

**SEVERITY OF PEDESTRIAN INJURIES DUE TO TRAFFIC
CRASHES AT SIGNALIZED INTERSECTIONS IN HONG KONG:
A BAYESIAN SPATIAL LOGIT MODEL**

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1 **ABSTRACT**

2
3 The present study intended to (1) investigate the injury risk of pedestrian casualties
4 involved in traffic crashes at signalized intersections in Hong Kong; (2) determine the
5 effect of pedestrian volumes on the severity levels of pedestrian injuries; and (3)
6 explore the role of spatial correlation in econometric crash-severity models. The data
7 from 1,889 pedestrian-related crashes at 318 signalized intersections between 2008
8 and 2012 were elaborately collected from the Traffic Accident Database System
9 maintained by the Hong Kong Transport Department. To account for the
10 cross-intersection heterogeneity, a Bayesian hierarchical logit model with uncorrelated
11 and spatially correlated random effects was developed. An intrinsic conditional
12 autoregressive prior was specified for the spatial correlation term. Results revealed
13 that (1) signalized intersections with greater pedestrian volumes generally exhibited a
14 lower injury risk; (2) ignoring the spatial correlation potentially results in reduced
15 model goodness-of-fit, an underestimation of variability and standard error of
16 parameter estimates, as well as inconsistent, biased and erroneous inference; (3)
17 special attention should be paid to the following factors, which led to a significantly
18 higher probability of pedestrians being killed or sustaining severe injury: pedestrian
19 age greater than 65 years, casualties with head injuries, crashes that occurred on
20 footpaths that were not obstructed/overcrowded, heedless or inattentive crossing,
21 crashes on the two-way carriageway and those that occurred near tram or light-rail
22 transit stops.

23
24 *Keywords:* Pedestrian Injury Severity; Signalized Intersection; Spatial Logit Model;
25 Conditional Autoregressive Prior; Bayesian Inference.

27 **1. INTRODUCTION**

28

29 Walking is one of the oldest and substantial modes of transportation that provides
30 numerous benefits. It is well known that walking is conducive to less congestion,
31 efficient urban transport, fewer outputs of pollutants and greenhouse gases, less traffic
32 noise, and livable community. Around the world, walking is also a popular physical
33 and recreational activity for people of all ages. Indeed, considering the increasing
34 number of short-distance trips, the growing levels of congestion, higher parking costs
35 and restrictions in a central business district, people are being encouraged to walk
36 more as a viable alternative and economical mode of transportation.

37 With the rapid progress of urbanization, a growing number of intersections in
38 cities are controlled by traffic signals. The inadequacy of accommodating pedestrians'
39 needs makes it difficult to cross streets and increases the number of pedestrian injuries.
40 Although annual road traffic crash statistics show that pedestrian casualties in Hong
41 Kong have been reduced by 19.3% over the past decade, 3,500 pedestrians are still
42 injured every year; these are classified as slight injuries (84%), serious injuries (15%),
43 and fatalities (1%). Moreover, about 42% of pedestrians are younger than 20 or older
44 than 60 years of age, and in approximately 50% of cases the major cause is pedestrian
45 inattentiveness, i.e., crossing of a road heedless of the traffic. Hence, a better
46 understanding of factors contributing to the severity of pedestrian injuries is pressing
47 if walking is considered as a safe and attractive mode of transportation. Such
48 information could also facilitate safety planners and policy makers in the design of
49 appropriate infrastructure and promotion of pedestrianization to improve pedestrian
50 mobility and safety at signalized intersections.

51 Researchers have attempted to establish predictive models to investigate the
52 possible factors influencing pedestrian–motor vehicle crashes (Zajac and Ivan [1],
53 Ballesteros et al. [2], Lee and Abdel-Aty [3], Sze and Wong [4], Eluru et al. [5],
54 Clifton et al. [6], Kim et al. [7], Moudon et al. [8], Tay et al. [9], Abay et al. [10], Aziz
55 et al. [11], Mohamed et al. [12], Sasidharan and Menendez [13]). A wide variety of
56 factors have been explored, including the demographic attributes of pedestrians and
57 drivers, traffic characteristics, road geometry, and environmental factors.

58 Specifically, Aziz et al. [11] suggested the road characteristics (e.g., the number
59 of lanes, the grade, lighting, and the road surface), traffic attributes (e.g., the presence
60 of a signal control and the type of vehicle), together with land use (e.g., parking
61 facilities, commercial, and industrial) have a significant effect on the likelihood of
62 mortality of pedestrians in New York City. Abay [1] found that the risk of fatal injury
63 for pedestrians involved in Denmark is greater for crashes that occurred at night and
64 on roads with high speed limits; for elderly and male pedestrians who were walking
65 while under the influence of alcohol; for pedestrians who were using unmarked
66 crossings or walking along the roadside; for drivers who were under the influence of
67 alcohol; for male drivers with a history of crime; for drivers who were driving straight
68 ahead; and for heavier vehicles. Based on a dataset from New York and Montreal,
69 Mohamed et al. [12] concluded that the pedestrian age, location type, driver age,
70 vehicle type, driver alcohol involvement, lighting conditions, and several built
71 environmental characteristics influence the likelihood of fatal crashes. Meanwhile,
72 Sasidharan and Menendez [13] indicated pedestrians over 75 years of age, unlit road
73 sections, and pedestrians crossing in the middle of a block to be associated with
74 higher levels of injury in Switzerland.

75 As the above analysis shows, human factors are the primary area of focus; there
76 is potential for further insights regarding sites design factors; and the effects of traffic
77 volume and pedestrian activity (e.g., pedestrian volume during a period of time) have
78 been rarely investigated. Although the severity-assessment method does not highly
79 require extensive volume data, the quality and insightfulness of analysis is expected to
80 improve if these variables are included (Yan et al. [14]).

81 Various methods, such as on-site investigation, mathematical modeling, and
82 simulation, have been used to evaluate the levels of pedestrian injuries. Of these,
83 econometric modeling approaches, which specifically focus on the analysis of injury
84 severity from the perspective of overall safety and its economic implications, hold
85 considerable promise. Conditional on a crash having occurred, econometric
86 crash-severity models cover a wide range of methods, including binary logit/probit
87 models (Ballasteros et al. [2], Sze and Wong [4], Moudon et al. [8]), multinomial logit
88 models (Tay et al. [9]), ordered logit/probit models (Zajac and Ivan [1], Lee and
89 Abdel-Aty [3]), generalized ordered logit/probit models (Clifton et al. [6]), partial
90 proportional odds models (Sasidharan and Menendez [13]), a latent class with ordered
91 probit model (Mohamed et al. [12]), mixed generalized ordered response models
92 (Eluru, et al. [5]), and mixed logit models (Kim et al. [7], Abay [10], Aziz et al. [11]).

93 Some of the many factors that influence the severity of crashes are not observed
94 or nearly impossible to collect. If these unobserved factors (i.e., often referred as
95 unobserved heterogeneity; Mannering and Bhat [15]) are correlated with observed
96 ones, biased parameters will be estimated and incorrect inference could be drawn.
97 Recently, random parameters approach has been widely used in crash injury severity
98 analysis for its ability to capture unobserved heterogeneity by allowing the parameters
99 to vary randomly across individual observations (Eluru, et al. [5], Kim et al. [7], Abay

100 [10], Aziz et al. [11], Milton et al. [16], Anastasopoulos and Mannering [17],
101 Anastasopoulos et al. [18]). However, crashes occurring at the same intersection
102 probably share common unobserved factors. The distributional assumption required to
103 estimate the random parameters may not adequately address this unobserved
104 group-specific feature (Mannering and Bhat [15]). Ignoring this within-intersection
105 correlation or cross-intersection heterogeneity results in inaccurate or biased estimates
106 (Jones and Jorgensen [19], Kim et al. [20], Huang et al. [21]).

107 Another major concern gaining growing interest is the spatial correlation. As
108 crash data are typically collected with reference to location dimension, spatial
109 correlation between observation sites is expected. Typically, the inclusion of spatial
110 effects has two main benefits. First, considering spatial correlation allows site
111 estimates to pool strength from neighbors, thereby improving model parameter
112 estimations (Aguero-Valverde and Jovanis [22]). Second, spatial dependence could
113 serve as a surrogate for unknown and relevant covariates that vary smoothly across
114 study area (Dubin [23], Cressie [24]). Although numerous road entity-specific and
115 area-wide safety studies have incorporated the spatial effects into crash frequency
116 modeling (Aguero-Valverde and Jovanis [22] [25], Guo et al. [26], Ahmed et al. [27],
117 Xie et al. [28], Dong et al. [29], Zeng and Huang [30], Barua et al. [31], Xu and
118 Huang [32]), limited research have been conducted in crash injury severity analysis to
119 address this issue. The consequence of this omission remains unknown.

120 Based on the urgent need to improve pedestrian safety and to address negligent
121 fundamental issue in crash injury severity modeling, the present study (1) investigates
122 the injury risk of pedestrian casualties involved in traffic crashes at signalized
123 intersections in Hong Kong; (2) determines the role played by pedestrian volumes in
124 the severity levels of pedestrian injuries; and (3) explores the effect of spatial

125 correlation on econometric crash-severity models. Following the multilevel data
126 structure proposed by Huang and Abdel-Aty [33], a Bayesian hierarchical logit model
127 incorporating both unstructured and spatially correlated heterogeneity is established to
128 estimate the likelihood of a pedestrian being killed or sustaining severe injury (KSI)
129 by considering the associations of various factors, such as detailed pedestrian
130 characteristics, traffic characteristics, environmental features and geometric design
131 data.

132

133 **2. DATA**

134

135 Our dataset integrated data from the Traffic Accident Database System from 2008 to
136 2012 with the geodatabase of the Traffic Information System maintained by the Hong
137 Kong Transport Department (HKTD). As described in detail by Sze and Wong [4],
138 three components from the Traffic Accident Database System were included: the crash
139 environment, the casualty injuries, and the vehicle involvement profiles. All these
140 three were converted into a geodatabase and displayed in ArcGIS.

141 318 signalized intersections were elaborately selected from three areas (i.e.,
142 Hong Kong Island, Kowloon, and New Territories) where 1,889 pedestrian-related
143 crashes collectively occurred. In Hong Kong, the severity of injury is typically
144 categorized as fatal, serious, or slight. In our sample, the fatal cases only accounted
145 for 6.8%. Given that the two adjacent injury categories were quite similar, merging
146 the fatal and serious injury categories was not expected to substantially affect the
147 inference (Sze and Wong [4], Yau [34], Yau et al. [35]). Consequently, the dependent
148 variable in the proposed model was a dichotomous injury outcome in which the
149 response of interest referred to KSI and slight injury was treated as the contrast.

150 By aggregating the crash environment and casualty injury profiles, the predictor
151 variables reflecting the demographic characteristics of pedestrian (i.e., sex and age),
152 the crash characteristics including injury location, crash location, crash time, special
153 circumstances (i.e. crowded/obstructed footpath), and pedestrian contributory factors
154 (i.e. heedless crossing, inattentive etc.), the traffic characteristics (i.e., road type,
155 junction type, speed limit, and traffic congestion), and the environmental factors (i.e.,
156 weather, light, and road surface) were extracted. The intersections' geometric features
157 were derived from the Digitized Traffic Aids Drawings in the Intelligent Road
158 Network Package provided by HKTD. These characteristics included the number of
159 approaches, approach lanes, traffic streams, pedestrian-vehicle conflict
160 points/locations, and the lane width. Traffic characteristics, such as the number of
161 traffic streams, the number of pedestrian crossing streams, the presence of tram and
162 light rail transit (LRT) stops, the presence of bus stops, and the presence of
163 right-turning pockets were also considered. The data for the signal phasing scheme
164 were manually measured on site.

165 Regarding the traffic volume measures, the annual average daily traffic of each
166 intersection was estimated based on the modeled peak-hour flow, which was obtained
167 from the Base District Traffic Models developed by HKTD, and the 24-hour traffic
168 flow data from the nearest counting station, as reported in the Annual Traffic Census.
169 Despite the pedestrian volume plays an important role in road safety analysis, few
170 transportation agencies collect pedestrian data from a large number of sites on a
171 regular basis due to the limited resources. The pedestrian volume of each intersection,
172 represented as the annual average daily pedestrian in this study, was estimated based
173 on the 24-hour zonal pedestrian flow profiles extracted from the Travel Characteristics

174 Survey 2011 database (Transport Department [36]), and further adjusted based on the
175 on-site surveys at signalized intersections under investigation.

176 The variables used for model development are displayed in Table 1, with the
177 proportions of the categorical variables above and the descriptive statistics of the
178 continuous or binary variables below.

179

180 [Insert Table 1 here]

181

182 3. METHODOLOGY

183

184 The response variable Y_{ij} for the i th pedestrian crash that occurred at the j th
185 intersection took one of two values: $Y_{ij} = 1$ for KSI and $Y_{ij} = 0$ for slight injury. The
186 probability of $Y_{ij} = 1$ was denoted by $\pi_{ij} = \Pr(Y_{ij} = 1)$, which was assumed to be
187 determined by a set of covariates representing crash- and site-specific attributes and a
188 corresponding set of unknown regression parameters, using the logit link:

189

$$190 \text{logit}(\pi_{ij}) = \log\left(\frac{\pi_{ij}}{1 - \pi_{ij}}\right) = \beta_0 + \sum_{p=1}^P \beta_p X_{ijp} + \sum_{q=1}^Q \gamma_q Z_{jq} \quad (1)$$

191

192 where X_{ijp} was the p th individual crash level explanatory variable and Z_{jq} was
193 the q th intersection level-specific factors, β_0 was the intercept, and
194 $\beta_p (p=1, \dots, P)$ and $\gamma_q (q=1, \dots, Q)$ were the regression coefficients to be estimated
195 for crash and intersection specific factors.

196 To address the potential within-intersection correlation or cross-intersection

197 heterogeneity, the random effects logit model further assumed (Jones and Jorgensen
 198 [19], Kim et al. [20], Huang et al. [21]):

199

$$200 \quad \text{logit}(\pi_{ij}) = \log\left(\frac{\pi_{ij}}{1-\pi_{ij}}\right) = \beta_0 + \sum_{p=1}^P \beta_p X_{ijp} + \sum_{q=1}^Q \gamma_q Z_{jq} + u_j \quad (2)$$

201 $u_j \sim \text{Normal}(0, \sigma_u^2)$

201

202 where u_j was included to permit the potential variations across intersections. In most
 203 cases, the spatial effects are expected because neighboring intersections typically have
 204 similar environmental and geographical characteristics (Castro et al. [37], Klassen et
 205 al. [38]). To this end, a spatially structured or spatially correlated error term s_j was
 206 added, resulting in a spatial logit model:

207

$$208 \quad \text{logit}(\pi_{ij}) = \log\left(\frac{\pi_{ij}}{1-\pi_{ij}}\right) = \beta_0 + \sum_{p=1}^P \beta_p X_{ijp} + \sum_{q=1}^Q \gamma_q Z_{jq} + u_j + s_j \quad (3)$$

209

210 One possible joint density for the spatial effects $\mathbf{s} = (s_1, s_2, \dots, s_m)$ was in terms
 211 of pairwise differences in errors and a variance term σ_s^2 (Banerjee et al. [39]):

212

$$213 \quad P(s_1, s_2, \dots, s_m) \propto \exp[-0.5(\sigma_s^2)^{-1} \sum_{j \sim k} c_{jk} (s_j - s_k)^2] \quad (4)$$

214

215 This joint density implies a normal conditional prior for s_j conditioning on the
 216 effect of s_k in remaining observation sites:

217

218 $s_j | s_{k \neq j} \sim \text{Normal}\left(\frac{\sum_k w_{jk} s_k}{\sum_k w_{jk}}, \frac{\sigma_s^2}{\sum_k w_{jk}}\right)$ (5)

219

220 where w_{jk} represents the un-normalized weight between intersection j and k .

221 The simplest neighboring structure is that of adjacency-based first-order neighbors,

222 which could be defined as all intersections that connect directly with the one in

223 question (Guo et al. [26], Xie et al. [28], Zeng and Huang [30]). As our intersection

224 locations were spread throughout three areas of Hong Kong, a large portion of

225 intersections had no directly connected neighbors. This produced an unstable model

226 that did not converge and was thus discarded.

227 An alternative is the distance decay based proximity structure, in which the

228 weight is calculated using an exponential decay function of the distance between

229 intersections (Congdon [40]):

230

231 $w_{jk} = e^{-\phi d_{jk}}$ (6)

232

233 where d_{jk} is the network distance between intersection j and k , and the

234 parameter ϕ controls the rate of decline of correlation. This approach is

235 computationally feasible for only a few hundred observations (Aguero-Valverde and

236 Jovanis [25]). Meanwhile, the full consideration of all possible spatial correlations for

237 all sites could also significantly reduce model performance (Dong et al. [29]).

238 Aguero-Valverde and Jovanis [25] deemed 1 mi (about 1.609km) a proper threshold

239 point for considering segments spatially correlated in Pennsylvania and Washington.

240 Thus, an arbitrary maximum distance of 1.5km was selected in the present study, i.e.,

241 any intersection whose distance was greater than this threshold was assumed to have a
 242 weight of zero. This setting allowed approximately 25 neighbors for each intersection
 243 on average.

244 Inspired by the work of Agüero-Valverde and Jovanis [25], a distance-order
 245 neighboring scheme was also introduced. The adjacency hierarchy was defined in
 246 terms of distances, i.e., the first-, second- and third-order neighbors were within 0.5, 1,
 247 and 1-1.5 km of the intersection of interest, respectively, hence:

248

$$249 \quad w_{jk} = \begin{cases} 1 & d_{jk} \leq 0.5 \text{ km} \\ 1/2 & 0.5 \text{ km} < d_{jk} \leq 1 \text{ km} \\ 1/3 & 1 \text{ km} < d_{jk} \leq 1.5 \text{ km} \end{cases} \quad (7)$$

250

251 Assessing the relative strength of spatial and unstructured variations requires
 252 estimates of marginal variances:

253

$$254 \quad \alpha = \frac{\text{sd}(\mathbf{s})}{\text{sd}(\mathbf{s}) + \text{sd}(\mathbf{u})} \quad (8)$$

255

256 where α is the proportion of variability in random effects due to the spatial
 257 correlation, and sd is the empirical marginal standard deviation function.

258 A full Bayesian inference using the Markov Chain Monte Carlo algorithm was
 259 implemented to construct above model. Non-informative priors were assigned for
 260 model parameters (El-Basyouny and Sayed [41], El-Basyouny and Sayed [42]):

261

$$262 \quad \begin{aligned} \beta_p &\sim \text{Normal}(0,1000) \\ \gamma_q &\sim \text{Normal}(0,1000) \end{aligned} \quad (9)$$

263

264 For the variance parameters, a $\text{uniform}(0,10)$ was specified for σ_u^2 and σ_s^2
265 (Gelman [43], Lee [44]). The decay parameter ϕ was assumed to be a
266 $\text{uniform}(0.53,76.75)$ (Thomas et al. [45]). This specification allowed a diffuse but
267 plausible prior range of correlation between 0.10 and 0.98 at the minimum distance of
268 0.03 km, and between 0 and 0.45 at the maximum distance of 1.5 km.

269 For model comparison, the Deviance Information Criterion (DIC) was used:

270

$$271 \text{DIC} = D(\bar{\theta}) + 2p_D = \bar{D} + p_D \quad (10)$$

272

273 where $D(\bar{\theta})$ is the deviance evaluated at $\bar{\theta}$, the posterior means of the parameter of
274 interest, p_D is the effective number of parameters in the model, and \bar{D} is the
275 posterior mean of the deviance statistic $D(\bar{\theta})$. The lower the DIC, the better the
276 model fit. Generally, differences in DIC of more than 10 definitely rule out the model
277 with the higher DIC, differences between 5 and 10 are considered substantial, while a
278 difference of less than 5 indicates that models are not statistically different
279 (Spiegelhalter et al. [46]).

280 4. RESULTS AND DISCUSSION

281

282 The freeware software WinBUGS was used to calibrate the above models
283 (Spiegelhalter et al. [47]). Three parallel chains with diverse starting values were
284 tracked. The first 10,000 iterations in each chain were discarded as burn-ins, and then
285 5,000 iterations were performed for each chain resulting in a sample distribution of
286 15,000 for each parameter. The model's convergence was monitored by the
287 Brooks-Gelman-Rubin (BGR) statistic (Brooks and Gelman [48]), visual examination
288 of the Markov Chain Monte Carlo chains, and the ratios of Monte Carlo errors relative
289 to the respective standard deviations of the estimates (as a rule of thumb, these ratios
290 should be less than 0.05).

291 The model specifications were developed based on the following principles. A
292 correlation test was first conducted to ensure the non-existence of any highly
293 correlated variables. The correlation analysis indicated a high correlation between the
294 time of day and natural light and street light, implying that those three variables
295 should not be included together in the model. Similarly, weather, rain and road surface;
296 the number of approaches, approach lanes and traffic streams; and the number of
297 pedestrian streams, conflict points and conflict locations, respectively, were all
298 correlated. Obstruction and traffic aids were also highly correlated, indicating that
299 only one of the two should be included in the model. DIC was then used to compare
300 alternative models with different covariate subsets. The one that produced a lower
301 DIC value was superior.

302 For the purpose of comparison, the basic binary logit model and the one with
303 uncorrelated random effects only were also estimated. As such, six models were

304 ultimately calibrated. The performances of the developed models are compared in this
305 section, followed by the presentation and interpretation of the parameter estimates.

306

307 **4.1 Model comparison**

308

309 Table 2 shows the goodness-of-fit measures for the calibrated models. The spatial
310 logit models outperformed according to DIC statistics. In particular, the second-order
311 distance model performed best with the lowest DIC value, which was approximately
312 20 points lower than the basic logit model and 15 points lower than the unstructured
313 random effects model. This result suggests that accounting for spatial correlation is
314 conducive to a substantial improvement in goodness-of-fit. It is also interesting to find
315 that the four spatial models had comparable performance. This finding indicated that
316 the estimated spatial models based on our dataset are robust to the configuration of
317 neighboring structures. In addition, a substantial proportion of variability (i.e. around
318 80%) was explained by the spatially correlated effects, confirming the extensive
319 existence of cross-intersection spatial correlation. This may be why the uncorrelated
320 random effects model did not provide a significantly improved performance relative
321 to the basic model.

322

323 [Insert Table 2 here]

324

325

326 **4.2 Parameter estimates**

327

328 Table 3 summarizes the final results for the basic, uncorrelated random-effects and

329 spatial logit (i.e., second-order distance) models. A 5% level of significance was used
330 as the threshold to determine whether the parameter estimates differed from zero. Any
331 variables that were insignificant in all three models were excluded.

332 Several general observations are worth noting. First, the significant variables
333 were not identical. For example, the presence of bus stops was statistically significant
334 in the former two models, but became totally insignificant once spatial correlation was
335 considered. Similar results also held true for the two-way carriageway and presence of
336 tram/LRT stops variables. This inconsistency may be the result of model
337 misspecification, including the omission of spatially relevant variables. Second, the
338 standard error of the coefficient estimates in the spatial logit model was slightly
339 greater than that in the basic model. Third, when spatial effects were introduced, the
340 standard deviation of the uncorrelated random effects was obviously reduced,
341 dropping from 0.404 to 0.179. This was expected because spatial effects can capture
342 some of the extra variation in the data previously explained by the uncorrelated
343 random effects. Fourth, the total variation explained in the spatial logit model
344 increased to nearly 1.0, which was higher than 0.404 in the corresponding model
345 without spatial effects. This implied that ignoring spatial dependence could lead to an
346 underestimation of variability.

347

348

349 [Insert Table 3 here]

350 Given that the spatial logit model performed best, we chose it to interpret our
351 results in the subsequent section. As Table 3 shows, the majority of the significant
352 variables in the spatial logit model were related to pedestrian rather than
353 environmental characteristics, or to the geometric designs of signalized intersections.
354 The following factors were associated with a significantly higher probability of KSI:
355 pedestrians older than 65 years of age (odds ratio, 2.878), casualties with head injuries
356 (3.626), crashes that occurred on footpaths that were not obstructed/overcrowded
357 (1.671), heedless (1.972) or inattentive (1.477) crossing and crashes on the two-way
358 carriageway (1.306) near tram/LRT stops (1.449). Accordingly, crashes occurring at or
359 near obstructions (0.599) and at intersections with greater pedestrian volume (0.850)
360 tended to have a lower likelihood of KSI.

361 The involvement of pedestrians over 65 years of age was found to have a more
362 significant relationship with KSI than that of youths under 15 years of age. This was
363 unsurprising, as the elderly are usually weaker in terms of physiological condition and
364 perception of safety, and slower to react in hazardous situations. Similar findings have
365 also been previously reported (Zajac and Ivan [1], Sze and Wong [4], 2007; Eluru et al.
366 [5], Moudon et al. [8], Abay [10], Aziz et al. [11]).

367 Regarding the location of injury, no one is likely to disagree that casualties with
368 head injuries are more likely to result in severe injuries or even death (Ballesteros et al.
369 [2]). According to the odds ratio in Table 3, the KSI risk of the crashes that involved a
370 pedestrian with a head injury was more than triple those with other injuries, implying
371 that special attention should be paid to this type of injury.

372 In addition to obstructed or overcrowded footpaths, other circumstances,
373 including the absence of a footpath on one or both sides of an intersection and a
374 pedestrian running onto the road or climbing over barrier rails, were more likely to

375 lead to KSI. This finding probably reflected the fact that drivers do not expect
376 pedestrians to appear on the carriageway except when it is obstructed or overcrowded.
377 Likewise, Abay [10] implied that pedestrians crossing with unmarked crossings
378 (non-crosswalks) were more likely to be seriously or fatally injured using a Danish
379 dataset. Thus, public transport economists and other policy makers should consider
380 investing in infrastructural facilities such as safer crossing and staying facilities for
381 pedestrians. Such direct countermeasures could improve the synergy of the mobility
382 and minimize the vulnerability of road users in the pre-crash phase.

383 Consistent with Sze and Wong [4], pedestrians who were heedless and inattentive
384 of crossing were prone to sustain a higher KSI likelihood. This elevated injury risk
385 may have been modified by pedestrian impairments, such as alcohol intoxication,
386 carelessness, or misjudgment, and also by the availability and accessibility of marked
387 crosswalks (Al-Ghamdi [49], Loo and Tsui [50]).

388 In addition, pedestrians at or near an obstruction were more likely to be slightly
389 injured. This protective effect was not surprising to some extent because the collision
390 speed may be substantially reduced in the presence of an obstruction, thus lowering
391 the probability of a severe injury.

392 Setting one-way roads as the base category, a higher risk of fatal or serious
393 injuries for pedestrians was observed on two-way carriageways. This was perhaps
394 related to the reduced possibility of turning negligently or drivers making
395 improper/illegal turns on one-way roads in Hong Kong (Transport Department, Hong
396 Kong [51]). The one-way carriageways were also observed to experience a lower risk
397 of fatal or serious injuries in multi-vehicle traffic crashes (Yau et al. [35]).

398 Pedestrian volume has been identified as one of the most influential factors in
399 predicting pedestrian–vehicle crashes. Leden [52], Lyon and Persaud [53], and

400 Miranda-Moreno et al. [54] reported a statistically significant and positive relationship
401 between pedestrian activity and crash occurrence at different types of intersections.
402 More importantly, a non-linear relationship has been found, suggesting that the
403 absolute number of collisions increases with the pedestrian volume, whereas the risk
404 faced by each pedestrian decreases. This is often referred as the “safety in numbers”
405 effect (Leden [52], Jacobsen [55], Geyer et al. [56]). By accounting for the pedestrian
406 activity in pedestrian injury severity modeling, the present study provided additional
407 evidence to existing research that the number of pedestrians was also closely
408 correlated with the injury severity outcomes, as our results implied that pedestrians at
409 signalized intersections with greater pedestrian volumes indeed sustained a relatively
410 lower likelihood of KSI. The pedestrian volume typically serves as a measurement for
411 the use and preference of crossing facilities (Cho et al. [57]). One potential
412 explanation is that pedestrians usually have a strong value preference for the
413 perceived safe crossing sites, either because they are following a knowledgeable
414 leader or there exists some collective wisdom of safe sites (Landis et al. [58], Jacobsen
415 et al. [59]). Therefore, intersections with more pedestrians are deemed to be inherently
416 safer with lower vehicle speeds, lower traffic volumes, and greater buffers between
417 pedestrians and motorists. Besides, pedestrians in intersections with higher AADP
418 may be more likely to cross a street close together in a group. This practice provides a
419 degree of collective vigilance regarding motorist hazards, or there may be more
420 physical buffering effects if a mass of pedestrians are crossing the street together
421 (Bhatia and Wier [60]). Furthermore, given that drivers’ speeds are potentially
422 influenced by pedestrians (Jacobsen [55], Todd [61]), the inclusion of AADP was
423 expected to enhance the model’s accountability, as it could be regarded as a superb
424 proxy for factors that were not available in current crash databases, such as collisions

425 speeds. Nevertheless, reaching above casual inferences should be conducted with
426 great caution, as the measure of pedestrian volume used in this empirical study was
427 based on the average daily pedestrian flow. This average metric may not always be
428 equivalent to the counterpart present when crashes actually occurred.

429 The presence of a tram or LRT stop increased the likelihood of KSI at a 10%
430 level of significance. This finding deserves substantial attention because most of the
431 tram stops in Hong Kong Island are located near signalized intersections, at which
432 traffic moves in the same direction on both sides of the island and is allowed to enter
433 the tram lanes in congested areas. This puts tram passengers in more danger because
434 traffic does not come from the anticipated direction when they cross the second half
435 of the road. Wong et al. [62] also revealed that the presence of tram or LRT stops
436 significantly increased the occurrence of traffic crashes at signalized intersections in
437 Hong Kong.

438 Finally, a significantly positive spatial correlation was expected due to the
439 missing variables (e.g., land use and coordinated signal control strategies along a
440 corridor) and spatial clustering pattern of crash counts.

441

442 **5. CONCLUSIONS**

443

444 This study investigated the injury severity sustained by pedestrians involved in
445 crashes at signalized intersections through an analysis of data from the Transport
446 Department of Hong Kong on detailed pedestrian characteristics, traffic
447 characteristics, environmental features and geometric design. To account for the
448 cross-intersection heterogeneity, a Bayesian hierarchical logit model incorporating
449 both uncorrelated and spatially correlated random effects was developed.

450 There were some key findings evident from this empirical analysis. By including
451 AADP, the present study demonstrated that the intersections with greater pedestrian
452 volume generally possessed a relatively lower risk of KSI (i.e., the places where more
453 people walk may be less risky). It is also noteworthy that perceived safety did not
454 necessarily correspond with actual safety (Cho et al. [57]). Perceived safety without
455 actual safety creates a false sense of security, whereas actual safety without perceived
456 safety discourages people from walking. Thus, to promote more walking, both the
457 safety of facilities and the number of pedestrians must increase. Planners should
458 improve pedestrianization designs by accommodating pedestrians' proper walking
459 behavior, particularly which of the more vulnerable elders, to satisfy their safety
460 concerns. Signs and markings should be placed around signalized intersections and
461 tram stops to alert pedestrians of the danger of heedless and inattentive crossing (e.g.,
462 while talking on the telephone, texting, or listening to music). Other remediation to
463 account for the potential risk of head injuries and the lack of footpaths is also required.
464 In the meantime, safety officials should consider providing education programs to
465 help pedestrians obey traffic rules and walk sensibly. All of these integrated
466 countermeasures would improve mobility and safety at signalized intersections while
467 raising the safety consciousness of pedestrians. Once people's perceptions of risk
468 increase, their behavior changes, creating a safer environment.

469 Despite the growing concern over spatial dependence in crash frequency
470 modeling, the role of spatial correlation in injury severity analysis has not been
471 comprehensively addressed. Thus, a full Bayesian hierarchical approach was used
472 here with an intrinsic conditional autoregressive prior for the spatial correlation term.
473 Different neighboring structures were tested to identify the most promising. Our
474 results revealed that ignoring the spatial correlation potentially results in reduced

475 model goodness-of-fit, an underestimation of variability and standard error of
476 parameter estimates, along with inconsistent, biased and erroneous inferences. The
477 fact that a large portion of extra variation is due to spatial effects suggests that the
478 spatial correlation between observation sites should be elaborately considered in the
479 context of injury severity modeling in road networks.

480 For future research, in addition to the typically used conditional autoregressive
481 model, other spatial prior distributions such as the jointly specified (Aguero-Valverde
482 [63]) and multiple membership (El-Basyouny and Sayed [64]) forms could be
483 attempted. Furthermore, as the severity of pedestrian injury greatly depends on the
484 individual specific factors, a natural next step is to consider how to incorporate the
485 cross-sites and unobserved individual heterogeneity into the modeling process
486 simultaneously. As the fatal cases only accounted for 6.8%, we merged the fatal and
487 serious injury categories as KSI. Future efforts to accommodate the small proportion
488 of fatal injuries in traffic safety modeling are desirable. Besides, as the results of the
489 study were based on a single dataset, future studies with different data sources would
490 also prove worthwhile to confirm the paper's findings.

491

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493

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502

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695

696 Table 1 Summary of the parameters in the pedestrian injury model

Factor	Attribute	Count (proportion)
Year	2008	433 (22.9%)
	2009	389 (20.6%)
	2010	384 (20.3%)
	2011	352 (18.7%)
	2012	331 (17.5%)
Injury severity	Killed or severe injury	518 (27.4%)
	Slight injury	1371 (72.6%)
Sex	Male	1000 (52.9%)
	Female	889 (47.1%)
Age (years)	Under 15	163 (8.6%)
	15 to 65	1350 (71.5%)
	Above 65	376 (19.9%)
Injury location	Head injury	573 (30.3%)
	Others	1316 (69.7%)
Pedestrian location	On the crossing	530 (28.1%)
	Within 15 m of the crossing	1159 (61.3%)
	Others	200 (10.6%)
Pedestrian action	Crossing road or junction	1011 (53.5%)
	Walking along footpath	170 (9.0%)
	Others	708 (37.5%)
Pedestrian special circumstance	Overcrowded footpath	264 (14.0%)
	Obstructed footpath	225 (11.9%)
	Others	835 (44.2%)
	None	565 (29.9%)
Pedestrian contributory	Heedless crossing	387 (20.5%)
	Inattentive	229 (12.1%)
	Others	616 (32.6%)
	None	657 (34.8%)
Day of week	Weekday (Monday-Friday)	1410 (74.6%)
	Weekend (Saturday-Sunday)	476 (25.4%)
Time of day	7:00 to 9:59 AM	266 (14.1%)
	10:00 AM to 3:59 PM	672 (35.6%)
	4:00 to 6:59 PM	411 (21.7%)
	7:00 PM to 6:59 AM	540 (28.6%)
Speed limit	Below 50 km/h	23 (1.2%)
	50 km/h	1851 (98.0%)
	Above 50 km/h	15 (0.8%)
Traffic aids	Poor aids	186 (9.8%)
	Normal	1703 (90.2%)
Traffic congestion	Severe congestion	340 (18.0%)
	Moderate congestion	476 (25.2%)
	No congestion	1073 (56.8%)

Factor	Attribute	Count (proportion)		
Obstruction	At or near obstruction	348	(18.4%)	
	No obstruction nearby	1541	(81.6%)	
Junction type	T-junction	767	(40.6%)	
	Y-junction	31	(1.6%)	
	Cross-roads	326	(17.3%)	
	Others	765	(40.5%)	
Road type	Single-way carriageway	877	(46.4%)	
	Two-way carriageway	461	(24.4%)	
	Multiple/dual carriageway	551	(29.2%)	
Weather	Clear	1736	(91.9%)	
	Dull	102	(5.4%)	
	Fog/mist	35	(1.9%)	
	Strong wind and unknown	16	(0.8%)	
Rain	Not raining	1635	(86.6%)	
	Light rain	202	(10.7%)	
	Heavy rain	41	(2.2%)	
	Unknown	11	(0.5%)	
Natural light	Daylight	1292	(68.4%)	
	Dawn/dusk	61	(3.2%)	
	Dark	536	(28.4%)	
Street light	Good	781	(41.3%)	
	Poor	11	(0.6%)	
	Obscured and others	1097	(58.1%)	
Road surface	Wet	265	(14.0%)	
	Dry	1617	(85.6%)	
	Unknown	7	(0.4%)	
Crossing facility	Traffic signal	731	(38.7%)	
	Others	1074	(56.9%)	
	None	84	(4.4%)	
Presence of tram/LRT stops	Yes	247	(13.1%)	
	No	1642	(86.9%)	
Presence of bus stops	Yes	670	(35.5%)	
	No	1219	(64.5%)	
Presence of right-turn pocket	Yes	191	(10.1%)	
	No	1698	(89.9%)	
		Range	Mean	S.D.
Exposure measures				
	Annual average daily traffic	1124 to 340516	35409.54	23887.61
	Annual average daily pedestrian	288 to 340107	56855.69	60849.93
Geometric design				
	Number of approaches	1 to 4	3.04	0.79
	Number of approach lanes	1 to 20	7.73	3.57
	Number of traffic streams	1 to 12	4.55	2.04
	Average lane width (m)	2.47 to 6.85	3.41	0.49
	Number of pedestrian streams	0 to 10	3.25	1.83

Factor	Attribute	Count (proportion)	
Number of conflict points	0 to 46	11.36	7.93
Number of conflict locations	0 to 46	10.24	7.43
Signal phasing scheme			
Cycle time (s)	30 to 150	103.46	19.69
Number of stages	1 to 5	2.80	0.91

697

698

699

700 Table 2 Goodness-of-fit measures for basic and random-effects binary logit models

Model type	Neighboring structure	\bar{D}	p_D	DIC	α
Basic model	None	1954.88	16.01	1970.89	—
Uncorrelated RE model	None	1907.24	58.32	1965.56	—
Spatial logit model	Distance exponential decay	1898.26	57.59	1955.85	0.76
	Distance first order	1886.26	67.32	1953.58	0.93
	Distance second order	1887.36	62.82	1950.17	0.83
	Distance third order	1894.77	58.06	1952.83	0.79

701 Note: RE refers to random effects; the estimate for ϕ was 2.89 with a 95% Bayesian credible

702 interval (0.60, 8.45).

703

Table 3 Estimates results for basic, and random effects binary logit models

Variables	Control	Basic model			Uncorrelated RE model			Spatial model			
		Mean	SD	95% BCI	Mean	SD	95% BCI	Mean	SD	95% BCI	OR
Constant		-2.664**	0.265	(-3.189,-2.156)	-2.718**	0.275	(-3.261, -2.190)	-2.606**	0.279	(-3.179,-2.074)	
Pedestrian age (years)	< 15										
15-65		0.175	0.209	(-0.225,0.592)	0.163	0.216	(-0.253,0.592)	0.145	0.219	(-0.277,0.589)	1.156
≥ 65		1.042**	0.228	(0.603,1.496)	1.053**	0.238	(0.595,1.526)	1.057**	0.240	(0.602,1.547)	2.878**
Head injury	Others	1.237**	0.116	(1.012,1.463)	1.259**	0.121	(1.023,1.496)	1.288**	0.123	(1.044,1.529)	3.626**
Pedestrian special circumstance											
Overcrowded footpath		0.121	0.196	(-0.262,0.503)	0.116	0.204	(-0.289,0.508)	0.111	0.207	(-0.299,0.514)	1.117
Obstructed footpath		0.262	0.199	(-0.130,0.650)	0.277	0.207	(-0.133,0.686)	0.317	0.210	(-0.098,0.727)	1.373
Others		0.503**	0.141	(0.226,0.779)	0.520**	0.146	(0.234,0.804)	0.513**	0.149	(0.228,0.807)	1.671**
Pedestrian contributory action	None										
Heedless crossing		0.710**	0.165	(0.388,1.031)	0.717**	0.169	(0.386,1.048)	0.679**	0.173	(0.341,1.023)	1.972**
Inattentive		0.301	0.205	(-0.103,0.699)	0.321	0.211	(-0.093,0.735)	0.390*	0.220	(-0.030,0.804)	1.477*
Others		0.602**	0.148	(0.311,0.890)	0.603**	0.152	(0.306,0.901)	0.534**	0.159	(0.222,0.853)	1.705**
At or near obstruction		-0.444**	0.150	(-0.746,-0.145)	-0.465**	0.158	(-0.782,-0.160)	-0.513**	0.163	(-0.838,-0.197)	0.599**
Road type	Single										
Two-way carriageway		0.360**	0.139	(0.087,0.634)	0.376**	0.144	(0.094,0.656)	0.267*	0.152	(-0.031,0.567)	1.306*
Multiple carriageway		0.043	0.142	(-0.237,0.322)	0.056	0.149	(-0.235,0.344)	0.144	0.155	(-0.156,0.445)	1.155
AADP		-0.221**	0.072	(-0.365,-0.081)	-0.215**	0.077	(-0.378,-0.056)	-0.162**	0.082	(-0.316,-0.016)	0.850**
Presence of tram/LRT stops		0.405**	0.163	(0.083,0.723)	0.450**	0.193	(0.072,0.835)	0.371*	0.206	(-0.036,0.770)	1.449*
Presence of bus stops		0.241**	0.119	(0.005,0.477)	0.240*	0.139	(-0.032,0.510)	0.125	0.134	(-0.143,0.384)	1.133
sd(u)					0.404**	0.137	(0.106,0.651)	0.179**	0.112	(0.033,0.456)	
sd(s)								0.815**	0.149	(0.571,1.163)	

Note: RE refers to random effects; OR represents odd ratio; BCI is the abbreviation for Bayesian credible interval; ** and * indicate 5% and 10% levels of significance, respectively.