\frac{d}{2}+\frac{1}{2}}}{|x|} \tag{4.6}
\end{equation*}
$$

for some constant $C>0$. In this way we obtain, using (4.5) and (4.6)

$$
\begin{equation*}
\left|\Sigma_{\varepsilon}^{i}(r, t, s)\right| \leq C(t-s)^{-H d-H}\left|K_{H}(t, r)-K_{H}(s, r)\right|, \tag{4.7}
\end{equation*}
$$

for some constant $C>0$, and by Lemma 7 in the Appendix we obtain that

$$
\begin{equation*}
\int_{r}^{T} \int_{r}^{t}(t-s)^{-H d-H}\left|K_{H}(t, r)-K_{H}(s, r)\right| d s d t \leq C\left(r^{\frac{1}{2}-H} \vee 1\right) \tag{4.8}
\end{equation*}
$$

By dominated convergence we deduce the convergence of the integrals

$$
\lim _{\varepsilon \downarrow 0} \int_{r}^{T} \int_{r}^{t} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t=\int_{r}^{T} \int_{r}^{t} \Sigma^{i}(r, t, s) d s d t
$$

for all $(r, \omega) \in[0, T] \times \Omega$, and a second application of the dominated convergence theorem yields that $\int_{r}^{T} \int_{r}^{t} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t$ converges in $L^{2}([0, T] \times \Omega)$ to $\int_{r}^{T} \int_{r}^{t} \Sigma^{i}(r, t, s) d s d t$. This implies the convergence of $L_{\varepsilon}^{(1)}$ to

$$
-\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{r}^{t} \Sigma^{i}(r, t, s) d s d t\right) d W_{r}^{i}
$$

in $L^{2}(\Omega)$ as $\varepsilon$ tends to zero.
Step 4 Consider now the case $s<r<t$. In this case the integral of the term $\Sigma_{\varepsilon}^{i}(r, t, s)$ is not necessarily bounded, and in order to show the convergence of $L_{\varepsilon}^{(2)}$ we will prove uniform bounds in $\varepsilon$ for the expectation
$E\left(\int_{r}^{T} \int_{r}^{t}\left|\Sigma_{\varepsilon}^{i}(r, t, s)\right|^{p} d s d t\right)$, for some $p>1$. We can write for $s<r<t$, using the first inequality in (4.6)

$$
\begin{align*}
\left|\Sigma_{\varepsilon}^{i}(r, t, s)\right| & \leq \frac{\left|A_{r, t, s}\right|}{\left(\varepsilon+\sigma_{r, s, t}^{2}\right)} p_{\varepsilon+\sigma_{r, s, t}^{2}}\left(A_{r, t, s}\right)\left|K_{H}(t, r)\right| \\
& =(2 \pi)^{-\frac{d}{2}} \frac{\left|A_{r, t, s}\right|}{\left(\varepsilon+\sigma_{r, s, t}^{2}\right)^{1+\frac{d}{2}}} \exp \left(-\frac{\left|A_{r, t, s}\right|^{2}}{2\left(\varepsilon+\sigma_{r, s, t}^{2}\right)}\right)\left|K_{H}(t, r)\right| \\
& \leq C\left(\varepsilon+\sigma_{r, s, t}^{2}\right)^{-\frac{d+1}{2}} \exp \left(-\frac{\left|A_{r, t, s}\right|^{2}}{4\left(\varepsilon+\sigma_{r, s, t}^{2}\right)}\right)\left|K_{H}(t, r)\right| \tag{4.9}
\end{align*}
$$

for some constant $C>0$. If $s<r<t$, using the local nondeterminism property (LND) we obtain the following lower bound for the conditional variance $\sigma_{r, s, t}^{2}$ :

$$
\begin{equation*}
\sigma_{r, s, t}^{2}=\operatorname{Var}\left(B_{t}^{H, i}-B_{s}^{H, i} \mid \mathcal{F}_{r}\right)=\operatorname{Var}\left(B_{t}^{H, i} \mid \mathcal{F}_{r}\right) \geq k_{2}(t-r)^{2 H} \tag{4.10}
\end{equation*}
$$

On the other hand, if $s<r<t$

$$
\begin{align*}
\sigma_{r, s, t}^{2} & =\operatorname{Var}\left(B_{t}^{H, i}-B_{s}^{H, i} \mid \mathcal{F}_{r}\right)=\operatorname{Var}\left(B_{t}^{H, i}-B_{r}^{H, i} \mid \mathcal{F}_{r}\right) \\
& \leq \operatorname{Var}\left(B_{t}^{H, i}-B_{r}^{H, i}\right)=(t-r)^{2 H} \tag{4.11}
\end{align*}
$$

Also we will make use of the estimate (see [8])

$$
\begin{equation*}
\left|K_{H}(t, r)\right| \leq k_{3}(t-r)^{H-\frac{1}{2}} r^{\frac{1}{2}-H} \tag{4.12}
\end{equation*}
$$

Substituting the estimates (4.10), (4.11) and (4.12) into (4.9) yields

$$
\begin{equation*}
\left|\Sigma_{\varepsilon}^{i}(r, t, s)\right| \leq C r^{\frac{1}{2}-H} \Psi_{\varepsilon}(r, t, s) \tag{4.13}
\end{equation*}
$$

for some constant $C$, where

$$
\begin{equation*}
\Psi_{\varepsilon}(r, t, s)=\left(\varepsilon+k_{2}(t-r)^{2 H}\right)^{-\frac{d+1}{2}}(t-r)^{H-\frac{1}{2}} \exp \left(-\frac{\left|A_{r, t, s}\right|^{2}}{4\left(\varepsilon+(t-r)^{2 H}\right)}\right) \tag{4.14}
\end{equation*}
$$

Notice that if $H d<\frac{1}{2}$, then $\left|\Sigma_{\varepsilon}^{i}(r, t, s)\right|$ is uniformly bounded by the integrable function $C r^{\frac{3}{2}-H}(t-r)^{-H d-\frac{1}{2}}$, and we can conclude as in Step 3. For this reason, we can assume that $H d \geq \frac{1}{2}$.

We claim that for some $p>1$, we have

$$
\begin{equation*}
\sup _{\varepsilon>0} E\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}^{p}(r, t, s) d s d t\right)<\infty \tag{4.15}
\end{equation*}
$$

To show this estimate we first derive a lower bound for the expectation of $\left|A_{r, t, s}^{1}\right|^{2}=\left[E\left(B_{t}^{H, 1}-B_{s}^{H, 1} \mid \mathcal{F}_{r}\right)\right]^{2}$. The main idea is to add and substract the term $B_{r}^{H, 1}$, and then neglect the expectation $E\left(\left(\left(E\left(B_{t}^{H, 1} \mid \mathcal{F}_{r}\right)-B_{r}^{H, 1}\right)^{2}\right)\right)$. This argument will be used later to find a lower bound for the covariance matrix of the vector $\left(E\left(B_{t_{i}}^{H, 1}-B_{s_{i}}^{H, 1} \mid \mathcal{F}_{r}\right), 1 \leq i \leq n\right)$.

$$
\begin{aligned}
E\left(\left|A_{r, t, s}^{1}\right|^{2}\right)= & E\left(\left(E\left(B_{t}^{H, 1}-B_{s}^{H, 1} \mid \mathcal{F}_{r}\right)\right)^{2}\right) \\
= & E\left(\left(E\left(B_{t}^{H, 1} \mid \mathcal{F}_{r}\right)-B_{r}^{H, 1}\right)^{2}\right) \\
& +2 E\left(\left(E\left(B_{t}^{H, 1} \mid \mathcal{F}_{r}\right)-B_{r}^{H, 1}\right)\left(B_{r}^{H, 1}-B_{s}^{H, 1}\right)\right)+E\left(\left(B_{r}^{H, 1}-B_{s}^{H, 1}\right)^{2}\right) \\
\geq & 2 E\left(\left(B_{t}^{H, 1}-B_{r}^{H, 1}\right)\left(B_{r}^{H, 1}-B_{s}^{H, 1}\right)\right)+E\left(\left(B_{r}^{H, 1}-B_{s}^{H, 1}\right)^{2}\right) \\
= & E\left(\left(B_{t}^{H, 1}-B_{s}^{H, 1}\right)^{2}\right)-E\left(\left(B_{t}^{H, 1}-B_{r}^{H, 1}\right)^{2}\right) \\
= & (t-s)^{2 H}-(t-r)^{2 H} .
\end{aligned}
$$

As a consequence, we obtain, assuming $p<2$

$$
\begin{aligned}
E(\exp & \left.\left(-\frac{p\left|A_{r, t, s}\right|^{2}}{4\left(\varepsilon+(t-r)^{2 H}\right)}\right)\right) \\
= & \left(1+\frac{p}{2}\left(\varepsilon+(t-r)^{2 H}\right)^{-1} E\left(\left|A_{r, t, s}^{1}\right|^{2}\right)\right)^{-\frac{d}{2}} \\
\leq & \left(1+\frac{p}{2}\left(\varepsilon+(t-r)^{2 H}\right)^{-1}\left[(t-s)^{2 H}-(t-r)^{2 H}\right]\right)^{-\frac{d}{2}} \\
= & \left(\varepsilon+(t-r)^{2 H}\right)^{\frac{d}{2}} \\
& \times\left(\varepsilon+\left(1-\frac{p}{2}\right)(t-r)^{2 H}+\frac{p}{2}(t-s)^{2 H}\right)^{-\frac{d}{2}}
\end{aligned}
$$

Hence,

$$
\begin{align*}
& E\left(\exp \left(-\frac{p\left|A_{r, t, s}\right|^{2}}{4\left(\varepsilon+(t-r)^{2 H}\right)}\right)\right) \\
& \quad \leq C\left(\varepsilon+(t-r)^{2 H}\right)^{\frac{d}{2}}(t-r)^{-2 H \alpha}(t-s)^{-2 H \beta} \tag{4.16}
\end{align*}
$$

where $\alpha+\beta=\frac{d}{2}$. Substituting (4.16) into (4.14) yields

$$
\begin{aligned}
E\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}^{p}(r, t, s) d s d t\right) \leq & C \int_{r}^{T} \int_{0}^{r}\left(\varepsilon+(t-r)^{2 H}\right)^{-\frac{d+1}{2} p+\frac{d}{2}-\alpha} \\
& \times(t-r)^{\left(H-\frac{1}{2}\right) p}(t-s)^{-\beta 2 H} d s d t \\
\leq & C \int_{r}^{T} \int_{0}^{r}(t-r)^{-p H d-\frac{p}{2}+2 H \beta}(t-s)^{-2 H \beta} d s d t
\end{aligned}
$$

If $H d>1$, we can choose $\beta$ such that $2 H \beta>1$, and integrating in the variable $s$, the above integral is bounded by

$$
C \int_{r}^{T}(t-r)^{-p H d-\frac{p}{2}+1} d t
$$

which is finite it $p>1$ satisfyes $\left(H d+\frac{1}{2}\right) p<2$ (this is possible because $H d+\frac{1}{2}<2$ ). If $H d \leq 1$, we can choose $\beta$ such that $2 H \beta=H d-\delta$, for any $\delta>0$, and we obtain the bound

$$
C \int_{r}^{T}(t-r)^{-p H d-\frac{p}{2}+H d-\delta} d t
$$

which is again finite if $p>1$ is close to one, and $\delta>0$ is small enough.
As a consequence, from (4.13) and (4.15), for any fixed $r \in[0, T]$, the family of functions $\left\{\Sigma_{\varepsilon}^{i}(r, t, s), \varepsilon>0\right\}$, is uniformly integrable in $[r, T] \times$ $[0, r]$, so it converges in $L^{1}([r, T] \times[0, r]) \times \Omega$ to $\Sigma^{i}(r, t, s)$, for $i=1, \ldots, d$. This implies the convergence of the integrals

$$
\lim _{\varepsilon \downarrow 0} \int_{r}^{T} \int_{0}^{r} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t=\int_{r}^{T} \int_{0}^{r} \Sigma^{i}(r, t, s) d s d t
$$

for each fixed $r \in[0, T]$ in $L^{1}(\Omega)$.
Finally, we claim that this convergence also holds in $L^{2}([0, T] \times \Omega)$, and this implies the convergence of $L_{\varepsilon}^{(2)}$ to

$$
-\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \Sigma^{i}(r, t, s) d s d t\right) d W_{r}^{i}
$$

in $L^{2}(\Omega)$ as $\varepsilon$ tends to zero. To show the convergence in $L^{2}([0, T] \times \Omega)$ of the integrals

$$
Y_{\varepsilon}^{i}(r)=\int_{r}^{T} \int_{0}^{r} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t
$$

it suffices to prove that

$$
\begin{equation*}
\sup _{\varepsilon>0} \int_{0}^{T} E\left(\left|Y_{\varepsilon}^{i}(r)\right|^{p}\right) d r<\infty \tag{4.17}
\end{equation*}
$$

for all $i=1, \ldots, d$ and for some $p>2$. The proof of (4.17) will be the last step in the proof of this theorem.
Step 5 Suppose first that $H d<1$. Then, from (4.13) we obtain

$$
\int_{0}^{T} E\left(\left|Y_{\varepsilon}^{i}(r)\right|^{p}\right) d r \leq C \int_{0}^{T} E\left[\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right)^{p}\right] r^{p\left(\frac{1}{2}-H\right)} d r
$$

Using (4.14) and Minkowski's inequality yields

$$
\begin{align*}
\left\|\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right\|_{p} \leq & \int_{r}^{T} \int_{0}^{r}\left(\varepsilon+k_{2}(t-r)^{2 H}\right)^{-\frac{d+1}{2}}(t-r)^{H-\frac{1}{2}} \\
& \times\left\|\exp \left(-\frac{\left|A_{r, t, s}\right|^{2}}{4\left(\varepsilon+(t-r)^{2 H}\right)}\right)\right\|_{p} d s d t,(4.18) \tag{4.18}
\end{align*}
$$

and from (4.16), choosing $\beta=\frac{d}{2}$, we get

$$
\begin{equation*}
\left\|\exp \left(-\frac{\left|A_{r, t, s}\right|^{2}}{4\left(\varepsilon+(t-r)^{2 H}\right)}\right)\right\|_{p} \leq C\left(\varepsilon+(t-r)^{2 H}\right)^{\frac{d}{2 p}}(t-s)^{-\frac{H d}{p}} \tag{4.19}
\end{equation*}
$$

Substituting (4.19) into (4.18) yields

$$
\left\|\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right\|_{p} \leq C \int_{r}^{T}(t-r)^{-H d-\frac{1}{2}+\frac{H d}{p}} d r
$$

which is finite if we choose $p>2$ such that $p<\frac{2 H d}{2 H d-1}$. Finally, if $p\left(\frac{1}{2}-H\right)>$ -1 we complete the proof of (4.17) in the case $H d<1$.

In the case $H d \geq 1$ we cannot apply the previous arguments, and the proof of (4.17) follows from the moment estimates given in Proposition 3 ,

Remark 1 Theorem 2also provides an alternative proof of the existence of the self-intersection local time in the case $H \in\left[\frac{1}{d}, \min \left(\frac{3}{2 d}, \frac{2}{d+1}\right)\right)$, which was proved by Hu and Nualart in $\left[9\right.$ in the general case $H d<\frac{3}{2}$. Notice that for $d \geq 3$, the condition $H \in\left[\frac{1}{d}, \min \left(\frac{3}{2 d}, \frac{2}{d+1}\right)\right)$ is equivalent to $1 \leq H d<\frac{3}{2}$, and for $d=2$ we require $H<\frac{2}{3}$, instead of the more general condition $H<\frac{3}{4}$,
that guarantees the existence of the renormalized local time (see [16] and [9]).

The next Proposition contains the basic estimates on the moments of the quadratic variation of the stochastic integral appearing in the representation of the renormalized self-intersection local time.

Proposition 3 Assume $1 \leq H d<\frac{3}{2}$. Set

$$
\Lambda_{\varepsilon}(r)=\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t
$$

where $\Psi_{\varepsilon}(r, t, s)$ has been defined in 4.14). Then, for any integer $n \geq 1$,

$$
E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq C^{n}(n!)^{\gamma},
$$

for some constant $C>0$, where

$$
\gamma>\left(\frac{1}{2}+H\right)\left(d-\frac{1}{2 H}\right) .
$$

Proof. Set $g_{\varepsilon}(t-r)=\left(\varepsilon+k_{2}(t-r)^{2 H}\right)^{-\frac{d+1}{2}}(t-r)^{H-\frac{1}{2}}$. We have

$$
\begin{align*}
E\left(\Lambda_{\varepsilon}^{n}(r)\right)= & E\left[\left(\int_{r}^{T} \int_{0}^{r} g_{\varepsilon}(t-r) \exp \left(-\frac{\left|A_{r, s, t}\right|^{2}}{4\left(\varepsilon+(t-r)^{2 H}\right)}\right) d s d t\right)^{n}\right] \\
= & n!\int_{[r, T]^{n}} \int_{S_{n}} \prod_{i=1}^{n} g_{\varepsilon}\left(t_{i}-r\right) \\
& \times\left(E\left(\exp \left(-\sum_{i=1}^{n} \frac{\left|A_{r, s_{i}, t_{i}}^{1}\right|^{2}}{4\left(\varepsilon+\left(t_{i}-r\right)^{2 H}\right)}\right)\right)\right)^{d} d s d t \tag{4.20}
\end{align*}
$$

where $S_{n}=\left\{0<s_{1}<\cdots<s_{n}<r\right\}, s=\left(s_{1}, \ldots, s_{n}\right)$ and $t=\left(t_{1}, \ldots, t_{n}\right)$.
We denote by $Q$ the covariance matrix of the vector

$$
\left(E\left(B_{t_{1}}^{H, 1}-B_{s_{1}}^{H, 1} \mid \mathcal{F}_{r}\right), \ldots, E\left(B_{t_{n}}^{H, 1}-B_{s_{n}}^{H, 1} \mid \mathcal{F}_{r}\right)\right)
$$

Then, a well-known formula for Gaussian random variables implies that

$$
\begin{align*}
E\left[\exp \left(-\sum_{i=1}^{n} \frac{\left|A_{r, s_{i}, t_{i}}^{1}\right|^{2}}{4\left(\varepsilon+\left(t_{i}-r\right)^{2 H}\right)}\right)\right] & =\operatorname{det}\left(I+\frac{1}{2} Q D^{-1}\right)^{-\frac{1}{2}} \\
= & 2^{\frac{n}{2}} \prod_{i=1}^{n} \sqrt{a_{i}} \operatorname{det}(2 D+Q)^{-\frac{1}{2}} \tag{4.21}
\end{align*}
$$

where $D$ denotes the $n \times n$ diagonal matrix with entries $a_{i}=\varepsilon+\left(t_{i}-r\right)^{2 H}$. As in the computation of $E\left(\left|A_{r, t, s}^{1}\right|^{2}\right)$, adding and substracting the term $B_{r}^{H, 1}$ yields

$$
\begin{aligned}
Q_{i j}= & E\left(E\left(B_{t_{i}}^{H, 1}-B_{s_{i}}^{H, 1} \mid \mathcal{F}_{r}\right) E\left(B_{t_{j}}^{H, 1}-B_{s_{j}}^{H, 1} \mid \mathcal{F}_{r}\right)\right) \\
= & E\left(E\left(B_{t_{i}}^{H, 1}-B_{r}^{H, 1} \mid \mathcal{F}_{r}\right) E\left(B_{t_{j}}^{H, 1}-B_{r}^{H, 1} \mid \mathcal{F}_{r}\right)\right) \\
& +E\left(\left(B_{r}^{H, 1}-B_{s_{i}}^{H, 1}\right)\left(B_{t_{j}}^{H, 1}-B_{r}^{H, 1}\right)\right)+E\left(\left(B_{t_{i}}^{H, 1}-B_{r}^{H, 1}\right)\left(B_{r}^{H, 1}-B_{s_{j}}^{H, 1}\right)\right) \\
& +E\left(\left(B_{r}^{H, 1}-B_{s_{i}}\right)\left(B_{r}^{H, 1}-B_{s_{j}}^{H, 1}\right)\right) \\
= & E\left(E\left(B_{t_{i}}^{H, 1}-B_{r}^{H, 1} \mid \mathcal{F}_{r}\right) E\left(B_{t_{j}}^{H, 1}-B_{r}^{H, 1} \mid \mathcal{F}_{r}\right)\right) \\
& -E\left(\left(B_{t_{i}}^{H, 1}-B_{r}^{H, 1}\right)\left(B_{t_{j}}^{H, 1}-B_{r}^{H, 1}\right)\right)+E\left(\left(B_{t_{i}}^{H, 1}-B_{s_{i}}^{H, 1}\right)\left(B_{t_{j}}^{H, 1}-B_{s_{j}}^{H, 1}\right)\right) .
\end{aligned}
$$

Hence, we obtain

$$
Q=R-N+M,
$$

where

$$
\begin{aligned}
R_{i j} & =E\left(E\left(B_{t_{i}}^{H, 1}-B_{r}^{H, 1} \mid \mathcal{F}_{r}\right) E\left(B_{t_{j}}^{H, 1}-B_{r}^{H, 1} \mid \mathcal{F}_{r}\right)\right) \\
M_{i j} & =E\left(\left(B_{t_{i}}^{H, 1}-B_{s_{i}}^{H, 1}\right)\left(B_{t_{j}}^{H, 1}-B_{s_{j}}^{H, 1}\right)\right) \\
N_{i j} & =E\left(\left(B_{t_{i}}^{H, 1}-B_{r}^{H, 1}\right)\left(B_{t_{j}}^{H, 1}-B_{r}^{H, 1}\right)\right) .
\end{aligned}
$$

All these matrices are nonnegative definite. The main idea will be to get rid off the matrix $R$, and control the matrix $N$ by its diagonal elements which are

$$
N_{i i}=\left(t_{i}-r\right)^{2 H} .
$$

Indeed, the matrix $N$ is nonnegative definite and, hence, it safisties the inequality

$$
\begin{equation*}
N \leq n D_{N}, \tag{4.22}
\end{equation*}
$$

where $D_{N}$ is a diagonal matrix whose entries are $N_{i i}$. Therefore,

$$
Q \geq-N+M \geq-n D_{N}+M
$$

and for any $1 \leq \delta<2$, we can write

$$
\begin{equation*}
\operatorname{det}(2 D+Q) \geq \operatorname{det}\left(2 D+\frac{2-\delta}{n} Q\right) \leq \operatorname{det}\left(2 D-(2-\delta) D_{N}+\frac{2-\delta}{n} M\right) \tag{4.23}
\end{equation*}
$$

The entries of the diagonal matrix $D_{1}=2 D-(2-\delta) D_{N}$ are the positive numbers

$$
2 \varepsilon+\delta\left(t_{i}-r\right)^{2 H}>0
$$

From (4.20), (4.21) and (4.23) we obtain

$$
\begin{aligned}
E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq & 2^{\frac{n d}{2}} n!\int_{[r, T]^{n}} \int_{S_{n}} \prod_{i=1}^{n}\left(g_{\varepsilon}\left(t_{i}-r\right) a_{i}^{\frac{d}{2}}\right) \\
& \times \operatorname{det}\left(D_{1}+\frac{2-\delta}{n} M\right)^{-\frac{d}{2}} d s d t
\end{aligned}
$$

We have

$$
\operatorname{det}\left(D_{1}+\frac{2-\delta}{n} M\right)^{-\frac{d}{2}} \leq\left(\frac{n}{2-\delta}\right)^{n \beta}\left(\operatorname{det} D_{1}\right)^{-\alpha}(\operatorname{det} M)^{-\beta}
$$

where $\alpha+\beta=\frac{d}{2}$. Hence,

$$
\begin{aligned}
E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq & \left(\frac{n}{2-\delta}\right)^{n \beta} 2^{\frac{n d}{2}} n!\int_{[r, T]^{n}} \int_{S_{n}} \prod_{i=1}^{n}\left(g_{\varepsilon}\left(t_{i}-r\right) a_{i}^{\frac{d}{2}}\left(2 \varepsilon+\delta\left(t_{i}-r\right)^{2 H}\right)^{-\alpha}\right) \\
& \times(\operatorname{det} M)^{-\beta} d s d t
\end{aligned}
$$

Then,

$$
\begin{aligned}
& g_{\varepsilon}\left(t_{i}-r\right) a_{i}^{\frac{d}{2}}\left(2 \varepsilon+2\left(t_{i}-r\right)^{2 H}\right)^{-\alpha} \\
= & \left(\varepsilon+k_{2}\left(t_{i}-r\right)^{2 H}\right)^{-\frac{d+1}{2}}\left(t_{i}-r\right)^{H-\frac{1}{2}}\left(\varepsilon+\left(t_{i}-r\right)^{2 H}\right)^{\frac{d}{2}}\left(2 \varepsilon+2\left(t_{i}-r\right)^{2 H}\right)^{-\alpha} \\
\leq & C\left(t_{i}-r\right)^{-\frac{1}{2}-2 H \alpha}
\end{aligned}
$$

for some constant $C>0$. Thus

$$
\begin{equation*}
E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq C^{n} n^{\beta n} n!\int_{[r, T]^{n}} \int_{S_{n}} \prod_{i=1}^{n}\left(t_{i}-r\right)^{-\frac{1}{2}-2 H \alpha}(\operatorname{det} M)^{-\beta} d s d t \tag{4.24}
\end{equation*}
$$

for some constant $C>0$.
Applying Lemma 5 in the Appendix and the local nondeterminism property of the fractional Brownian motion we obtain

$$
\begin{align*}
\operatorname{det} M & =\operatorname{Var}\left(B_{t_{n}}-B_{s_{n}}\right) \operatorname{Var}\left(B_{t_{n-1}}-B_{s_{n-1}} \mid B_{t_{n}}-B_{s_{n}}\right) \\
& \times \cdots \times \operatorname{Var}\left(B_{t_{1}}-B_{s_{1}} \mid B_{t_{2}}-B_{s_{2}}, \ldots, B_{t_{n}}-B_{n}\right) \\
& =\left(t_{n}-s_{n}\right)^{2 H} \operatorname{Var}\left(B_{s_{n-1}} \mid B_{t_{n-1}}, B_{t_{n}}, B_{s_{n}}\right) \\
& \times \cdots \times \operatorname{Var}\left(B_{s_{1}} \mid B_{t_{1}}, \ldots, B_{t_{n}}, B_{s_{1}}, \ldots, B_{s_{n-1}}\right) \\
\geq & k_{2}^{n-1}\left(r-s_{n}\right)^{2 H}\left(\left(s_{n}-s_{n-1}\right) \wedge s_{n-1}\right)^{2 H} \cdots\left(\left(s_{2}-s_{1}\right) \wedge s_{1}\right)^{2 H} \tag{4.25}
\end{align*}
$$

Substituting (4.25) into (4.24), and choosing $\alpha$ such that $\alpha<\frac{1}{4 H}$ (this is possible because $H d \geq 1$ ) yields
$E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq C^{n} n^{\beta n} n!\int_{S_{n}}\left[\left(r-s_{n}\right)\left(\left(s_{n}-s_{n-1}\right) \wedge s_{n-1}\right) \cdots\left(\left(s_{2}-s_{1}\right) \wedge s_{1}\right)\right]^{-2 \beta H} d s$.
Finally, by Lemma 8 in the Appendix we obtain

$$
E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq \frac{C^{n} n^{\beta n} n!}{\Gamma(n(1-2 H \beta)+1)}
$$

Notice that $\beta=\frac{d}{2}-\alpha>\frac{d}{2}-\frac{1}{4 H}$. And hence,

$$
E\left(\Lambda_{\varepsilon}^{n}(r)\right) \leq C^{n}\left(n!^{\beta+2 H \beta},\right.
$$

where

$$
\beta(1+2 H)>\frac{d}{2}-\frac{1}{4 H}+H d-\frac{1}{2}=\left(\frac{1}{2}+H\right)\left(d-\frac{1}{2 H}\right) .
$$

This concludes the proof.
Using the above proposition we can deduce the following integrability results for the renormalized self-intersection local time.

Theorem 4 Assume $\frac{1}{d} \leq H<\min \left(\frac{3}{2 d}, \frac{2}{d+1}\right)$. For any integer $p<\frac{1}{2}\left[\left(\frac{1}{2}+H\right)\left(d-\frac{1}{2 H}\right)\right]^{-1}$ we have

$$
E\left(\exp |\widetilde{L}|^{p}\right)<\infty
$$

Proof. Taking into account Lemma 6 in the Appendix, it suffices to show that

$$
E\left(\exp \langle\widetilde{L}\rangle^{p}\right)<\infty
$$

where

$$
\langle\widetilde{L}\rangle=\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{t} \Sigma^{i}(r, t, s) d s d t\right)^{2} d r
$$

As in the proof of Theorem 2 we make the decomposition

$$
\int_{r}^{T} \int_{0}^{t} \Sigma^{i}(r, t, s) d s d t=\int_{r}^{T} \int_{r}^{t} \Sigma^{i}(r, t, s) d s d t+\int_{r}^{T} \int_{0}^{r} \Sigma^{i}(r, t, s) d s d t
$$

From (4.7) and (4.8) we know that

$$
\left|\int_{r}^{T} \int_{r}^{t} \Sigma^{i}(r, t, s) d s d t\right| \leq C\left(r^{\frac{1}{2}-H} \vee 1\right) .
$$

Therefore, applying Fatou's lemma and the estimate (4.13) yields

$$
\begin{aligned}
E\left(\exp \langle\widetilde{L}\rangle^{p}\right) & \leq C E\left(\exp \left(\left|\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \Sigma^{i}(r, t, s) d s d t\right)^{2} d r\right|^{p}\right)\right) \\
& \leq C \liminf _{\varepsilon \downarrow 0} E\left(\exp \left(\left|\sum_{i=1}^{d} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \Sigma_{\varepsilon}^{i}(r, t, s) d s d t\right)^{2} d r\right|^{p}\right)\right) \\
& \leq C \lim \inf _{\varepsilon \downarrow 0} E\left(\exp \left(C\left|\int_{0}^{T} r^{1-2 H}\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right)^{2} d r\right|^{p}\right)\right)
\end{aligned}
$$

Applying Hölder and Jensen inequalities we obtain

$$
\begin{aligned}
E\left(\exp \langle\widetilde{L}\rangle^{p}\right) & \leq C \lim \inf _{\varepsilon \downarrow 0} E\left(\exp \left(C \int_{0}^{T} r^{1-2 H}\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right)^{2 p} d r\right)\right) \\
& \leq C \lim \inf _{\varepsilon \downarrow 0} \int_{0}^{T} r^{1-2 H} E\left(\exp \left(C\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right)^{2 p}\right)\right) d r
\end{aligned}
$$

Finally,

$$
\begin{aligned}
& E\left(\exp \left(C\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right)^{2 p}\right)\right) \\
= & \sum_{n=1}^{\infty} \frac{C^{n}}{n!} E\left(\left(\int_{r}^{T} \int_{0}^{r} \Psi_{\varepsilon}(r, t, s) d s d t\right)^{2 n p}\right) \\
\leq & \sum_{n=1}^{\infty} \frac{C^{n}}{n!}(([2 n p]+1)!)^{\gamma}
\end{aligned}
$$

and it suffices to apply Proposition 3 to conclude the proof.
Remark 2 The exponent $p_{0}=\frac{1}{2}\left[\left(\frac{1}{2}+H\right)\left(d-\frac{1}{2 H}\right)\right]^{-1}$ is not optimal. For instance, if $H d=1$, then $p_{0}=\frac{2 H}{1+2 H}$ and we know that for $H d<1$, then $p_{0}=\frac{1}{H d}$. In particular, if $H=\frac{1}{2}$ and $d=2$ we obtain $p_{0}=\frac{1}{2}$, and we know that in this case the critical exponent is $p_{0}=1$. The lack of optimality is due to the factor $n$ in the estimation of the positive definite matrix $N$ by its diagonal elements given in (4.22). Without this factor $n$ we would get the critical exponent $\frac{1}{2 H d-1}$, but our method does not allow to get this value.

Remark 3 In the case of the planar Brownian motion $B=\left\{B_{t}, t \geq 0\right\}$ (that is, $d=2$, and $H=\frac{1}{2}$ ), formula (4.2) yields

$$
\begin{equation*}
\widetilde{L}=-\frac{1}{2 \pi} \sum_{i=1}^{2} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \frac{B_{r}^{i}-B_{s}^{i}}{(t-r)^{2}} \exp \left(-\frac{\left|B_{r}-B_{s}\right|^{2}}{2(t-r)}\right) d s d t\right) d B_{r}^{i} \tag{4.26}
\end{equation*}
$$

The quadratic variation of this stochastic integral is

$$
\begin{aligned}
\langle\widetilde{L}\rangle & =\frac{1}{4 \pi^{2}} \sum_{i=1}^{2} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \frac{B_{r}^{i}-B_{s}^{i}}{(t-r)^{2}} \exp \left(-\frac{\left|B_{r}-B_{s}\right|^{2}}{2(t-r)}\right) d s d t\right)^{2} d r \\
& \leq \frac{1}{4 \pi^{2}} \int_{0}^{T}\left(\int_{r}^{T} \int_{0}^{r} \frac{\left|B_{r}-B_{s}\right|}{(t-r)^{2}} \exp \left(-\frac{\left|B_{r}-B_{s}\right|^{2}}{2(t-r)}\right) d s d t\right)^{2} d r \\
& =\frac{1}{\pi^{2}} \int_{0}^{T}\left(\int_{0}^{r} \frac{1}{\left|B_{r}-B_{s}\right|} \exp \left(-\frac{\left|B_{r}-B_{s}\right|^{2}}{2(T-r)}\right) d s\right)^{2} d r \\
& \leq \frac{1}{\pi^{2}} \int_{0}^{T}\left(\int_{0}^{r} \frac{d s}{\left|B_{r}-B_{s}\right|}\right)^{2} d r .
\end{aligned}
$$

From Itô's calculus we know that

$$
\int_{0}^{r} \frac{d s}{\left|B_{r}-B_{s}\right|}=\frac{1}{d-1}\left(X_{r}-b_{r}\right)
$$

where $X_{r}$ has the law of the modulus of a $d$-dimensional Brownian motion at time $r$ (Bessel process), and $b_{r}$ has a normal $N(0, r)$ law. We can write

$$
\exp (\lambda\langle\widetilde{L}\rangle) \leq \frac{1}{T} \int_{0}^{T} \exp \left(\frac{T \lambda}{\pi^{2}}\left(\int_{0}^{r} \frac{d s}{\left|B_{r}-B_{s}\right|}\right)^{2}\right) d r
$$

which clearly imply the existence of some $\lambda_{0}$ such that $E(\exp (\lambda\langle\widetilde{L}\rangle))<$ $\infty$ for all $\lambda<\lambda_{0}$. From Lemma 6 we get that there exists $\beta_{0}$ such that $E(\exp (\beta|\widetilde{L}|))<\infty$ for all $\beta<\beta_{0}$. This method does not allows us to obtain the critical exponent, just the existence of exponential moments.
Remark 4 The above results remain true if we replace the fractional Brownian motion with Hurst paramter $H$, by an arbitrary centered Gaussian process of the form (3.1) satisfying the local nondeterminism property (LND) and following properties:
(C1) For any $s, t \in[0, T], s<t$, there exist constants $k_{3}$ and $k_{4}$ such that

$$
k_{3}(t-s)^{2 H} \leq E\left(\left|B_{t}^{i}-B_{s}^{i}\right|^{2}\right) \leq k_{4}(t-s)^{2 H} .
$$

(C2) The kernel $K(t, s)$ satisfies the estimates

$$
|K(t, s)| \leq k_{5}(t-s)^{H-\frac{1}{2}} s^{\frac{1}{2}-H},
$$

for all $s<t$, and

$$
\int_{r}^{T} \int_{r}^{t}(t-s)^{-H d-H}|K(t, r)-K(s, r)| d s d t \leq \psi(r)
$$

where $\int_{0}^{T} \psi(r)^{2} d r<\infty$.

## 5 Appendix

In this Appendix we will first state and prove some elementary lemmas. The first one is well-known.

Lemma 5 Suppose that $\mathcal{G}_{1} \subset \mathcal{G}_{2}$ are two $\sigma$-fields contained in $\mathcal{F}$. Then, for any square integrable random variable $F$ we have

$$
\operatorname{Var}\left(F \mid \mathcal{G}_{1}\right) \geq \operatorname{Var}\left(F \mid \mathcal{G}_{2}\right) .
$$

Let $M=\left\{M_{t}, t \geq 0\right\}$ be a continuous local martingale such that $M_{0}=0$. Then, the following maximal exponential inequality is well-known

$$
P\left(\sup _{0 \leq t \leq T}\left|M_{t}\right| \geq \delta,\langle M\rangle_{T}<\rho\right) \leq 2 \exp \left(-\frac{\delta^{2}}{2 \rho}\right) .
$$

As a consequence of this inequality we can obtain exponential moments for $M_{T}$ from exponential moments of the quadratic variation $\langle M\rangle_{T}$

Lemma 6 Suppose that for some $\alpha>0$ and $p \in(0,1]$ we have $E\left(e^{\alpha\langle M\rangle_{T}^{p}}\right)<$ $\infty$. Then,
(i) if $p=1$, for any $\lambda<\sqrt{\frac{\alpha}{2}}$, $E\left(e^{\lambda\left|M_{T}\right|}\right)<\infty$, and
(ii) if $p<1, E\left(e^{\lambda\left|M_{T}\right|^{p}}\right)<\infty$ for all $\lambda>0$.

Proof. Set $X=\left|M_{T}\right|^{p}$. For any constant $c>0$ we can write

$$
\begin{aligned}
E\left(e^{\lambda X}\right) & =\int_{0}^{\infty} P(X \geq y) \lambda e^{\lambda y} d y \\
& =\int_{0}^{\infty}\left[P\left(X \geq y,\langle M\rangle_{T}^{p}<c y\right)+P\left(X \geq y,\langle M\rangle_{T}^{p} \geq c y\right)\right] \lambda e^{\lambda y} d y \\
& \leq \int_{0}^{\infty} 2 \exp \left(-\frac{y^{\frac{1}{p}}}{2 c^{\frac{1}{p}}}\right) \lambda e^{\lambda y} d y+\int_{0}^{\infty} P\left(\frac{\langle M\rangle_{T}^{p}}{c} \geq y\right) \lambda e^{\lambda y} d y \\
& =\int_{0}^{\infty} 2 \lambda \exp \left(\lambda y-\frac{y^{\frac{1}{p}}}{2 c^{\frac{1}{p}}}\right) d y+E\left(e^{\frac{\lambda}{c}\langle M\rangle_{T}^{p}}\right) .
\end{aligned}
$$

Then it suffices to choose $c=\frac{\lambda}{\alpha}$ to complete the proof.
The next two results are technical lemmas used in the paper.
Lemma 7 Suppose that $H<\min \left(\frac{2}{d+1}, \frac{3}{2 d}\right)$. Then, we have

$$
\int_{r}^{T} \int_{r}^{t}(t-s)^{-H d-H}\left|K_{H}(t, r)-K_{H}(s, r)\right| d s d t \leq C\left(r^{\frac{1}{2}-H} \vee 1\right),
$$

for some constant $C$.
Proof. We know that

$$
\frac{\partial K_{H}}{\partial t}(t, s)=c_{H}\left(H-\frac{1}{2}\right)\left(\frac{t}{s}\right)^{H-\frac{1}{2}}(t-s)^{H-\frac{3}{2}}
$$

Then

$$
\begin{aligned}
& I:=\int_{r}^{T} \int_{r}^{t}(t-s)^{-H d-H}\left|K_{H}(t, r)-K_{H}(s, r)\right| d s d t \\
\leq & C \int_{r}^{T} \int_{r}^{t} \int_{s}^{t}(t-s)^{-H d-H}\left(\frac{\theta}{r}\right)^{H-\frac{1}{2}}(\theta-r)^{H-\frac{3}{2}} d \theta d s d t .
\end{aligned}
$$

If $H<\frac{1}{2}$, then, $\left(\frac{\theta}{r}\right)^{H-\frac{1}{2}} \leq 1$, and if $H>\frac{1}{2}$, then $\left(\frac{\theta}{r}\right)^{H-\frac{1}{2}} \leq C r^{\frac{1}{2}-H}$. Hence, the above integral is bounded by

$$
C\left(r^{\frac{1}{2}-H} \vee 1\right) \int_{r}^{T} \int_{r}^{t} \int_{s}^{t}(t-s)^{-H d-H}(\theta-r)^{H-\frac{3}{2}} d \theta d s d t
$$

From the decomposition

$$
\begin{aligned}
\frac{3}{2}-H & =\alpha+\beta \\
H d+H & =\gamma+\delta
\end{aligned}
$$

we obtain

$$
\begin{aligned}
& \int_{r}^{T} \int_{r}^{t} \int_{s}^{t}(t-s)^{-H d-H}(\theta-r)^{H-\frac{3}{2}} d \theta d s d t \\
= & \int_{r}^{T} \int_{r}^{t} \int_{s}^{t}(s-r)^{-\alpha}(\theta-s)^{-\beta-\gamma}(t-\theta)^{-\delta} d \theta d s d t .
\end{aligned}
$$

Finally, it suffices to show the parameters $\alpha, \beta, \gamma$ and $\delta$ in such a way that $\alpha<1, \delta<1$ and $\beta+\gamma<1$. This leads to the condition

$$
\frac{1}{2}+H d<\min \left(1, \frac{3}{2}-H\right)+\min (1, H d+H)
$$

which is satisfied if $H<\min \left(\frac{2}{d+1}, \frac{3}{2 d}\right)$.
Lemma 8 Let $a<1$. Fix an interval $[0, T]$. For each integer $n \geq 1$ we have

$$
\begin{align*}
& \int_{\Delta_{n}(T)}\left[\left(\left(T-s_{n}\right) \wedge s_{n}\right)\left(\left(s_{n}-s_{n-1}\right) \wedge s_{n-1}\right) \cdots\left(\left(s_{2}-s_{1}\right) \wedge s_{1}\right)\right]^{-a} d s \\
& \quad \leq \frac{T^{n(1-a)}}{\Gamma(n(1-a)+1)} C^{n} \tag{5.1}
\end{align*}
$$

where $\Delta_{n}(T)=\left\{0<s_{1}<\cdots<s_{n}<T\right\}$
Proof. We proceed by induction on $n$. For $n=1$ we can write

$$
\begin{aligned}
\int_{0}^{T}\left(\left(T-s_{1}\right) \wedge s_{1}\right)^{-a} d s_{1} & =\int_{0}^{\frac{T}{2}} s_{1}^{-a} d s_{1}+\int_{\frac{T}{2}}^{T}\left(T-s_{1}\right)^{-a} d s_{1} \\
& =\frac{2}{1-a}\left(\frac{T}{2}\right)^{1-a},
\end{aligned}
$$

which implies (5.1) with $C=\frac{\Gamma(2-a)}{1-a} 2^{a}$.

Suppose that the result holds for $n-1$. Then,

$$
\begin{aligned}
I_{n}= & \int_{\Delta_{n}(T)}\left[\left(\left(T-s_{n}\right) \wedge s_{n}\right)\left(\left(s_{n}-s_{n-1}\right) \wedge s_{n-1}\right) \cdots\left(\left(s_{2}-s_{1}\right) \wedge s_{1}\right)\right]^{-a} d s \\
= & \int_{0}^{T}\left(\left(T-s_{n}\right) \wedge s_{n}\right)^{-a} \\
& \times\left(\int_{\Delta_{n-1}\left(s_{n}\right)}\left[\left(\left(s_{n}-s_{n-1}\right) \wedge s_{n-1}\right) \cdots\left(\left(s_{2}-s_{1}\right) \wedge s_{1}\right)\right]^{-a} d s_{1} \cdots d s_{n-1}\right) d s_{n}
\end{aligned}
$$

By the induction hypothesis we can write

$$
\begin{aligned}
I_{n} \leq & \frac{C^{n-1}}{\Gamma(n-a)} \int_{0}^{T}\left(\left(T-s_{n}\right) \wedge s_{n}\right)^{-a} s_{n}^{(n-1)(1-a)} d s_{n} \\
= & \frac{C^{n-1}}{\Gamma((n-1)(1-a)+1)} \\
& \times\left(\int_{0}^{\frac{T}{2}} s_{n}^{(n-1)(1-a)-a} d s_{n}+\int_{\frac{T}{2}}^{T}\left(T-s_{n}\right)^{-a} s_{n}^{(n-1)(1-a)} d s_{n}\right) \\
\leq & \frac{C^{n-1}}{\Gamma(n(1-a)+a)} \\
& \times\left(\frac{1}{n(1-a)}\left(\frac{T}{2}\right)^{n(1-a)}+T^{n(1-a)} \int_{0}^{1}(1-x)^{-a} x^{(n-1)(1-a)} d x\right) \\
\leq & \frac{T^{n(1-a)} C^{n-1}}{\Gamma(n(1-a)+a)}\left(\frac{1}{n(1-a)}+\frac{\Gamma(1-a) \Gamma((n-1)(1-a)+1)}{\Gamma(n(1-a)+1)}\right) \\
= & T^{n(1-a)} C^{n-1}\left(\frac{1}{n(1-a) \Gamma(n(1-a)+a)}+\frac{\Gamma(1-a)}{\Gamma(n(1-a)+1)}\right)
\end{aligned}
$$

Using the relation $\Gamma(n+1)=n \Gamma(n)$ we obtain

$$
n(1-a) \Gamma(n(1-a)+a) \geq n(1-a) \Gamma(n(1-a))=\Gamma(n(1-a)+1)
$$

and, as a consequence

$$
I_{n} \leq T^{n(1-a)} C^{n-1}(1+\Gamma(1-a)) \frac{1}{\Gamma(n(1-a)+1)}
$$

and it suffices to take $C \geq \max \left(\frac{\Gamma(2-a)}{1-a} 2^{a}, 1+\Gamma(1-a)\right)$.

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